

# 從信號與系統到控制

## 單元：離散摺積-3

### 離散摺積計算-以輸入時間觀點

授課老師：連 豐 力

# 單元學習目標與大綱

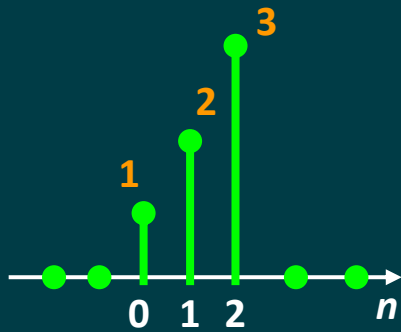
- 離散摺積計算範例
- 以輸入信號時間軸為觀點
- 以輸出信號時間軸為觀點

# 離散摺積計算



$x[n]$

\*



$h[n]$

=  $y[n]$

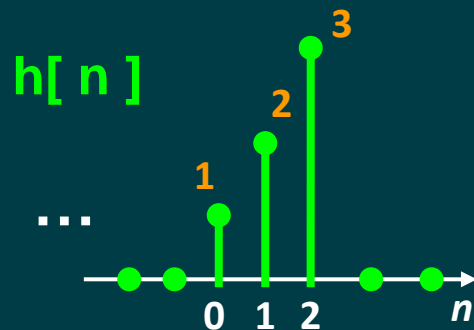
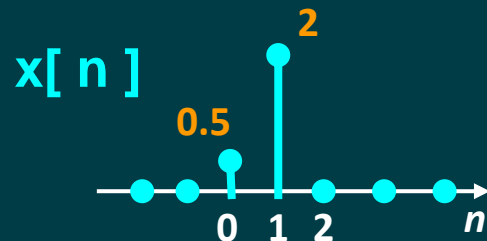
$$= \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

# 離散摺積計算-以輸入時間觀點

$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

$$= \dots + x[-1] h[n+1] + x[0] h[n] + x[1] h[n-1] + x[2] h[n-2] + \dots$$

$$= \dots + 0 h[n+1] + 0.5 h[n] + 2 h[n-1] + 0 h[n-2] + \dots$$



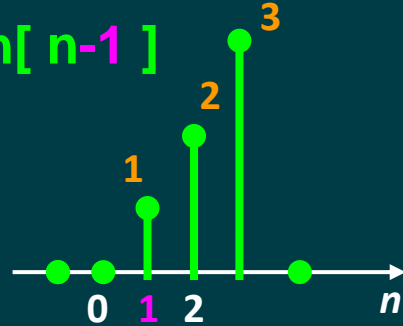
# 離散摺積計算-以輸入時間觀點

$$= 0.5 h[n] + 2 h[n-1]$$

$0.5 h[n]$



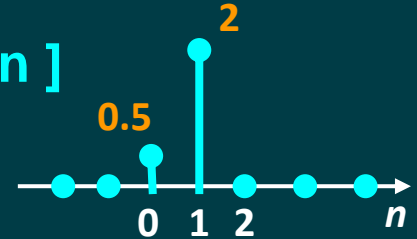
$h[n-1]$



$2 h[n-1]$



$x[n]$



$h[n]$



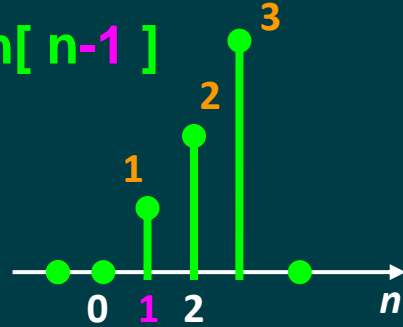
# 離散摺積計算-以輸入時間觀點

$$= 0.5 h[n] + 2 h[n-1]$$

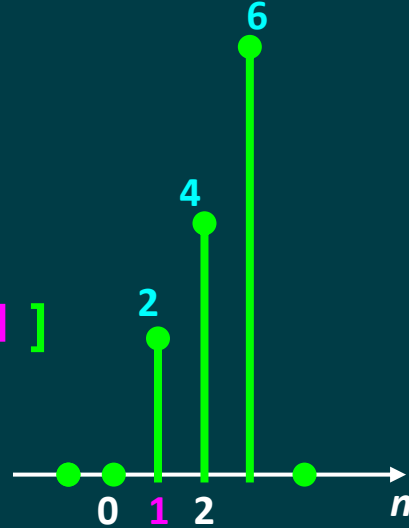
$0.5 h[n]$



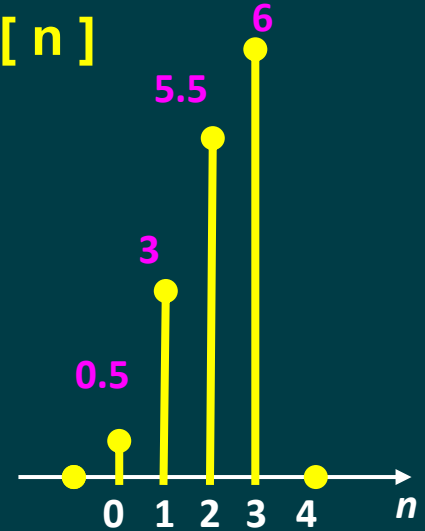
$h[n-1]$



$2 h[n-1]$

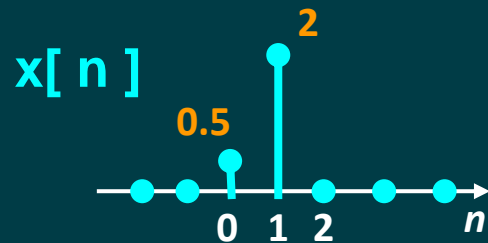


$y[n]$



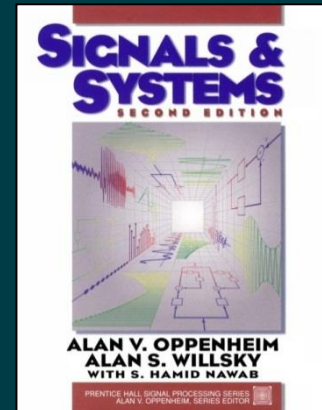
# 離散摺積計算-以輸入時間觀點

$$y[n] = 0.5 h[n] + 2 h[n-1]$$



# 參考文獻

- Alan V. Oppenheim, Alan S. Willsky, S. Hamid, **Signals & Systems**, Prentice Hall, 2nd Edition, 1997



- **SciLab:**  
Open source software for numerical computation  
<http://www.scilab.org/>