

從信號與系統到控制

單元：離散摺積-2

離散脈衝響應與摺積計算

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單元學習目標與大綱

- 線性 非時變 系統 – 基本定義
- 離散 脈衝響應 – 輸入輸出操作
- 離散 摺積計算 – 公式推導

線性非時變系統 (LTI system)

- 線性 (Linear)

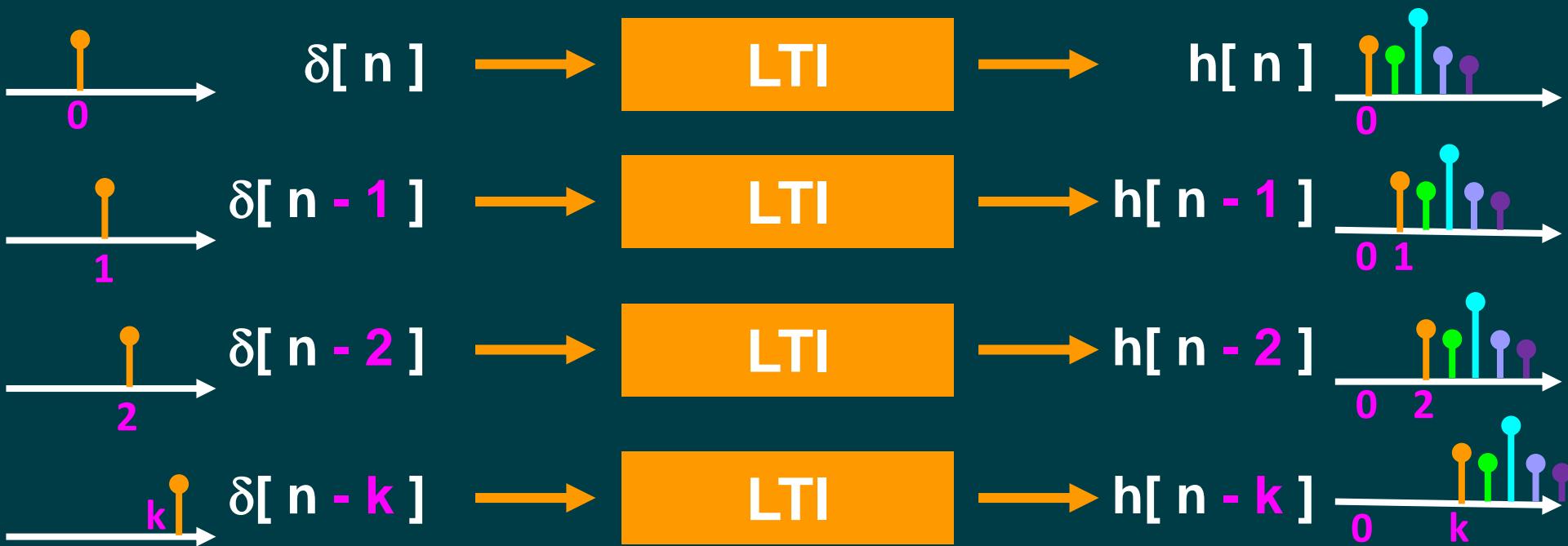


線性非時變系統 (LTI system)

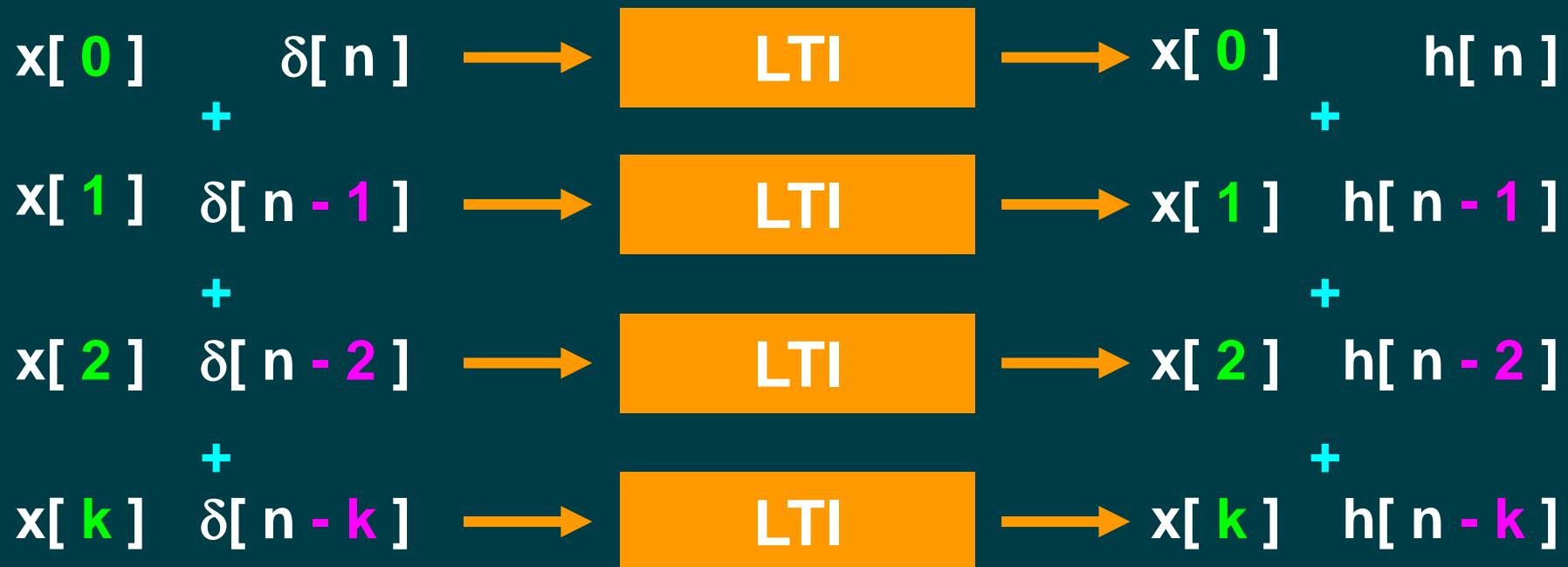
- 非時變 (Time-Invariant)



