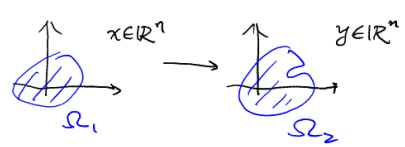


Stokes theorem and Poincaré lemma [BT, §I.3 and §I.4]

recall $y = y(x)$ diffeomorphism



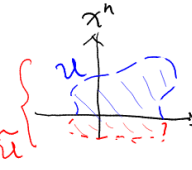
$$\int_{\Omega_2} f(y) dy^1 \dots dy^n = \int_{\Omega_1} f(y(x)) \left| \det \frac{\partial(y^1, \dots, y^n)}{\partial(x^1, \dots, x^n)} \right| dx^1 \dots dx^n$$

Riemann (or Lebesgue) integral

§I. orientation and boundary ⚠ not in the sense of topological space

1° defn M : manifold with boundary: para compact and Hausdorff.

- $\forall p \in M$. \exists open neighborhood that is homeomorphic to an open subset of $\mathbb{H}^n = \{(x^1, \dots, x^n) \in \mathbb{R}^n \mid x^n \geq 0\}$
- transition functions are smooth



★ a function / map f defined on an open subset U of \mathbb{H}^n is said to be smooth if $\exists \tilde{U}$: open in \mathbb{R}^n , $\tilde{U} \cap \mathbb{H}^n = U$, $\exists \tilde{f}$: smooth on \tilde{U} . $\Rightarrow \tilde{f}|_U = f$

- interior points = $\{p \in M \mid \exists \text{ open nbd homeomorphic to open sets in } \mathbb{R}^n\}$
- $\partial M = M \setminus \{\text{interior points}\}$

2° lemma M^n : manifold w/ boundary $\Rightarrow \partial M$ is a manifold w/o boundary of dimension $n-1$



pf: [DIY]

3° a differential form is said to be smooth if \star (i.e. locally \exists smooth extension)

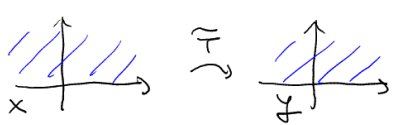
recall [HW] M is orientable if $\exists \omega \in \Omega^n(M)$ nowhere zero $\Leftrightarrow \exists$ coordinate cover $\Rightarrow \det(\text{Jacobian of transition}) > 0$

lemma $\tilde{T}: \mathbb{H}^n \hookrightarrow \mathbb{R}^n$ diffeomorphism and $\det(\text{Jac}(\tilde{T})) > 0$
Then, $T = \tilde{T}|_{\mathbb{R}^n \times \{0\}}$ is also a diffeomorphism and $\det(\text{Jac}(T)) > 0$

pf: Denote $\mathbb{R}^n \times \{0\}$ by $\partial \mathbb{H}^n$.

By IFT, $\tilde{T}: \mathbb{H}^n \hookrightarrow \mathbb{R}^n$. Hence, $\tilde{T}: \partial \mathbb{H}^n \hookrightarrow \mathbb{R}^n$

In terms of coordinate, \tilde{T} is given by $y = y(x)$ defined on some open set in \mathbb{R}^n containing \mathbb{H}^n .



and
$$\begin{cases} y^n(x^1, \dots, x^{n-1}, 0) = 0 \\ \det \left[\frac{\partial(y^1, \dots, y^n)}{\partial(x^1, \dots, x^{n-1})} \right] > 0 \end{cases}$$

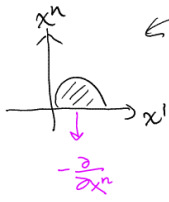
On $\partial \mathbb{H}^n \ni (x^1, \dots, x^{n-1}, 0)$, $\det(\text{Jac}(\tilde{T})) = \det \begin{bmatrix} \text{Jac}(T) & \begin{matrix} * \\ \vdots \\ * \end{matrix} \\ \frac{\partial y^i}{\partial x^j} \Big|_{\mathbb{H}^n} = 0 \dots 0 & \frac{\partial y^n}{\partial x^j} \Big|_{\mathbb{H}^n} \end{bmatrix} > 0$

