

Nonlinear Systems Analysis

Lecture 8

3.2: Dependence on Data

3.3: Sensitivity Analysis

3.4: Comparison Principle

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Outline

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■ 3.2: Continuous Dependence on Data

- Gronwall-Bellman Inequality
- Closeness of Solutions
- Continuous Dependence on Initial State and Parameters

■ 3.3: Sensitivity Analysis

- Differentiability of Solutions
- Sensitivity Equations

■ 3.4: Comparison Principle

- Here, we discuss the **dependence** of the **solution** of (3.1) on the **initial state** x_0 , and the **RHS function** $f(t, x)$.
- Let $y(t)$ be a **solution** of (3.1) that starts at $y(t_0) = y_0$ and is defined on the compact time interval $[t_0, t_1]$.

- **Dependence on x_0 :**
- $B_\delta(y_0) = \left\{ x \in R^n \mid \|x - y_0\| < \delta \right\}$
- Given $\epsilon > 0$, there is $\delta > 0$ such that for all z_0 in $B_\delta(y_0)$, $\dot{x} = f(t, x)$ has a **unique** solution $z(t)$ defined on $[t_0, t_1]$, with $z(t_0) = z_0$, and satisfies $\|z(t) - y(t)\| < \epsilon$ for all $t \in [t_0, t_1]$.

- Dependence on $f(t, x)$:

- One way to look at

$$\dot{x} = f(t, x)$$

$$\dot{x}_m = f_m(t, x)$$

IF $f_m(t, x) \rightarrow f(t, x), \text{ as } m \rightarrow \infty$

THEN $x_m \rightarrow x$

- The other way:
- Assume that f depends continuously on a set of constant parameters; that is,
 $f = f(t, x, \lambda)$, where $\lambda \in R^p$.
- Let $x(t, \lambda_0)$ be a solution of $\dot{x} = f(t, x, \lambda_0)$ defined on $[t_0, t_1]$, with $x(t_0, \lambda_0) = x_0$.
- And $x(t, \lambda)$ be a solution of $\dot{x} = f(t, x, \lambda)$ defined on $[t_0, t_1]$, with $x(t_0, \lambda) = x_0$.

- The solution is said to depend continuously on λ if for any $\epsilon > 0$, there is $\delta > 0$ such that for all λ in $B_\delta(\lambda_0)$, $\dot{x} = f(t, x, \lambda)$ has a **unique** solution $x(t, \lambda)$ defined on $[t_0, t_1]$, with $x(t_0, \lambda) = x_0$, and satisfies $\|x(t, \lambda) - x(t, \lambda_0)\| < \epsilon$ for all $t \in [t_0, t_1]$.

3.2: Gronwall-Bellman Inequality – 1 (App. A, page 651)

- **Lemma A.1:** (Gronwall-Bellman Inequality)
- Let $\lambda : [a, b] \rightarrow R$ be **continuous** and $\mu : [a, b] \rightarrow R$ be **cont. and nonnegative**.
- **IF** a **continuous** function $y : [a, b] \rightarrow R$ satisfies

$$y(t) \leq \lambda(t) + \int_a^t \mu(s)y(s)ds$$

for $a \leq t \leq b$,

THEN on the same interval

$$y(t) \leq \lambda(t) + \int_a^t \lambda(s) \mu(s) \exp\left(\int_s^t \mu(\tau) d\tau\right) ds$$

- In particular,
if $\lambda(t) \equiv \lambda$ is a constant, then

$$y(t) \leq \lambda \exp\left[\int_a^t \mu(\tau) d\tau\right]$$

- If, in addition,
 $\mu(t) \equiv \mu \geq 0$ is a constant, then

$$y(t) \leq \lambda \exp[\mu(t - a)]$$

3.2: Closeness of Solutions – 1

- Theorem 3.4:
- Let $f(t, x)$ be
piecewise continuous in t and
Lipschitz in x on $[t_0, t_1] \times W$
with a Lipschitz constant L ,
where $W \subset R^n$ is an open connected set.

- Let $y(t)$ and $z(t)$ be solutions of

$$\dot{y} = f(t, y), \quad y(t_0) = y_0$$

$$\text{and } \dot{z} = f(t, z) + g(t, z), \quad z(t_0) = z_0$$

such that $y(t), z(t) \in W$ for all $t \in [t_0, t_1]$.

- Suppose that

$$\|g(t, x)\| \leq \mu, \quad \forall (t, x) \in [t_0, t_1] \times W$$

for some $\mu > 0$.

