

Nonlinear Systems Analysis

Lecture 7

3.1: Existence & Uniqueness

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Outline

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- 3.1: Existence & Uniqueness
 - Introduction
 - Local Existence and Uniqueness
 - Lipschitz Property & Continuity
 - Global Existence and Uniqueness

- **Fundamental properties** of solutions of ODEs:
existence,
uniqueness,
continuous dependence on initial conditions,
and continuous dependence on parameters.
- Starting an experiment at t_0 ,
we **expect** that
the system will **move** and
its states will be **defined** at $t > t_0$.

- With a **deterministic** system,
we **expect** that
we can **repeat** the experiment **exactly**,
i.e. get **same motion** and **same state**
at $t > t_0$.
- To obtain this prediction,
the **initial-value problem**
$$\dot{x} = f(t, x), \quad x(t_0) = x_0$$
must have a **unique** solution.

- The **existence** and **uniqueness** can be ensured by imposing **some constraints** on $f(t, x)$.
- The **key constraint** is the **Lipschitz condition**:

for all (t, x) and (t, y)
in **some neighborhood** of (t_0, x_0) .

- An **essential factor** in the **validity** of any math model is the **continuous dependence** of its solutions on the **data** of the problem.
- The **data** are the **initial state** x_0 , the **initial time** t_0 , and the $f(t, x)$.
- Arbitrarily **small errors** in the data will **not** result in **large errors** in the solutions.

- **Sensitivity equations**
to describe the effect
of **small parameter variations**
on the performance of the system.
- **Comparison principle**
to **bound** the solution
of a scalar differential inequality

by the solution of

3.1: Existence and Uniqueness – 1

- To study the **sufficient conditions**
for the **existence** and **uniqueness**
of the solution
of the initial-value problem (3.1).
- A **solution** of (3.1) over **interval** $[t_0, t_1]$ is
a **continuous** function $x : [t_0, t_1] \rightarrow R^n$
such that
 $\dot{x}(t)$ is defined and
 $\dot{x} = f(t, x(t))$ for all $t \in [t_0, t_1]$.

- If $f(t, x)$ is **continuous** in t and x , then the **solution** $x(t)$ will be **continuously differentiable**.
- If $f(t, x)$ is **continuous** in x , but only **piecewise continuous** in t , then a **solution** $x(t)$ could only be **piecewise continuously differentiable**.

- A ball: $B_r(x_0) = \left\{ x \in \mathbb{R}^n \mid \|x - x_0\| \leq r \right\}$

- Theorem 3.1

(Local Existence and Uniqueness)

Let $f(t, x)$ be **piecewise continuous** in t and satisfy the **Lipschitz condition**

$$\|f(t, x) - f(t, y)\| \leq L\|x - y\|$$

$$\forall x, y \in B_r(x_0), \quad \forall t \in [t_0, t_1].$$

Then, there exists some $\delta > 0$

such that $\dot{x} = f(t, x)$ with $x(t_0) = x_0$

has a **unique** solution over $[t_0, t_0 + \delta]$.

- **Proof:**
- First, $x(t)$ satisfies both the following eqns:

- View its **RHS** as a **mapping** of the continuous function $x : [t_0, t_1] \rightarrow R^n$,
- Denote it by $(Tx)(t)$,
- Write it as $x(t) = (Tx)(t)$
- Note that $(Tx)(t)$ is continuous in t .
- A **solution** of it is a **fixed point** of the mapping T that maps x into Tx .
- **Existence** of a **fixed pint** can be established by using the **contraction mapping theorem**.

- We need to define a Banach space χ and a closed set $S \subset \chi$ such that T maps S into S and is a contraction over S .
- Let $\chi =$
(set of all cont. fun.)
with norm $\|x\|_C =$
and $S =$
- We restrict the choice of δ to satisfy $\delta \leq t_1 - t_0$ so that $[t_0, t_0 + \delta] \subset [t_0, t_1]$.

- Notice that $\|x(t)\|$ denotes a norm on R^n , while $\|x\|_C$ denotes a norm on χ .
- Also, B is a ball in R^n , while S is a ball in χ .
- By definition, T maps χ into χ .

- To show that T maps S into S , write

$$(Tx)(t) - x_0$$

- By **piecewise continuity** of f ,
we know that $f(t, x_0)$ is **bounded** on $[t_0, t_1]$.
Let $h = \max_{t \in [t_0, t_1]} \|f(t, x_0)\|$.

- Using the **Lipschitz condition** and
the fact that for each $x \in S$,
 $\|x(t) - x_0\| \leq r, \quad \forall t \in [t_0, t_0 + \delta]$,
we obtain

$$\|(Tx)(t) - x_0\| \leq$$

- To show that
 T is a contraction mapping over S :
- Let $x, y \in S$, consider
 $\|(Tx)(t) - (Ty)(t)\| =$

- Therefore, for $\delta \leq \frac{\rho}{L}$,

$$\|Tx - Ty\|_C \leq$$

- Choosing $\rho < 1$ and $\delta \leq \rho/L$ ensures that

T is a **contraction mapping** over S .

- By the **contraction mapping theorem**,

if δ is chosen to satisfy

$$\delta \leq$$

then (C.2) will have a **unique** solution in S .

