

Spring 2021

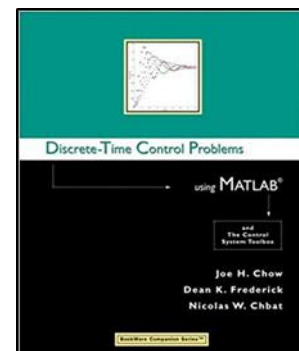
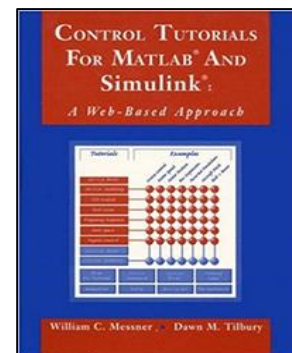
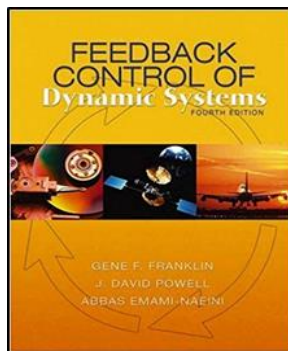
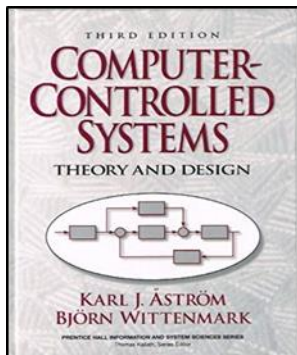
# 數位控制系統 Digital Control Systems

## DCS-02 Project

Feng-Li Lian

NTU-EE

Feb – Jun, 2021



## ■ Lecture Information:

- Time: Tuesdays 1:30pm-4:20pm
- Room: MD-303
- Office Hours: by e-mail appointment
- Website:  
<http://cc.ee.ntu.edu.tw/~fengli/Teaching/DigitalControl>

## ■ Instructor:

- 連豐力 (Feng-Li Lian)
- Office: MD-717
- Email: [fengli@ntu.edu.tw](mailto:fengli@ntu.edu.tw)
- Phone: 02-3366-3606

## ■ Grading:

- Homework (30%) bi-week
- Midterm (30%) on x/y
- Project (40%) on x/y

## ■ Textbooks:

- **Computer-Controlled Systems: Theory & Design**, 3rd. Ed., (1997),  
by Astrom & Wittenmark
- **Discrete Time Control Problems Using Matlab and the Control System Toolbox**, (2003),  
by Chow, Frederick & Chbat

## ■ References:

- **Digital Control of Dynamic Systems**, 3rd Ed., (1998),  
by Franklin, Powell, Workman
- **Real-Time Systems**, (1997),  
by Krishna & Shin
- **Real-Time Computer Control: An Introduction**, 2nd Ed., (1994),  
by Bennett
- **Control in an Information Rich World**,  
Report of the Panel on Future Directions  
in Control, Dynamics, and Systems.  
<http://www.cds.caltech.edu/~murray/cdspanel/report/cdspanel-15aug02.pdf>

### ■ Team members:

- About 1-3 students of different levels
- Auditing/Visiting students are encouraged to join a team

### ■ Subject/Title:

- Theoretical study
  - Study any digital control theory and derive possible new results
- Simulation study
  - Detailed and thorough simulation study of one application
- Software package development of digital control systems
  - Develop toolkits similar to CCSDemo and Control Tutorial

### ■ Agenda:

- 5/3: Form a team and submit one-page proposal
- 6/14: Progress Report
- 6/25: Final Report

## ■ “Economy” Class:

- Only 1 student
- Simulation study of one typical control application
  - Such as flight, DVD/HD, motor, robot, etc.
  - Should include modeling, (timing) analysis, design, and [simulation validation](#)

## ■ “Business” Class:

- $\geq 2$  students
- $\geq 10$  [digital-control-related](#) IEEE journal papers
- Could only focus on one or two of the following areas:
  - Modeling, (system or timing) analysis, design, etc.
- Strongly suggest to re-do the simulation results in the survey papers