Hence, $\det(\text{Jac}(T)) \cdot \frac{\partial y^n}{\partial x^j} \Big|_{\mathbb{H}^n} > 0$

Since \tilde{T} maps \mathbb{H}^n to \mathbb{H}^n , $\left. \frac{\partial y^i}{\partial x^j} \right|_{\partial \mathbb{H}^n} > 0 \Rightarrow \det(\text{Jac}(T)) > 0$ *

Cor If M is orientable, then ∂M is also orientable.

discussion



Suppose that M is orientable w/ a choice of (equivalent class of) orientation ω . Let N be a connected component of ∂M

On a coordinate chart: $\omega = f(x) dx^1 \wedge \dots \wedge dx^n$ $f(x) \neq 0$

defn Define the induced (class of) orientation by

outward direction $\left(-\frac{\partial}{\partial x^n} \right) \omega = (-1)^n f(x) dx^1 \wedge \dots \wedge dx^{n-1}$

From the proof of the lemma, the equivalent class is well-defined

On a connected, oriented manifold, there are two equivalent classes of orientations

§ II. integration and Stokes theorem

1° $f: N^n \rightarrow M^m$ a smooth map between manifolds

$$\eta \in \Omega^k(M) \rightsquigarrow f^*(\eta) \in \Omega^k(N)$$

$$\left(\begin{array}{l} \forall p \in N \quad T_p N \xrightarrow{f_*} T_{F(p)} M \\ \rightsquigarrow T_p^* N \xleftarrow{f^*} T_{F(p)}^* M \rightsquigarrow \Lambda^k(T_p^* N) \xleftarrow{f^*} \Lambda^k(T_{F(p)}^* M) \\ \forall v_1, \dots, v_k \in T_p N. \quad (f^*(\eta))(v_1, \dots, v_k) = \eta|_{F(p)}(f_* v_1, \dots, f_* v_k) \end{array} \right)$$

check $d \overset{N}{f^*(\eta)} = f^*(\overset{M}{d\eta})$

The proof is the same as the well-definedness of d

2° defn M^n w/ orientation, $\eta \in \Omega^n(M)$ w/ compact support

Define $\int_M \eta$ as follows:

Let $\{\rho_\alpha\}_\alpha$: partition of unity, $\text{supp } \rho_\alpha \subset \text{some coordinate chart}$

$\Rightarrow \rho_\alpha \eta$: still has compact support. compact support

$\Rightarrow \rho_\alpha \eta = f_\alpha(x) dx^1 \wedge \dots \wedge dx^n$ use the coordinate $\rightarrow dx^1 \wedge \dots \wedge dx^n$ is (equivalent to) the orientation

\Rightarrow Define $\int_M \rho_\alpha \eta$ by $\int_{\mathbb{R}^n} f_\alpha(x) dx^1 \wedge \dots \wedge dx^n$ Riemann integral!

Finally, $\int_M \eta := \sum_\alpha \int_M \rho_\alpha \eta$

rmk • change of variable formula for integration $\Rightarrow \int_M \rho_\alpha \eta$ does not depend on the coordinate coordinate

• By the common refinement argument, $\int_M \eta$ is independent of the choice of $\{\rho_\alpha\}_\alpha$

• reversing the orientation \Rightarrow flip the sign of $\int_M \eta$

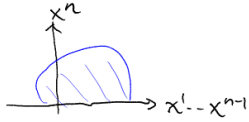
3° thm (Stokes) M^n = manifold w/ boundary and orientation.

$\eta \in \Omega^{n-1}(M)$ w/ compact support. Then $\int_M d\eta = \int_{\partial M} \eta$

pf: i) $\eta = \sum \rho_\alpha \eta$ Since $\text{supp } \eta$ is compact, this is a finite sum

$d\eta = \sum d(\rho_\alpha \eta)$ $\int_M d\eta = \sum \int_M d(\rho_\alpha \eta) \stackrel{?}{=} \sum \int_{\partial M} \rho_\alpha \eta$ It suffices to prove it for each $\rho_\alpha \eta$

ii) Assume $\text{supp}(\eta) \subset$ some chart



• By $x^i \rightarrow -x^i$, we may assume $dx^1 \wedge \dots \wedge dx^n$ is the orientation.