- Our final goal is to establish

uniqueness of the solution

among all continuous functions $x(t)$,

that is, **uniqueness in χ** .

- It turns out that

any solution of (C.2) in χ will lie in S .

- Note that

since $x(t_0) = x_0$ is inside the ball B ,
any continuous solution $x(t)$ must
lie inside B for some interval of time.

- Suppose that

$x(t)$ leaves the ball B and

let $t_0 + \mu$ be the first time

$x(t)$ intersects the boundary of B .

Then, $\|x(t_0 + \mu) - x_0\| = r$.

- On the other hand, for all $t \leq t_0 + \mu$,

$$\|x(t) - x_0\| \leq$$

- Hence,
the solution $x(t)$ cannot leave the set B
within the time interval $[t_0, t_0 + \delta]$,
which implies that
any solution in χ lies in S .
- Consequently,
uniqueness of the solution in S
implies uniqueness in χ .
- QED

3.1: Lipschitz in x – 1

- A function is Lipschitz in x
with a Lipschitz constant: L
- A function $f(x)$ is said to be
local Lipschitz on a domain
(open and connected set) $D \subset R^n$
if each point of D has a neighborhood D_0
such that
 f satisfies the Lipschitz condition (3.2)
for all points in D_0
with some Lipschitz constant L_0 .

3.1: Lipschitz in x – 2

- A **local Lipschitz** function on a domain D is not necessarily **Lipschitz** on D , since the **Lipschitz condition** may **not** hold **uniformly** (with the **same constant L**) for all points in D .
- A **local Lipschitz** function on a domain D is **Lipschitz** on every **compact** (closed and bounded) subset of D .
- A function $f(x)$ is said to be **globally Lipschitz** if it is **Lipschitz** on R^n .

3.1: Lipschitz Property & Continuity – 1

- **Lemma 3.1** shows how a **Lipschitz constant** can be **calculated** using knowledge of $[\partial f/\partial x]$.
- **Lemma 3.1**
- Let $f : [a, b] \times D \rightarrow R^m$ be **continuous** for some domain $D \subset R^n$.
- Suppose that $[\partial f/\partial x]$ exists and is **continuous** on $[a, b] \times D$.

- For a convex subset $W \subset D$,
if there is a constant $L \geq 0$ such that

on $[a, b] \times W$,

then

for all $t \in [a, b]$, $x, y \in W$.

- Lemma 3.2

If $f(t, x)$ and $[\partial f / \partial x](t, x)$ are continuous on $[a, b] \times D$, for some domain $D \subset \mathbb{R}^n$,
then f is local Lipschitz in x on $[a, b] \times D$.

- Lemma 3.3

If $f(t, x)$ and $[\partial f / \partial x](t, x)$ are continuous on $[a, b] \times \mathbb{R}^n$,
then f is globally Lipschitz in x on $[a, b] \times \mathbb{R}^n$
iff $[\partial f / \partial x]$ is uniformly bounded on $[a, b] \times \mathbb{R}^n$.

- If $f(x)$ is **Lipschitz** on W ,
then it is **uniformly continuous** on W
(Exercise 3.20).
The converse is not true.
- The **Lipschitz** property is **stronger**
than **continuity**.
- **Lemma 3.2** shows that
the **Lipschitz** property is **weaker**
than **continuous differentiability**.

- Example

$$f(x) = \begin{bmatrix} \sin 3x_1 + \cos 3x_2 \\ 2 \cos x_1 - \sin x_2 \end{bmatrix}$$

- Example 3.1

$$f(x) = \begin{bmatrix} -x_1 + x_1x_2 \\ x_2 - x_1x_2 \end{bmatrix}$$

- Example 3.2

$$f(x) = \begin{bmatrix} x_2 \\ -\text{sat}(x_1 + x_2) \end{bmatrix}$$

- Theorem 3.2

(Global Existence and Uniqueness)

Suppose that

$f(t, x)$ is piecewise continuous in t

and satisfies

$$\|f(t, x) - f(t, y)\| \leq L \|x - y\|$$

$$\forall x, y \in R^n, \quad \forall t \in [t_0, t_1].$$

Then, the state equation $\dot{x} = f(t, x)$,

with $x(t_0) = x_0$,

has a **unique** solution over $[t_0, t_1]$.

- **Local Lipschitz property** of a function is basically a **smoothness** requirement. It is implied by **continuous differentiability**. Except for **discontinuous nonlinearities**, it is reasonable to expect models of physical systems to have **locally Lipschitz RHS functions**.
- **Global Lipschitz property** is restrictive.

- The following **Theorem 3.3** shows that **global existence and uniqueness** only needs the **local Lipschitz property** of f at the **expense** of having to know **more about the solution** of the system.

- Theorem 3.3

(Global Existence and Uniqueness)

- Let $f(t, x)$ be piecewise continuous in t and local Lipschitz in x for all $t \geq t_0$ and all x in a domain $D \subset \mathbb{R}^n$.
- Let W be a compact subset of D , $x_0 \in W$, and suppose it is known that every solution of $\dot{x} = f(t, x)$, $x(t_0) = x_0$ lies entirely in W .
- Then, there is a unique solution that is defined for all $t \geq t_0$.