

# 從信號與系統到控制

## 單元：連續控制-2

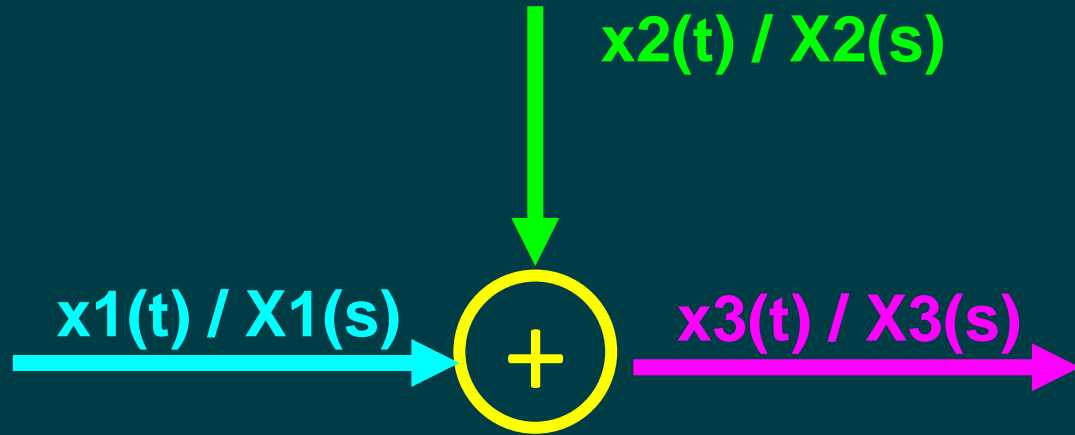
### 用基本元件 建立 連續時間系統

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# 單元學習目標與大綱

- 討論用**基本元件**來建立一個連續時間系統
- **基本元件**：加法、增益、微分、積分

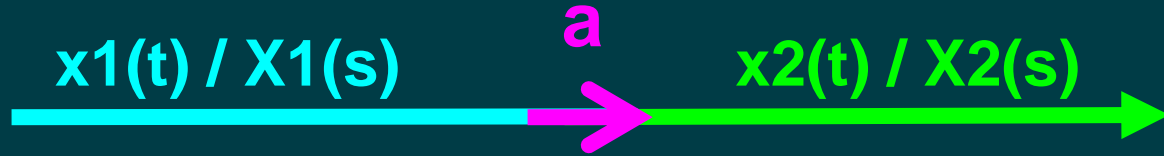
# 建立系統的基本元件 – 加法器



$$x_3(t) = x_1(t) + x_2(t)$$

$$X_3(s) = X_1(s) + X_2(s)$$

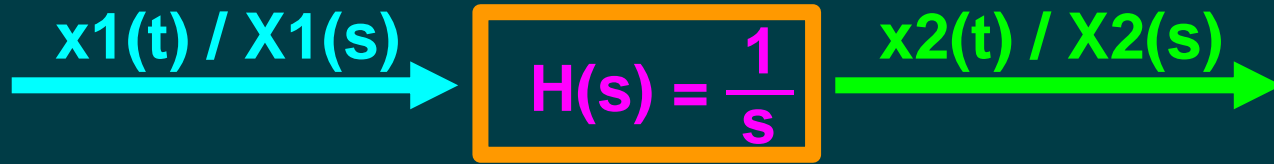
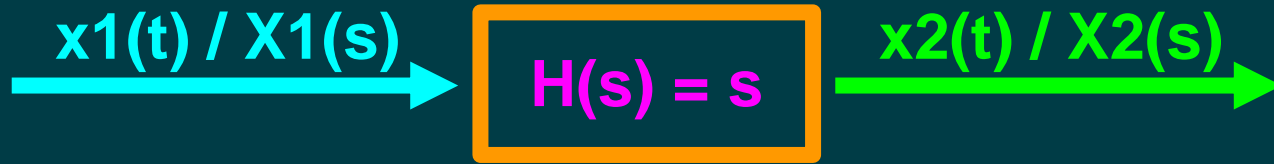
# 建立系統的基本元件 – 增益