\Rightarrow The induced orientation on $\mathbb{R}^n \times \{0\}$ is $(-1)^n dx^1 \wedge \dots \wedge dx^{n-1}$

$\eta = \sum_{j=1}^n (-1)^{j-1} \eta_j(x) dx^1 \wedge \dots \wedge \widehat{dx^j} \wedge \dots \wedge dx^n$

\rightarrow smooth with compact support

$x^n = 0$ on $\partial M \Rightarrow dx^n = 0$ on ∂M

iii) $d\eta = \left(\sum_j \frac{\partial \eta_j}{\partial x^j} \right) dx^1 \wedge \dots \wedge dx^n$

$\int_M d\eta = \int_{\mathbb{R}^{n-1}} \left(\sum_j \frac{\partial \eta_j}{\partial x^j} \right) dx^1 \dots dx^{n-1} dx^n$

$\eta|_{\partial M} = \eta_n(x) (-1)^{n-1} dx^1 \wedge \dots \wedge dx^{n-1}$

$\Rightarrow \int_{\partial M} \eta = \int_{\mathbb{R}^{n-1}} \eta_n(x) dx^1 \dots dx^{n-1}$

Riemann integrals

For $j \neq n$ $\int_{\mathbb{R}^{n-1}} \frac{\partial \eta_j}{\partial x^j} dx^1 \dots dx^{n-1} = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} \frac{\partial \eta_j}{\partial x^j} dx^j \right) dx^1 \wedge \dots \wedge \widehat{dx^j} \wedge \dots \wedge dx^{n-1} = 0$

For $j = n$ $\int_0^\infty \frac{\partial \eta_n}{\partial x^n} dx^n = \eta_n(\infty) - \eta_n(0) = \eta_n(\infty) - \eta_n(-\infty) = 0$ by compact supp.

$\Rightarrow \int_{\mathbb{R}^{n-1}} \int_0^\infty \frac{\partial \eta_n}{\partial x^n} dx^n dx^1 \dots dx^{n-1} = - \int_{\mathbb{R}^{n-1}} \eta_n dx^1 \dots dx^{n-1} \quad \neq$

4° rk • $M =$ curve in \mathbb{R}^3 $\eta =$ function \Rightarrow fundamental theorem of vector line integral

(HW)

• $M =$ surface $\partial M =$ curve, $\eta = 1$ -form \Rightarrow (classical) Stokes theorem

• $M =$ domain in \mathbb{R}^3 , $\partial M =$ surface, $\eta = 2$ -form \Rightarrow divergence theorem

LHS: only differential forms and orientation

RHS: need inner product \Rightarrow normal, area, etc.

5° Now, shift the focus to de Rham cohomology.

Assumption M : compact and boundaryless, connected with an orientation usually call closed manifold

lemma \int_M descends to a map on $H_{dR}^n(M) \rightarrow \mathbb{R}$

pf: $H_{dR}^n(M) = \Omega^n(M) / d\Omega^{n-1}(M)$

$[\eta] = [\eta + d\xi] \Rightarrow \int_M \eta \stackrel{?}{=} \int_M \eta + d\xi$ (with arrows pointing to η as n-form and $d\xi$ as (n-1)-form)

$\Leftrightarrow \int_M d\xi = \int_{\partial M = \emptyset} \xi = 0 \quad \neq$

lemma $\int \cdot \wedge \cdot$ descends to a map on $H_{dR}^k(M) \times H_{dR}^{n-k}(M) \rightarrow \mathbb{R}$

pf: $H_{dR}^k = \text{closed } k\text{-forms } (\ker(d|_{\Omega^k})) / \text{exact } k\text{-forms } (d\Omega^{k-1})$

$$\downarrow$$

$$[\eta + d\xi] = [\eta] \quad , \quad \text{also } [\tilde{\eta} + d\tilde{\xi}] = [\tilde{\eta}] \in H_{dR}^{n-k}$$