## ■ “First” Class:

- $\leq 3$  students
- $\geq 20$  [digital-control-related](#) IEEE journal papers
- Generate good/nice (possibly new) theoretical results
- Develop different (possibly useful) digital-control-related software package

## ■ Agenda:

- 5/1: Submit one-page proposal
  - > Including title, team members, affiliation, etc., and one or two paragraphs describing your ideas
- 6/19: Presentation slides and Video and other files:
  - > One zipped file of the related electronic files including videos, documentation (docx) or presentation (pptx), matlab (m) files, etc.
    - » Presentation slides in PPTX
    - » Presentation video of 10-15 mins
    - » Submit the report to NTU-Cool  
Deadline: By 11pm, 6/19
- 6/29: Grading (Evaluation) Report
  - » Please submit the grading (evaluation) report to NTU-Cool  
Deadline: By 11pm, 6/29

### ■ Proposal by 5/1, 2021:

- Page 1:
  - Title:
  - Team: Name, ID, Department
  - Date:
- Page 2:
  - Systems:
    - > Edit a few paragraphs/keywords to describe the **specifications** of the system and **design goals**
    - > Might include 1-2 pictures
- Page 3:
  - Models:
    - > **Continuous-Time Models:** Transfer Function, State Space
    - > **Discrete-Time Models:** Transfer Function, State Space
- Page 4:
  - References: Books, Papers, Websites, etc.

- Presentation Slides, Video, Other files by 6/19, 2021:
  - Page 1:
    - Title:
    - Team: Names, IDs, Departments
    - Date:
    - etc.
  - Pages 2:
    - Outline and Summary
  - Pages 3:
    - Systems:
      - > Edit a few paragraphs/keywords to describe the **specifications** of the system and **design goals**
      - > Might include 1-2 pictures

### ■ Presentation Slides and Video by 6/19, 2021:

- Pages 4, etc.:
  - Modeling:
    - > CT vs DT models, (TF/SS) in terms of different sampling times
  - Analysis:
    - > Stability, Controllability, Observability, in terms of different sampling times
  - Design:
    - > Different controllers, observers, etc.,  
vs different sampling times, performance specification
  - Simulation studies with:
    - > Different sampling times
    - > Different design parameters
    - > Different performance specifications
- Page zzz:
  - References: Books, Papers, Websites, etc.



### ■ Grading (60%):

- Writing style & contents (10%)
- Technical content (20%)
- Evaluation by other students, teaching assistant, instructor (20%)
- Your evaluation quality (10%)

## ■ Grading (60%):

### – Writing style & contents (10%)

#### > Title

- » Does “title” actually and precisely reflect the content of this report?

#### > Introduction

- » Does it provide enough background information about this study?
- » Are references properly cited?

#### > Main results, including theoretical derivation or simulation study

- » Do it explicitly and concisely describe the results?
- » Are they good or solid enough to give readers any useful information?

#### > Discussions, summary/conclusions

- » Does it conclude anything and provide good suggestion for the future?

#### > References

- » Does it list enough cited papers?

### – Technical content (20%)

- > The contents on main result and discussions

## ■ Grading (60%):

- Evaluation by other students, teaching assistant, instructor (20%)
- Your evaluation quality (10%)
- Suggested Format:
  - > Each group should use PPTX to give a formal presentation.
  - > Every group member should video-record 10-15-min talk.
  - > Every student should grade other presentation precisely.

