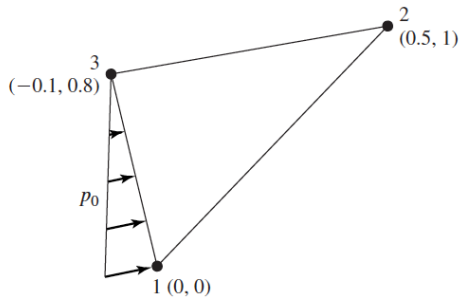


1. The T3 element shown below is subjected to the linearly varying pressure as shown below. Determine the equivalent nodal forces.

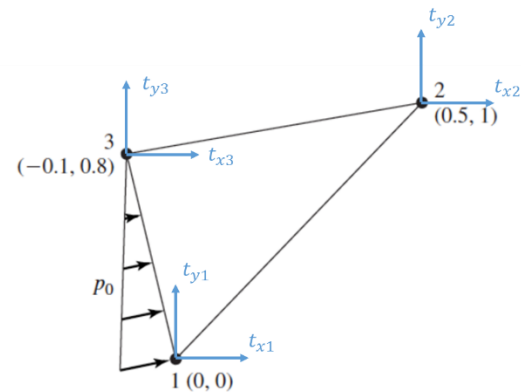


$$N_1(x, y) = \frac{A_1}{A_e} = 1 + 0.4x - 1.2y$$

$$N_2(x, y) = \frac{A_2}{A_e} = 1.6x + 0.2y$$

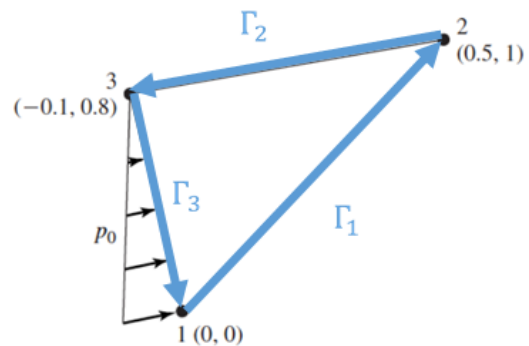
$$N_3(x, y) = \frac{A_3}{A_e} = -2x + y$$

$$\bar{\mathbf{t}} = \mathbf{N}^e \mathbf{t} = \mathbf{N}^e \begin{bmatrix} t_{x1} \\ t_{y1} \\ t_{x2} \\ t_{y2} \\ t_{x3} \\ t_{y3} \end{bmatrix} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \begin{bmatrix} p_0 * \frac{8}{\sqrt{65}} \\ p_0 * \frac{1}{\sqrt{65}} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$



$$\mathbf{f}_\Gamma^e = \mathbf{t} \oint \mathbf{N}^{eT} \bar{\mathbf{t}} d\Gamma = \mathbf{0} + \mathbf{0} + \mathbf{t} \int_{\Gamma_3} \mathbf{N}^{eT} \mathbf{N}^e \mathbf{t} d\Gamma$$

$$= \frac{t}{\sqrt{65}} \begin{bmatrix} \int_{\Gamma_3} N_1^2 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1^2 \cdot 1 \cdot p_0 d\Gamma \\ 0 \\ 0 \\ \int_{\Gamma_3} N_1 N_3 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1 N_3 \cdot 1 \cdot p_0 d\Gamma \end{bmatrix}$$



There are no traction on Γ_1 & Γ_2 , so equivalent nodal force from Γ_1 & Γ_2 are zero.

$$y = -8x, \begin{cases} N_1(x) = 1 + 10x \\ N_3(x) = -10x \end{cases}$$

$$\Gamma^2 = x^2 + y^2 = 65x^2 \rightarrow \Gamma = \sqrt{65}x \rightarrow \frac{d\Gamma}{dx} = \sqrt{65} \text{ (Jacobian)}$$