$$\int_M (\eta + d\xi) \wedge (\tilde{\eta} + d\tilde{\xi}) \neq \int_M \eta \wedge \tilde{\eta}$$

$$\Leftrightarrow 0 = \int d\xi \wedge \tilde{\eta} = \int \eta \wedge (d\tilde{\xi}) = \int d\xi \wedge d\tilde{\xi}$$

$$d(\xi \wedge \tilde{\eta}) = d\xi \wedge \tilde{\eta} + (-1)^{k-1} \xi \wedge d\tilde{\eta} \xrightarrow{0} \text{ since } \tilde{\eta} \in \ker(d)$$

$$\Rightarrow 0 = \int_{\partial M = \emptyset} \xi \wedge \tilde{\eta} = \int_M d(\xi \wedge \tilde{\eta}) = \int_M d\xi \wedge \tilde{\eta} \quad \neq$$

thm (Poincaré duality in de Rham cohomology) Under assumption the above pairing $H_{dR}^k(M) \times H_{dR}^{n-k}(M) \rightarrow \mathbb{R}$ is non-degenerate. Hence, $H_{dR}^{n-k}(M) \cong (H_{dR}^k(M))^*$, $\Rightarrow H_{dR}^n(M) \cong (H_{dR}^0(M))^* \cong \mathbb{R}$ [sketch the (one) proof next week] constant functions

§ III. homotopy and Poincaré lemma

goal $H_{dR}^k(\mathbb{R}^n) = \mathbb{R}$ if $k=0$, and trivial for other k

0° M, N : manifold w/o boundary (for simplicity)

$$f: M \rightarrow N \Rightarrow f^*: \Omega^k(N) \rightarrow \Omega^k(M)$$

Since $f^*d = d f^* \Rightarrow f^*$ descends to $H_{dR}^k(N) \xrightarrow{f^*} H_{dR}^k(M)$

$$[\eta + d\xi] \mapsto [f^*\eta + d f^*\xi]$$

1° defn $f_0, f_1: M \rightarrow N$ are said to be homotopic

if $\exists F: M \times [0, 1] \rightarrow N$ such that $\begin{cases} F(-, 0) = f_0 \\ F(-, 1) = f_1 \end{cases}$

still d-closed
well-definedness

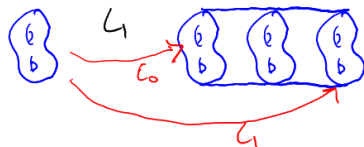
prop If f_0 and f_1 are homotopic,

then $f_0^* = f_1^*$ as a map from $H_{dR}^k(N)$ to $H_{dR}^k(M)$

pf:

$$\begin{aligned} \omega(p) &= (p, 0) \\ \omega(p) &= (p, 1) \end{aligned}$$

$$M \begin{matrix} \xrightarrow{\omega_0} \\ \xrightarrow{\omega_1} \end{matrix} M \times [0, 1] \xrightarrow{F} N$$



$$\begin{aligned} f_0 &= F \circ \omega_0 \\ f_1 &= F \circ \omega_1 \end{aligned}$$

$\omega_0^*: \Omega^k(M \times [0, 1]) \rightarrow \Omega^k(M)$: restriction on $M \times \{0\}$

$\eta \in \Omega^k(M)$ with $d\eta = 0$

$$\Rightarrow F^* \eta = \underbrace{\alpha(t)}_{\substack{\text{only } dx^i \\ \text{no } dt}} + dt \wedge \underbrace{\beta(t)}$$

where $\alpha(t) \in \Omega^k(M)$ and $\beta(t) \in \Omega^{k-1}(M)$
 I-parameter family of k & $k-1$ forms

$$\alpha(t) = \sum_{i_1, \dots, i_k} S_{i_1, \dots, i_k}(x, t) dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

in coordinate

$$\sigma = F^* d\eta = dF^* \eta$$

$$= d_M \alpha(t) + dt \wedge \frac{\partial \alpha(t)}{\partial t} - dt \wedge d_M \beta(t)$$

$$\Rightarrow \begin{cases} d_M \alpha(t) = 0 \\ \frac{\partial \alpha(t)}{\partial t} = d_M \beta(t) \end{cases}$$

