

# root system and Dynkin diagram of special unitary group

## § I. representation of torus

$T^n = S^1 \times \dots \times S^1$  consider  $T^n \rightarrow \mathbb{R}^n$ , preserving the standard inner product  
 $\Leftrightarrow \langle g \cdot \mathbf{x}, g \cdot \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{y} \rangle \Leftrightarrow T^n \rightarrow O(N)$

1°  $S^1 \rightarrow \mathbb{R}^n$

Extend to  $\mathbb{R}^n \otimes \mathbb{C} = \mathbb{C}^n$  by  $g \cdot (\bar{z}x) = z(g \cdot x)$

Also, let  $\langle z\mathbf{x}, w\mathbf{y} \rangle = z\bar{w} \langle \mathbf{x}, \mathbf{y} \rangle$  (extend to a Hermitian inner product)

$\rightsquigarrow S^1 \rightarrow \mathbb{C}^n$  is unitary  $\rightsquigarrow \mathbb{R}^2 \rightarrow \mathbb{C}^n$  is skew-Hermitian  
 $e^{2\pi i t}$   $v \mapsto \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{2\pi i t} \cdot v = A(v)$

$S^1 \rightarrow U(N) \rightsquigarrow \mathbb{R}^2 \cong T_1 S^1 \rightarrow T_2 U(N) \cong \text{skew-Herm}(N)$   
 $1 \longmapsto A$

$\Rightarrow$  Since  $A + A^* = 0$ ,  $A$  diagonalizable by unitary basis.  $\{v_1, \dots, v_N\}$ , and  $\lambda_j \in i\mathbb{R}$

2° exponential map on  $S^1 \ni \{e^{is}\}$

unit-normed complex numbers

$i\mathbb{R} \cong T_1 S^1 \rightarrow S^1$

$is \mapsto \exp(is) = 1 + is + \frac{1}{2!}(is)^2 + \dots$

Consider  $i\mathbb{R} \cong \mathbb{R}$ ; choose another identification of  $T_1 S^1$

$$is \mapsto t = \frac{s}{2\pi} \quad \exp(t) = \exp(2\pi it)$$

$T_1 S^1$  has "lattice"  $\hookrightarrow$  mapped to  $I$  under exp.

under the  $t$ -identification, integers  $= \mathbb{Z}$  CIR

3°  $A v_j = 2\pi i \lambda_j v_j \rightsquigarrow \exp(tA) v_j = e^{2\pi i \lambda_j t} v_j$

$e^{2\pi i t} \cdot v_j$

$$\begin{aligned} T_1 S^1 &\xrightarrow{\rho_*} T_2 U(N) \\ \text{Exp} &\quad 2 \quad \text{Exp} \\ S^1 &\xrightarrow{\rho} U(N) \end{aligned}$$

$\Rightarrow$  When  $t \in \mathbb{Z}$ , the action is the identity  $\Rightarrow \lambda_j \in \mathbb{Z}$ .

rank/eg.

$S^1 \rightarrow \mathbb{R}^3$

$$e^{it} \rightarrow \begin{bmatrix} \cos(lt) & \sin(lt) & 0 \\ -\sin(lt) & \cos(lt) & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \lambda = l, -l, 0.$$

4° For  $T^n \rightarrow \mathbb{R}^n$ , again identify  $T_1 T^n$  with  $\mathbb{R}^n$   
such that lattice  $= \mathbb{Z}^n$

Since  $T^n$  is abelian, its Lie algebra has  $[ , ] = 0$

Hence, the image of  $T_1 T^n$  in skew-Herm( $N$ ) has vanishing matrix bracket

By linear algebra, they can be diagonalized unitarily simultaneously.