$$\mathbf{f}_{\Gamma}^e = \frac{t}{\sqrt{65}} \begin{bmatrix} \int_{\Gamma_3} N_1^2 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1^2 \cdot 1 \cdot p_0 d\Gamma \\ 0 \\ 0 \\ \int_{\Gamma_3} N_1 N_3 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1 N_3 \cdot 1 \cdot p_0 d\Gamma \end{bmatrix} = \frac{t}{\sqrt{65}} \begin{bmatrix} \int_{-0.1}^0 N_1^2(x) \cdot 8 \cdot p_0 \cdot \sqrt{65} dx \\ \int_{-0.1}^0 N_1^2(x) \cdot 1 \cdot p_0 \cdot \sqrt{65} dx \\ 0 \\ 0 \\ \int_{-0.1}^0 N_1(x) N_3(x) \cdot 8 \cdot p_0 \cdot \sqrt{65} dx \\ \int_{-0.1}^0 N_1(x) N_3(x) \cdot 1 \cdot p_0 \cdot \sqrt{65} dx \end{bmatrix} = p_0 t \begin{bmatrix} \frac{4}{15} \\ \frac{1}{30} \\ 0 \\ 0 \\ \frac{2}{15} \\ \frac{1}{60} \end{bmatrix} \approx p_0 t \begin{bmatrix} 0.2667 \\ 0.0333 \\ 0 \\ 0 \\ 0.1333 \\ 0.0167 \end{bmatrix}$$

$$x = -\frac{1}{8}y, \begin{cases} N_1(y) = 1 - \frac{5}{4}y \\ N_3(y) = \frac{5}{4}y \end{cases}$$

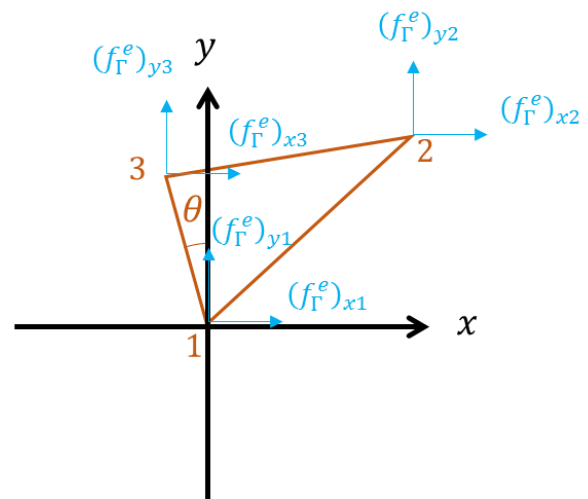
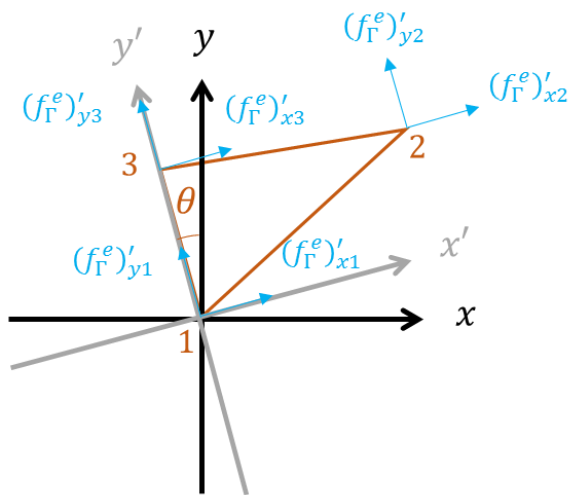
$$\Gamma^2 = x^2 + y^2 = \frac{65}{64}y^2 \rightarrow \Gamma = \sqrt{\frac{65}{64}}y \rightarrow \frac{d\Gamma}{dy} = -\frac{\sqrt{65}}{8} \text{ (Jacobian)}$$

$$\mathbf{f}_{\Gamma}^e = \frac{t}{\sqrt{65}} \begin{bmatrix} \int_{\Gamma_3} N_1^2 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1^2 \cdot 1 \cdot p_0 d\Gamma \\ 0 \\ 0 \\ \int_{\Gamma_3} N_1 N_3 \cdot 8 \cdot p_0 d\Gamma \\ \int_{\Gamma_3} N_1 N_3 \cdot 1 \cdot p_0 d\Gamma \end{bmatrix} = \frac{t}{\sqrt{65}} \begin{bmatrix} \int_{0.8}^0 N_1^2(y) \cdot 8 \cdot p_0 \cdot -\frac{\sqrt{65}}{8} dy \\ \int_{0.8}^0 N_1^2(y) \cdot 1 \cdot p_0 \cdot -\frac{\sqrt{65}}{8} dy \\ 0 \\ 0 \\ \int_{0.8}^0 N_1(y) N_3(y) \cdot 8 \cdot p_0 \cdot -\frac{\sqrt{65}}{8} dy \\ \int_{0.8}^0 N_1(y) N_3(y) \cdot 1 \cdot p_0 \cdot -\frac{\sqrt{65}}{8} dy \end{bmatrix} = p_0 t \begin{bmatrix} \frac{4}{15} \\ \frac{1}{30} \\ 0 \\ 0 \\ \frac{2}{15} \\ \frac{1}{60} \end{bmatrix} \approx p_0 t \begin{bmatrix} 0.2667 \\ 0.0333 \\ 0 \\ 0 \\ 0.1333 \\ 0.0167 \end{bmatrix}$$