Note that $f_0^* \eta = (F \circ \iota_0)^*(\eta) = \iota_0^*(F^* \eta) = \alpha(0) \in \Omega^k(M)$
 $f_1^* \eta = \alpha(1)$

$$\Rightarrow \alpha(1) - \alpha(0) = \int_0^1 d_M \beta(t) dt = d_M \left(\int_0^1 \beta(t) dt \right)$$

a path of $(k-1)$ -forms

$$\Rightarrow [f_0^* \eta] = [f_1^* \eta] \in H_{dR}^k(M) \quad \#$$

2° lemma (Poincaré) $H_{dR}^0(\mathbb{R}^n) = \mathbb{R}$, $H_{dR}^{k \neq 0}(\mathbb{R}^n) = 0$

pf: $n=1$: by single variable calculus.

$n > 1$

$$\mathbb{R}^{n-1} \times \mathbb{R}^2 \begin{matrix} \xrightarrow{\pi} \\ \xleftarrow{S} \end{matrix} \mathbb{R}^{n+1}$$

$$\begin{aligned} \pi(x^1, \dots, x^{n-1}, x^n) &= (x^1, \dots, x^{n-1}) \\ S(x^1, \dots, x^{n-1}, 0) &= (x^1, \dots, x^{n-1}, 0) \end{aligned}$$

$$\pi \circ S = \mathbb{1}_{\mathbb{R}^{n-1}} \Rightarrow S^* \circ \pi^* = \mathbb{1} \text{ on } H_{dR}^k(\mathbb{R}^{n-1})$$

It remains to check $\pi^* \circ S^* = \mathbb{1}$ on $H_{dR}^k(\mathbb{R}^n)$

$$S \circ \pi : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$(x^1, \dots, x^{n-1}, x^n) \mapsto (x^1, \dots, x^{n-1}, 0)$$

Clearly, $S \circ \pi$ is homotopic to $\mathbb{1}$ by $(1-t)(S \circ \pi) + t \mathbb{1}$

By prop, $(\pi \circ S)^* = S^* \circ \pi^* = \mathbb{1}$ on $H_{dR}^k(\mathbb{R}^n) \quad \#$

$$(x^1, \dots, x^{n-1}, x^n) \mapsto (x^1, \dots, x^{n-1}, t x^n)$$

3° remark on the argument in [BT, §I.4]

Some homology algebra: $\mu_0, \mu_1 : \Omega^{\tilde{q}} \rightarrow \tilde{\Omega}^{\tilde{q}}$ commute with d .

$$0 \rightarrow \Omega^0 \xrightarrow{d} \dots \rightarrow \Omega^{\tilde{q}-1} \xrightarrow{d} \Omega^{\tilde{q}} \xrightarrow{d} \Omega^{\tilde{q}+1} \rightarrow \dots$$

$$\mu_0 \downarrow \mu_1 \quad \swarrow \mu_0 \downarrow \mu_1 \quad \swarrow \mu_0 \downarrow \mu_1$$

$$0 \rightarrow \tilde{\Omega}^0 \xrightarrow{d} \dots \rightarrow \tilde{\Omega}^{\tilde{q}-1} \xrightarrow{d} \tilde{\Omega}^{\tilde{q}} \xrightarrow{d} \tilde{\Omega}^{\tilde{q}+1} \rightarrow \dots$$

μ_0 is "chain homotopic" to μ_1 if

$$\exists K : \Omega^{\tilde{q}} \rightarrow \tilde{\Omega}^{\tilde{q}+1}$$

$$\Rightarrow \mu_0 - \mu_1 = \pm dK \pm Kd$$

lemma chain homotopic $\Rightarrow \mu_0 = \mu_1$ on $H^{\tilde{q}}$ to $\tilde{H}^{\tilde{q}}$

Compare with the prop: $\mu_0 = f_0^*$, $\mu_1 = f_1^*$, only apply to $\ker d$
 $\Rightarrow f_0^* - f_1^* = \pm dK$

crystalised as
 a homological algebra
 lemma

$\Rightarrow K$ can be constructed explicitly if there is a homotopy in the level of manifold.