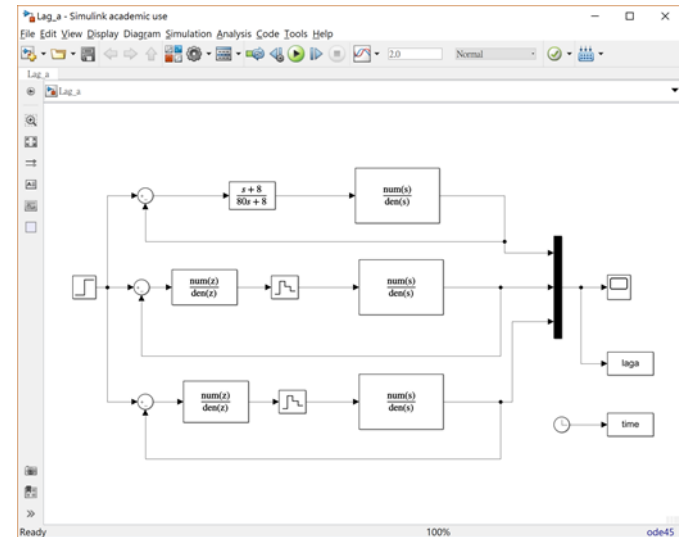
## ■ Grading (40%):

### • Report (30% from group performance):

#### – Technical content (20%)

##### > Simulation studies with:

- » Different **sampling times**
- » CT vs DT models, in terms of **different sampling times**



#### Examples – Lag

Feng-Li Lian © 2019  
DCS35-DelayCompensation-18

$$\Rightarrow G_c(s) = \frac{1}{80} \frac{(s+8)}{(s+0.1)}$$

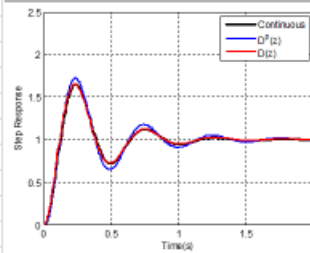
■  $D'(z)$ : by Tustin

Table 1			
	$D'(z)$	Multiplier	$D(z)$
$T = 0.01$ s	$\frac{0.0130z - 0.0120}{z - 0.9990}$	$\frac{2z}{z+1}$	$\frac{0.0260z^2 - 0.0240z}{z^2 + 0.0010z - 0.9990}$
$T = 0.05$ s	$\frac{0.0150z - 0.0100}{z - 0.9950}$	$\frac{2z}{z+1}$	$\frac{0.0299z^2 - 0.0200z}{z^2 + 0.0050z - 0.9950}$
$T = 0.1$ s	Unstable $\frac{0.0174z - 0.0075}{z - 0.9900}$	$\frac{2z}{z+1}$	Unstable $\frac{0.0348z^2 - 0.0150z}{z^2 + 0.0100z - 0.9900}$
$T = 0.1$ s	Unstable $\frac{0.0174z - 0.0075}{z - 0.9900}$	$\frac{2(z-0.2)}{(z+0.6)}$	$\frac{0.0348z^2 - 0.0219z + 0.0030}{z^2 - 0.3900z - 0.5940}$

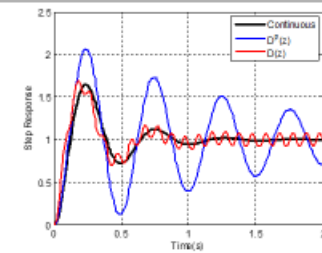
Raviv & Djaja 1999

#### Examples – Lag

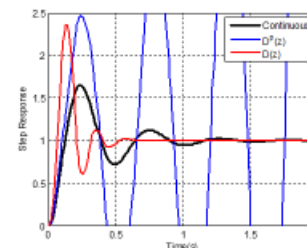
Feng-Li Lian © 2019  
DCS35-DelayCompensation-20