$$x_2(t) = a x_1(t)$$

$$X_2(s) = a X_1(s)$$

# 建立系統的基本元件 – 微分與積分



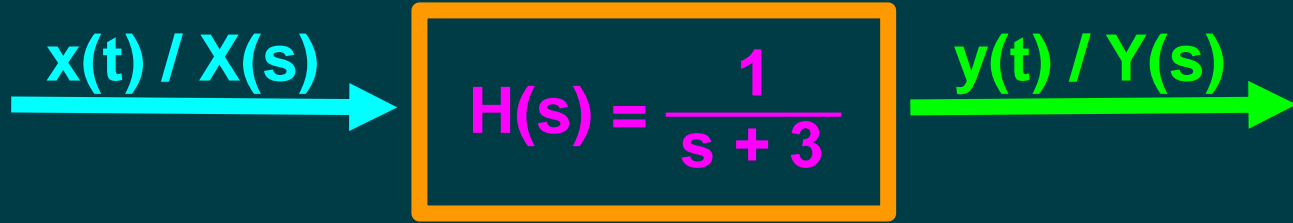
$$X_2(s) = s X_1(s)$$

$$x_2(t) = \frac{d}{dt} x_1(t)$$

$$X_2(s) = \frac{1}{s} X_1(s)$$

$$x_2(t) = \int_{-\infty}^t x_1(q) dq$$

# 連續時間系統的範例

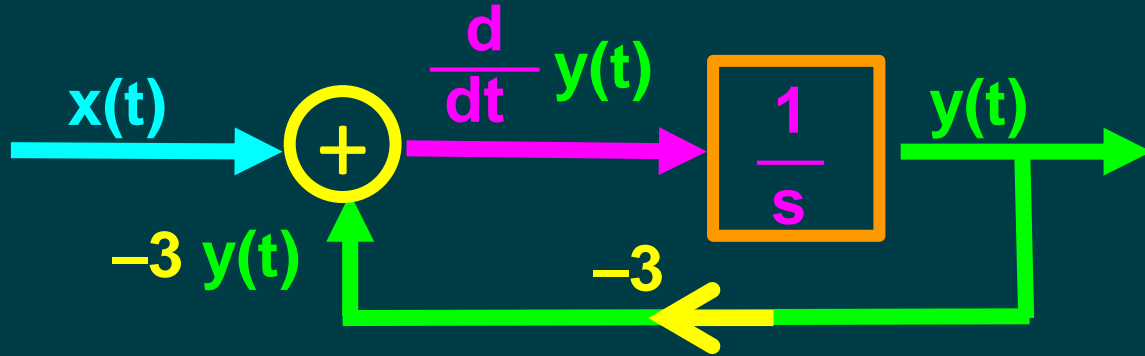
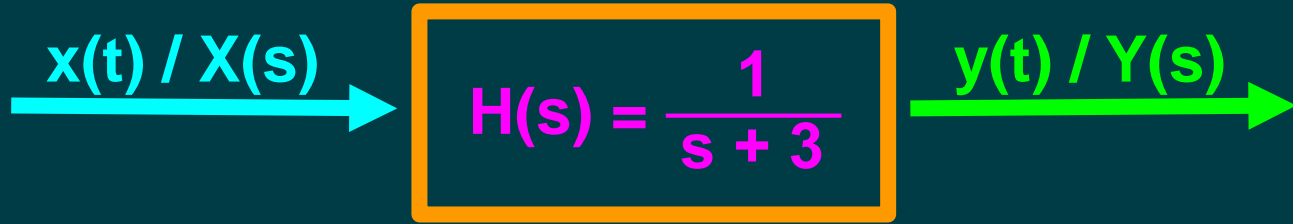