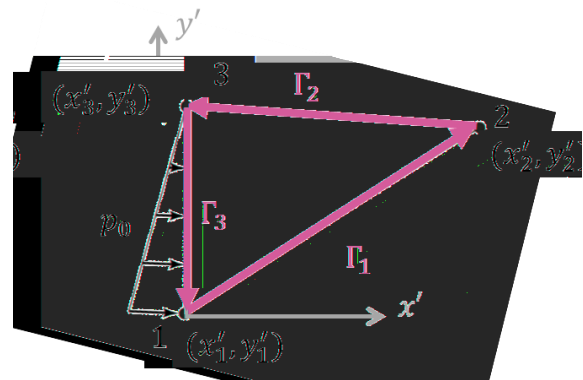
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{T} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$A_e = \frac{1}{2} \begin{vmatrix} 1 & x_1' & y_1' \\ 1 & x_2' & y_2' \\ 1 & x_3' & y_3' \end{vmatrix} = \frac{1}{4} \quad A_1' = \frac{1}{2} \begin{vmatrix} 1 & x' & y' \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{vmatrix} \quad A_2' = \frac{1}{2} \begin{vmatrix} 1 & x' & y' \\ 1 & x_3 & y_3 \\ 1 & x_1 & y_1 \end{vmatrix} \quad A_3' = \frac{1}{2} \begin{vmatrix} 1 & x' & y' \\ 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \end{vmatrix}$$

$$N_1(x', y') = \frac{A_1'}{A_e} \quad N_2(x', y') = \frac{A_2'}{A_e} \quad N_3(x', y') = \frac{A_3'}{A_e}$$



$$\bar{\mathbf{t}} = \mathbf{N}^e \mathbf{t} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \begin{bmatrix} p_0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$



$$\mathbf{f}_\Gamma^e = t \oint \mathbf{N}^{eT} \bar{\mathbf{t}} d\Gamma = \mathbf{0} + \mathbf{0} + t \int_{\Gamma_3} \mathbf{N}^{eT} \mathbf{N}^e \mathbf{t} d\Gamma = t \begin{bmatrix} \int_{\Gamma_3} N_1^2(x', y') p_0 dy' \\ 0 \\ 0 \\ 0 \\ \int_{\Gamma_3} N_1(x', y') N_3(x', y') p_0 dy' \\ 0 \end{bmatrix} = \begin{bmatrix} (f_\Gamma^e)'_{x1} \\ (f_\Gamma^e)'_{y1} \\ (f_\Gamma^e)'_{x2} \\ (f_\Gamma^e)'_{y2} \\ (f_\Gamma^e)'_{x3} \\ (f_\Gamma^e)'_{y3} \end{bmatrix}$$

$$\therefore \mathbf{F}' = \mathbf{T} \mathbf{F}$$

$$\Rightarrow \mathbf{F} = \mathbf{T}^{-1} \mathbf{F}'$$

$$\Rightarrow \begin{bmatrix} (f_\Gamma^e)_{x1} & (f_\Gamma^e)_{x2} & (f_\Gamma^e)_{x3} \\ (f_\Gamma^e)_{y1} & (f_\Gamma^e)_{y2} & (f_\Gamma^e)_{y3} \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} (f_\Gamma^e)'_{x1} & (f_\Gamma^e)'_{x2} & (f_\Gamma^e)'_{x3} \\ (f_\Gamma^e)'_{y1} & (f_\Gamma^e)'_{y2} & (f_\Gamma^e)'_{y3} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} (f_\Gamma^e)_{x1} & (f_\Gamma^e)_{x2} & (f_\Gamma^e)_{x3} \\ (f_\Gamma^e)_{y1} & (f_\Gamma^e)_{y2} & (f_\Gamma^e)_{y3} \end{bmatrix} = t p_0 \begin{bmatrix} 0.2667 & 0 & 0.1333 \\ 0.0333 & 0 & 0.0167 \end{bmatrix}$$

$$\mathbf{f}_\Gamma^e = p_0 t \begin{bmatrix} 0.2667 \\ 0.0333 \\ 0 \\ 0 \\ 0.1333 \\ 0.0167 \end{bmatrix}$$

ξ



$N_1(\xi$