$T = 0.01s$



$T = 0.05s$



$T = 0.1s$

Raviv & Djaja 1999

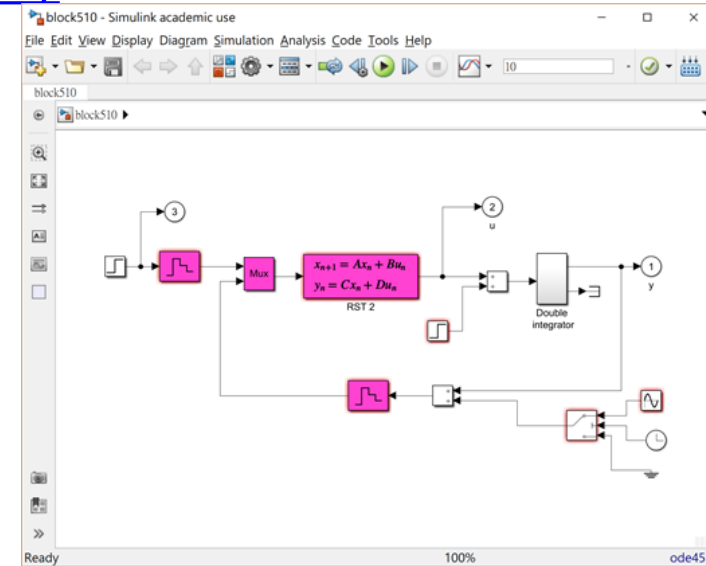
## ■ Grading (40%):

### • Report (30% from group performance):

#### – Technical content (20%)

##### > Simulation studies with:

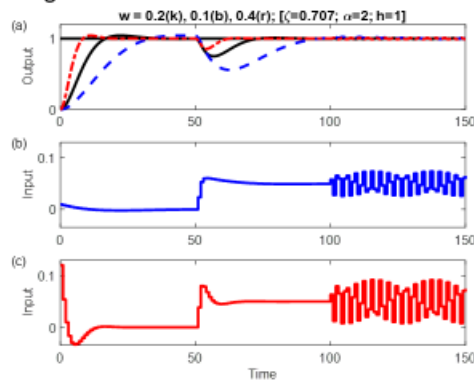
- » Different performance specifications
- » Different controllers, observers, etc.,  
vs different sampling times,  
performance specification



#### Controller Design for Double Integrator

Feng-Li Lian © 2019  
DCS32-InOutDesign-47

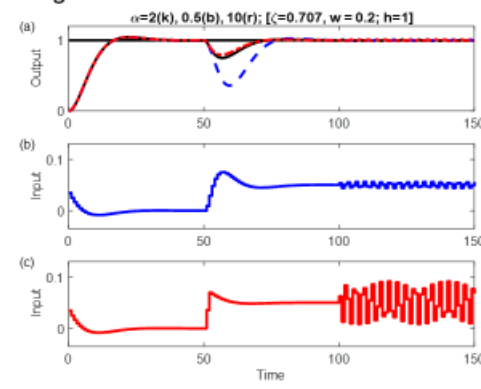
- Changing Natural Frequency  $\omega$ :
- (a)  $\omega = 0.2, 0.1, 0.4$ ; [ $\zeta = 0.707$ ;  $\alpha = 2$ ;  $h = 1$ ]
- (b) control signal when  $\omega = 0.1$
- (c) control signal when  $\omega = 0.4$



#### Controller Design for Double Integrator

Feng-Li Lian © 2019  
DCS32-InOutDesign-49

- Changing Observer Poles  $\alpha$ :  $z = e^{-\alpha h}$
- (a)  $\alpha = 2, 0.5, 10$ ; [ $\zeta = 0.707$ ;  $\omega = 0.2$ ;  $h = 1$ ]
- (b) control signal when  $\alpha = 0.5$
- (c) control signal when  $\alpha = 10$



## ■ Grading (40%):

- Presentation (10% from individual performance):
  - Evaluation by instructor (5%)
  - Evaluation by other students (5%)
  - Suggested Format:
    - > Each group should use PowerPoint to give a formal presentation.
    - > Every group member should provide at least 7-min talk.
    - > After everyone's presentation, we will have Question-&-Answer session!