- **THEN**, $\forall t \in [t_0, t_1]$

$$\begin{aligned} \|y(t) - z(t)\| &\leq \|y_0 - z_0\| \exp^{[L(t-t_0)]} \\ &\quad + \frac{\mu}{L} \left\{ \exp^{[L(t-t_0)]} - 1 \right\} \end{aligned}$$

- **Proof:**
- The solutions $y(t)$ and $z(t)$ are given by

- **Subtracting** the two equations
and taking **norms** yield

- By the **Gronwall-Bellman inequality**
(Lemma A.1)

$$\|y(t) - z(t)\| \leq$$

- Integrating the RHS by parts, we obtain

3.2: Dependence on Initial States & Parameters – 1

- Theorem 3.5:
- Let $f(t, x, \lambda)$ be
continuous in (t, x, λ) and
locally Lipschitz in x (uniformly in t and λ)
on $[t_0, t_1] \times D \times \{\|\lambda - \lambda_0\| \leq c\}$
where $D \subset \mathbb{R}^n$ is an open connected set.
- Let $y(t, \lambda_0)$ be a solution of $\dot{x} = f(t, x, \lambda_0)$
with $y(t_0, \lambda_0) = y_0 \in D$.
- Suppose $y(t, \lambda_0)$ is defined and
belongs to D for all $t \in [t_0, t_1]$.

- Then, given $\epsilon > 0$, there is $\delta > 0$

such that **IF**

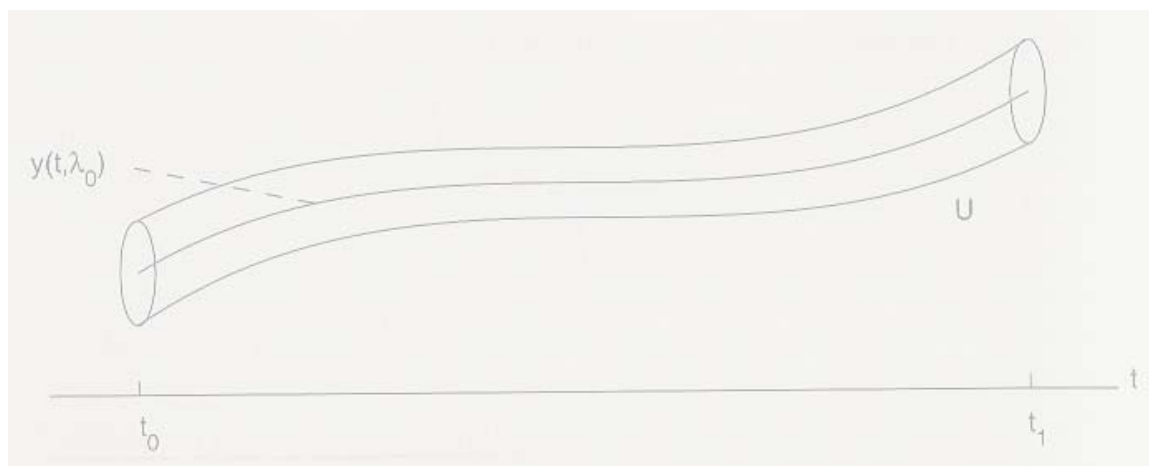
THEN there is a **unique** solution $z(t, \lambda)$

of $\dot{x} = f(t, x, \lambda)$

defined on $[t_0, t_1]$, with $z(t_0, \lambda) = z_0$,

and $z(t, \lambda)$ satisfies

- **Proof Concept:**



- Suppose that $f(t, x, \lambda)$ is continuous in (t, x, λ) and has continuous first partial derivatives w.r.t. x and λ for all $(t, x, \lambda) \in [t_0, t_1] \times \mathbb{R}^n \times \mathbb{R}^p$.
- Let λ_0 be a nominal value of λ , and suppose that the nominal state equation $\dot{x} = f(t, x, \lambda_0)$, with $x(t_0) = x_0$ has a unique solution $x(t, \lambda_0)$ over $[t_0, t_1]$.

- From Thm 3.5, for all λ sufficiently close to λ_0 , that is, $\|\lambda - \lambda_0\|$ sufficiently small, $\dot{x} = f(t, x, \lambda)$, with $x(t_0) = x_0$ has a unique solution $x(t, \lambda)$ over $[t_0, t_1]$ that is close to the nominal solution $x(t, \lambda_0)$.
- The continuous differentiability of f w.r.t. x, λ implies the additional property that the solution $x(t, \lambda)$ is differentiable w.r.t. λ near λ_0 .