i.e.  $\exists v_1, \dots, v_N \in \mathbb{C}^N$ .  $\Rightarrow \rho(A) \cdot v_j = 2\pi i \lambda_j(A) v_j$

$$T_1 T^n \xrightarrow{\rho_*} \text{skew-Herm}(N)$$

$\{\lambda_j\}_{j=1}^N$ : linear functional on  $T_1 T^n \cong \mathbb{R}^n$

$$T^n \xrightarrow{\rho} U(N)$$

taking integer value on  $\mathbb{Z}^n$

## §II. $G = SU(n)$

$$G = \{ S \in M(n \times n; \mathbb{C}) \mid S^* S = I, \det S = 1 \} \quad \dim G = n^2 - 1$$

$$\mathfrak{g} = \{ U \in M(n \times n; \mathbb{C}) \mid U^* + U = 0, \text{tr}(U) = 0 \}$$

$$\begin{aligned} S(t) : S(0) = I, S'(0) = U \Rightarrow \frac{d}{dt} \Big|_{t=0} (S^* S) = 0 &= U^* + U \\ \frac{d}{dt} \Big|_{t=0} \det(S) = 0 &= \text{tr}(U) \end{aligned}$$

1°  $G$  contains a torus.  $T^{n-1} = \text{diag}(e^{2\pi i \theta_1}, \dots, e^{2\pi i \theta_n})$  with  $e^{2\pi i \sum_j \theta_j} = 1$

check:  $T^{n-1}$  is maximal i.e.  $\nexists T^n \subset G \Leftrightarrow \text{max dim of abelian Lie subalgebra in } \mathfrak{g} \text{ is } n-1$

goal: study  $T^{n-1} \xrightarrow{\text{Ad}} \mathbb{R}^{n^2-1} \cong \mathfrak{g}$ , or  $T_1 T^{n-1} \cong \mathbb{R}^{n-1} \xrightarrow{\text{ad}} \mathbb{R}^{n^2-1} \cong \mathfrak{g}$

2° inner product on  $\mathfrak{g} = \mathbb{R}^{n^2-1}$

For  $U, V \in \mathfrak{g}$ ,  $\langle U, V \rangle = \text{Re } \text{tr}(U^* V)$  defines an inner product (linear algebra)  
 $= -\text{Re } \text{tr}(UV) = -\text{tr}(UV)$  in the Hermitian case

This is the one commonly used in matrix calculation. It turns out to be equivalent to the Killing form.

Indeed,  $B(U, V) = 2n \text{tr}(UV) = -\frac{1}{2n} \langle U, V \rangle$  = negative-definite

$\hookrightarrow \text{SU}(n) \xrightarrow{\text{Ad}} \mathfrak{g}$ : irreducible  $\Rightarrow$  any two  $SU(n)$ -invariant bilinear forms are proportional to each other.

rmk:  $U(n) \xrightarrow{\text{Ad}} \mathfrak{u}(n) = \text{skew-Hermitian}(n)$  is NOT irreducible

$\{ \text{diag}(is, is, \dots, is) \} \cong \mathbb{R}^1$ : I-doul invariant subspace

Now,  $T^{n-1} \subset \text{SU}(n)$ , identify  $T_1 T^{n-1} \cong \mathfrak{t} = \{ (\theta_1, \dots, \theta_n) \in \mathbb{R}^n \mid \sum_{j=1}^n \theta_j = 0 \} \subset \mathbb{R}^n$   
 $\downarrow \exp$   
 $(e^{2\pi i \theta_1}, \dots, e^{2\pi i \theta_n})$  lattice =  $\mathbb{Z}^n \cap \mathfrak{t}$

Then,  $\rho_*(\theta_1, \dots, \theta_n) = 2\pi i \text{diag}(\theta_1, \dots, \theta_n) \in \mathfrak{g}$

Now, use the following inner product on  $\mathfrak{g}$

$$\langle U, V \rangle = \frac{-1}{4\pi^2} \text{tr}(UV) \quad \text{rescaling by } \frac{1}{4\pi^2}$$

advantage:  $\langle , \rangle$  takes integer value on lattice

3° Study  $(T^{n-1} \xrightarrow{\text{Ad}} \mathfrak{g} \cong \mathbb{R}^{n^2-1} \rightsquigarrow) \mathfrak{t} \xrightarrow{\text{ad}} \mathfrak{g} \cong \mathbb{R}^{n^2-1}$

$\mathfrak{g}$  = traceless, skew-Hermitian matrices  $\xrightarrow{\text{ad}}$  traceless, Hermitian matrices

$\mathfrak{g} \otimes \mathbb{C}$  can be naturally identified with traceless matrices.