## ■ Digital Control Systems

- From Analog to Digital World
- Design Consideration
- Z-transform
- Controller Design



## ■ Computer Control Systems (Single Centralized Control)

- Real-Time Operation Systems
- Analog to Digital
- Digital to Analog

## ■ Networked Control Systems (Multiple Distributed Control)

- Control Networks Protocols
- Networked Controllers & Managers
- Networked Sensors
- Networked Actuators

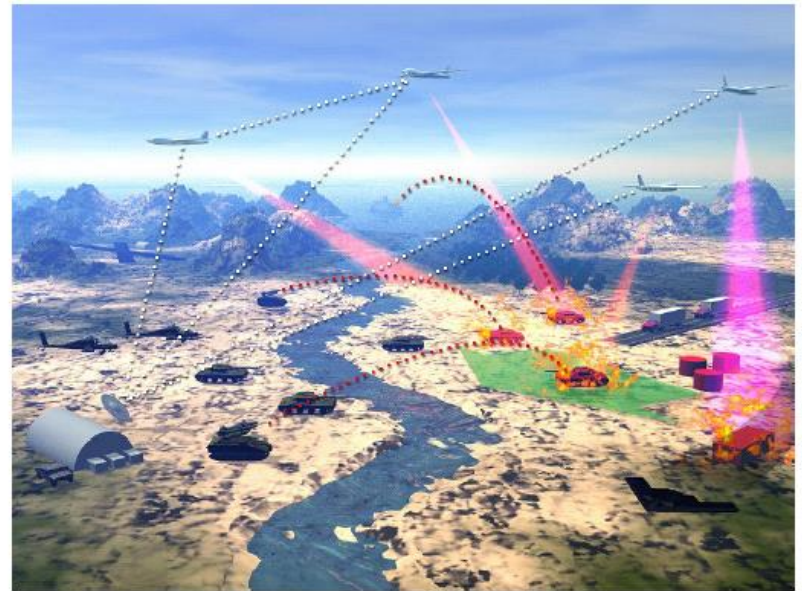
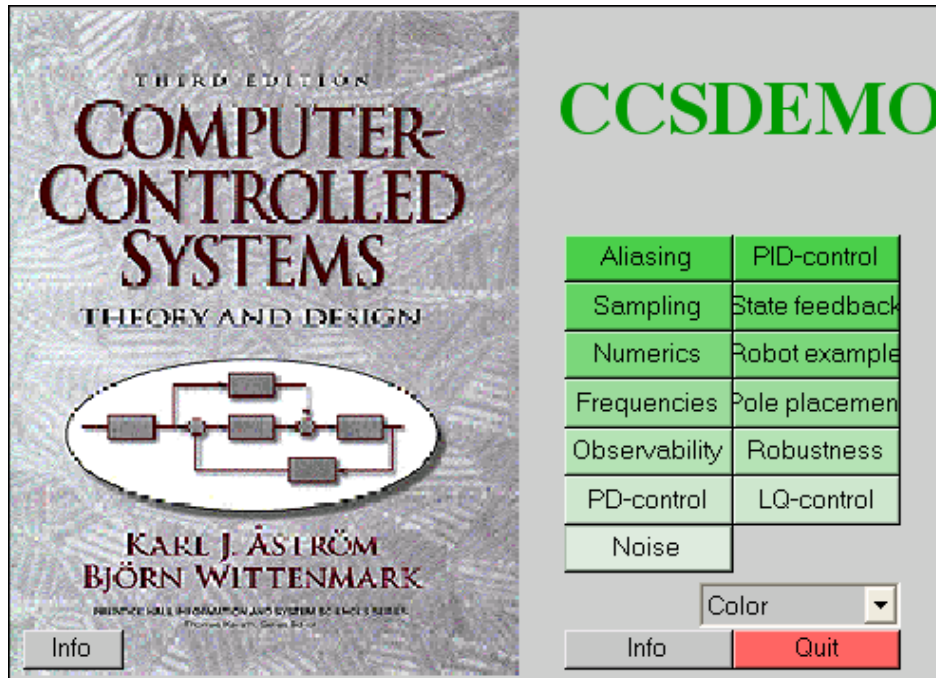


Figure 3.2. Battle space management scenario illustrating distributed command and control between heterogeneous air and ground assets. Figure courtesy of DARPA.