離散脈衝響應 (Impulse Response)



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$$\dots + x[0] \delta[n]$$

$$+ x[1] \delta[n-1]$$

$$+ x[2] \delta[n-2]$$

$$+ \dots$$

$$+ x[k] \delta[n-k] + \dots$$

$$= \sum_{k=-\infty}^{+\infty} x[k] \delta[n-k]$$

$$= x[n]$$



LTI



$$\dots + x[0] h[n]$$

$$+ x[1] h[n-1]$$

$$+ x[2] h[n-2]$$

$$+ \dots$$

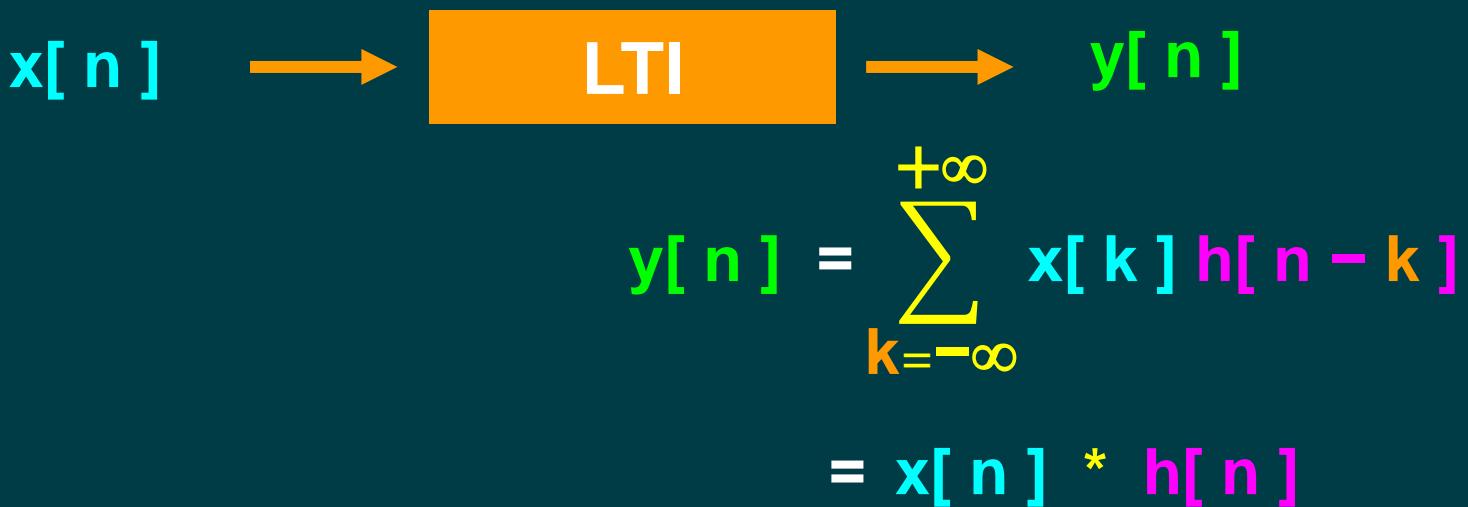
$$+ x[k] h[n-k]$$

$$+ \dots$$

$$= \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

$$= y[n]$$

離散摺積計算 (Convolution Sum)



- 級散摺積計算 (DT Convolution Sum)

離散摺積計算 (Convolution Sum)

$$x[n] * h[n] = y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

Diagram illustrating the convolution sum:

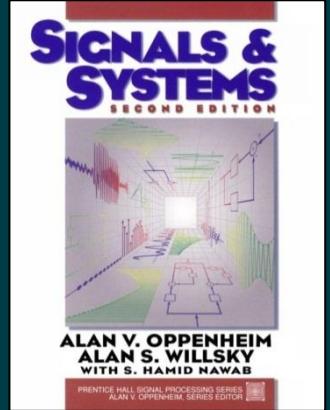
The input signal $x[n]$ (blue dots) and the impulse response $h[n]$ (magenta dots) are shown as discrete-time signals. Their convolution sum $y[n]$ (green dots) is the result of shifting $h[n]$ and summing the products of corresponding values from $x[n]$ and the shifted $h[n]$.

$$x[n] \rightarrow \text{LTI} \rightarrow y[n] = x[n] * h[n]$$

$$\delta[n] \xrightarrow{\text{LTI}} h[n] \cdot \text{離散脈衝響應}$$

參考文獻

- Alan V. Oppenheim, Alan S. Willsky, S. Hamid,
Signals & Systems,
Prentice Hall, 2nd Edition, 1997



- **SciLab:**
Open source software for numerical computation
<http://www.scilab.org/>