$$Y(s) = \frac{1}{s + 3} X(s)$$

$$(s + 3) Y(s) = X(s)$$

$$s Y(s) + 3 Y(s) = X(s) \quad \frac{d}{dt} y(t) + 3 y(t) = x(t)$$

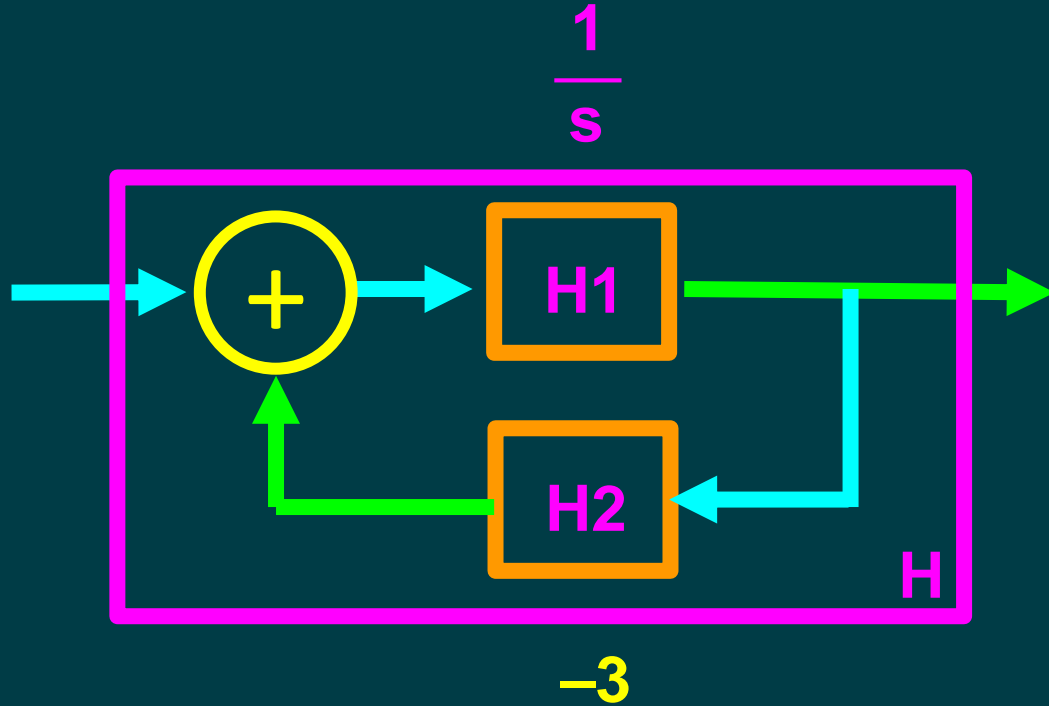
# 連續時間系統的範例



$$\frac{d}{dt} y(t) = x(t) - 3 y(t)$$

$$\frac{d}{dt} y(t) + 3 y(t) = x(t)$$

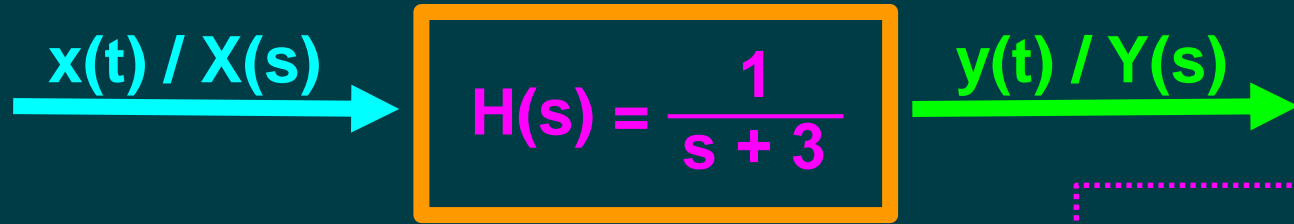
# 兩個系統的連接 – 迴授



$$\begin{aligned} H &= \frac{H1}{(1 - H1 \cdot H2)} \\ &= \frac{\frac{1}{s}}{(1 - \frac{1}{s} \cdot (-3))} \\ &= \frac{1}{(s + 3)} \end{aligned}$$

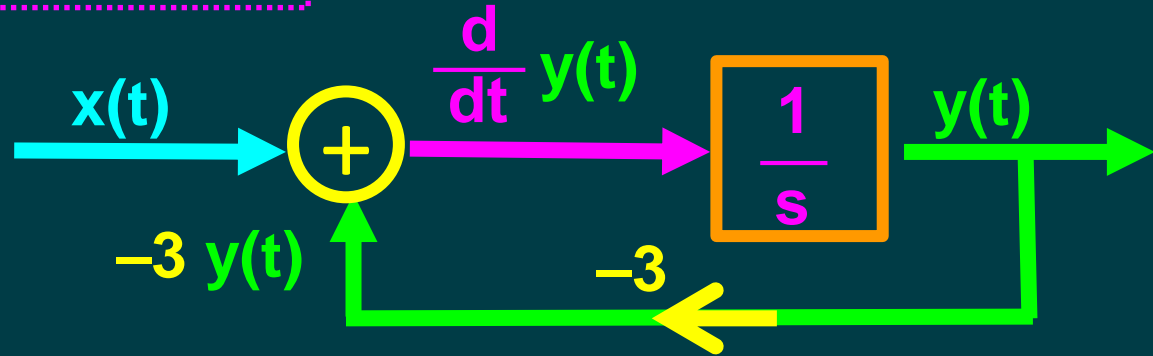


# 連續時間系統的範例



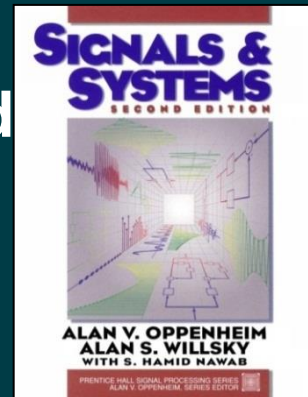
$$\frac{d}{dt} y(t) = x(t) - 3 y(t)$$

$$Y(s) = \frac{1}{s+3} X(s)$$



# 參考文獻

- Alan V. Oppenheim, Alan S. Willsky, S. Hamid  
**Signals & Systems**,  
Prentice Hall, 2nd Edition, 1997



- **SciLab:**  
Open source software for numerical computation  
<http://www.scilab.org/>