- To see that, write

$$x(t, \lambda) =$$

- Take partial derivatives wrt λ yields

$$x_\lambda(t, \lambda) =$$

- Differentiating wrt t ,
it can be seen that $x_\lambda(t, \lambda)$ satisfies

$$\frac{\partial}{\partial t} x_\lambda(t, \lambda) =$$

$$A(t, \lambda) =$$

$$B(t, \lambda) =$$

- For λ sufficiently close to λ_0 ,
the matrices $A(t, \lambda)$ and $B(t, \lambda)$ are
defined on $[t_0, t_1]$.
Hence, $x_\lambda(t, \lambda)$ is defined
on the same interval.

- At $\lambda = \lambda_0$,
the RHS of (3.4) depends only on
the nominal solution $x(t, \lambda_0)$.

- Let $S(t) = x_\lambda(t, \lambda_0)$;
then $S(t)$ is the **unique** solution of

- $S(t)$ is called the **sensitivity function**, and
(3.5) is called the **sensitivity equation**.

- **Sensitivity functions** provide **first-order estimates** of the effect of **parameter variations** on solutions.
- For **small** $\|\lambda - \lambda_0\|$, $x(t, \lambda)$ can be expanded in a Taylor series about the **nominal** solution $x(t, \lambda_0)$:

- **Procedure** for calculating $S(t)$:
 - Solve the **nominal state equation** for the **nominal** solution $x(t, \lambda_0)$
 - Evaluate the **Jacobian matrices**

$$A(t, \lambda_0) = \left. \frac{\partial f(t, x, \lambda)}{\partial x} \right|_{x=x(t, \lambda_0), \lambda=\lambda_0}$$

$$B(t, \lambda_0) = \left. \frac{\partial f(t, x, \lambda)}{\partial \lambda} \right|_{x=x(t, \lambda_0), \lambda=\lambda_0}$$

- Solve the **sensitivity equation** (3.5) for $S(t)$.

- Alternative approach for calculating $S(t)$:

$$\dot{x} = f(t, x, \lambda_0), \quad x(t_0) = x_0,$$

$$\dot{S} = \left[\frac{\partial f(t, x, \lambda)}{\partial x} \right]_{\lambda=\lambda_0} S + \left[\frac{\partial f(t, x, \lambda)}{\partial \lambda} \right]_{\lambda=\lambda_0}$$

$$S(t_0) = 0$$

which is solved numerically.

3.4: Comparison Principle – 1

- Sometimes we only want to compute the **bounds** of $x(t)$ without solving it.
- The **Gronwall-Bellman Inequality** is a tool. Another tool is the **comparison lemma**.

- Consider a **differential inequality**

$$\dot{v}(t) \leq f(t, v(t))$$

and a **differential equation**

$$\dot{u}(t) = f(t, u(t)).$$

- And **two facts**:
 - If $v(t)$ is differentiable at t ,
then $D^+v(t) = \dot{v}(t)$.
 - If $\frac{1}{h}|v(t+h) - v(t)| \leq g(t, h)$, $\forall h \in (0, b]$
and $\lim_{h \rightarrow 0^+} g(t, h) = g_0(t)$
then $D^+v(t) \leq g_0(t)$.

upper RH derivative:

$$D^+v(t) = \limsup_{h \rightarrow 0^+} \frac{v(t+h) - v(t)}{h}$$

The limit $h \rightarrow 0^+$ means that h approaches zero from above.

- **Lemma 3.4: (Comparison Lemma)**
- Consider $\dot{u} = f(t, u)$, $u(t_0) = u_0$
where $f(t, u)$ is
continuous in t and
locally Lipschitz in u ,
for all $u \in J \subset \mathbb{R}$.
- Let $[t_0, T)$ (T could be infinity)
be the maximal interval of existence
of the solution $u(t)$,
and suppose $u(t) \in J$ for all $t \in [t_0, T)$.

- Let $v(t)$ be a continuous function whose upper RH derivative $D^+v(t)$ satisfies the differential inequality $D^+v(t) \leq f(t, v(t))$, $v(t_0) \leq u_0$ with $v(t) \in J$ for all $t \in [t_0, T)$.
- Then, $v(t) \leq u(t)$ for all $t \in [t_0, T)$.

3.4: Example 3.8 – 1

- Example 3.8:
- Consider the scalar D.E.

$$\dot{x} = f(x) = -(1 + x^2)x, \quad x(0) = a$$

has a unique solution on $[0, t_1)$,
for some $t_1 > 0$,
because $f(x)$ is local Lipschitz.

- Let

- $v(t)$ is differentiable and its derivative is given by

- Hence,
 $v(t)$ satisfies the differential inequality

- Let $u(t)$ be the solution of the D.E.

- Then, by the comparison lemma,
the solution $x(t)$ is defined for all $t \geq 0$
and satisfies