$$\mathbb{Z} = X + iY \in \mathfrak{g} \oplus i\mathfrak{g} \quad \begin{cases} X = \frac{1}{2}(Z - Z^*) \\ iY = \frac{1}{2}(Z + Z^*) \end{cases}$$

$$Z^* = -X + iY$$

$\rightsquigarrow \mathfrak{t} \xrightarrow{\text{ad}} \mathfrak{g} \otimes \mathbb{C} = \{\text{traceless}\}$  is still matrix bracket

$$\star = 2\pi i \operatorname{diag}(\theta_1, \dots, \theta_n)$$

$$\operatorname{ad}_{\star}(E_{ke}) = 2\pi i [\operatorname{diag}(\theta_1, \dots, \theta_n), E_{ke}] = 2\pi i \left[ \sum_j \frac{\partial}{\partial \theta_j} E_{kj}, E_{ke} \right] \\ = 2\pi i (\theta_k - \theta_e) E_{ke}$$

$(\dim \mathfrak{g} = n^2 - 1)$	$\operatorname{ad}_{\star}$	eigen values	eigen vectors	
	$k \neq e$	$2\pi i (\theta_k - \theta_e)$	$E_{ke}$	$n(n-1)$
	$k > e$	0	$E_{11} - E_{kk}$	$n-1$

4° as discussed in § I - 4°.  $(n^2 - 1)$ -eigenvalues  
are  $(n^2 - 1)$ -linear functional on  $\star$ ) roots

From 3°. they are  $(\theta_1, \dots, \theta_n) \mapsto \theta_k - \theta_e \quad k \neq e$   
 $\sum \theta_j = 0$

By using  $\langle U, V \rangle = -\frac{1}{4\pi^2} \operatorname{tr}(UV)$  on  $2\pi i \operatorname{diag}(\theta_1, \dots, \theta_n)$ ,  
the inner product on  $\star \subset \mathbb{R}^n$  is the one induced by the  
standard inner product on  $\mathbb{R}^n$ .

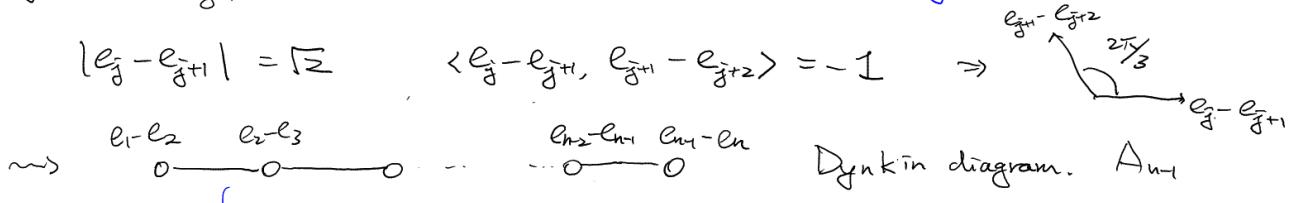
Then  $\{\text{linear functional on } \star\} \leftrightarrow \{\text{inner product with some element in } \star\}$

$$(\theta_1, \dots, \theta_n) \mapsto \theta_k - \theta_e \leftrightarrow \text{inner product with } e_k - e_e$$

Note that  $\{e_j - e_{j+1}\}_{j=1}^{n-1}$  span all the eigenvalues (roots)

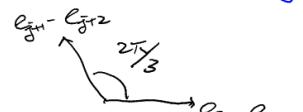
$$\text{If } k < e, \quad e_k - e_e = \sum_{j=k}^{e-1} (e_j - e_{j+1})$$

They  $\{e_j - e_{j+1}\}_{j=1}^{n-1}$  are called "simple roots" (simplest eigenvalues of  $\star \xrightarrow{\operatorname{ad}} \mathfrak{g}$ )



$$|e_j - e_{j+1}| = \sqrt{2}$$

$$\langle e_j - e_{j+1}, e_{j+1} - e_{j+2} \rangle = -1 \Rightarrow$$



$$4 \cos^2(\text{angle}) = 1$$

$$4 \cos^2(\frac{\pi}{3}) = 0 \Rightarrow \text{do not connect}$$

one key in the classification:  $4 \cos^2(\text{angle}) \in \{0, 1, 2, 3\}$