## ■ CCSDemo by Astrom & Wittnemark of Lund



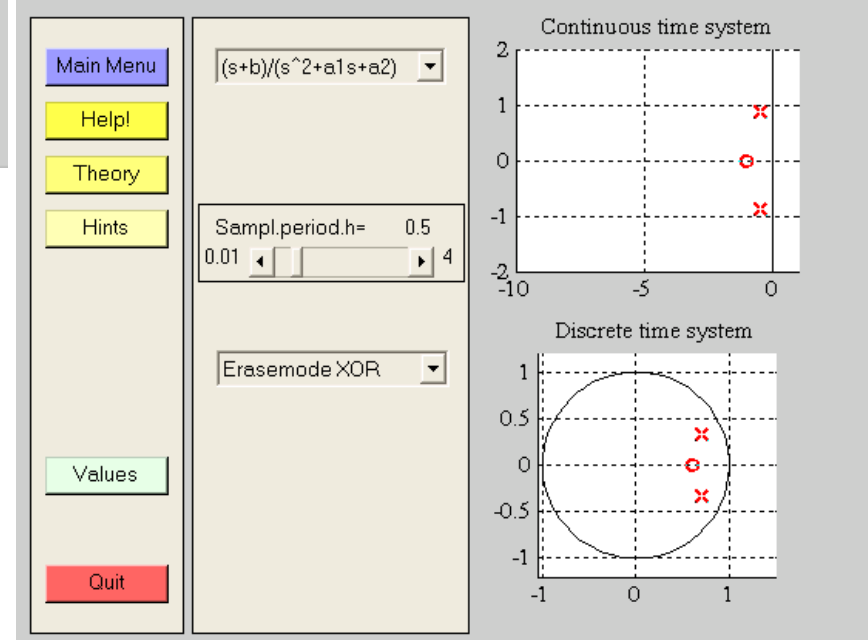
### CCSDemo

Aliasing	PID-control
Sampling	State feedback
Numerics	Robot example
Frequencies	Pole placement
Observability	Robustness
PD-control	LQ-control
Noise	

Color

Info

Quit





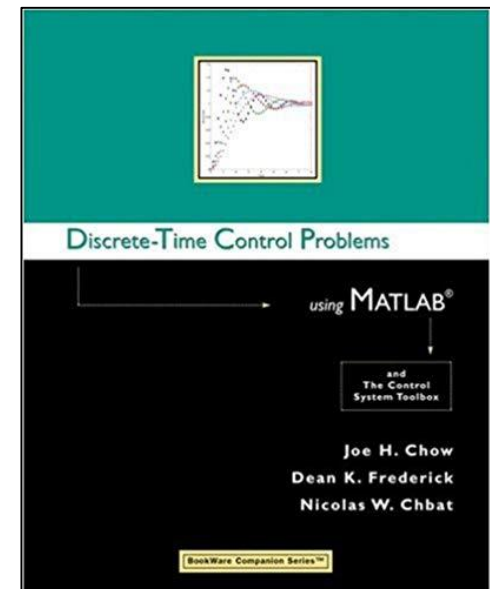
## ■ Discrete Time Control Problems

Using Matlab and the Control System Toolbox, (2003)

- by Joe H. Chow, Dean K. Frederick, Nicholas W. Chbat

## ■ Table of Content:

- 1. INTRODUCTION
- 2. SINGLE-BLOCK MODELS AND THEIR RESPONSES
- 3. BUILDING AND ANALYZING MULTI-BLOCK MODELS
- 4. STATE-SPACE MODELS
- 5. SAMPLE-DATA CONTROL SYSTEMS
- 6. FREQUENCY RESPONSE, DIGITAL FILTERS, AND DISCRETE EQUIVALENTS
- 7. SYSTEM PERFORMANCE
- 8. PROPORTIONAL-INTEGRAL-DERIVATIVE CONTROL
- 9. FREQUENCY-RESPONSE DESIGN
- 10. STATE-SPACE DESIGN METHODS
- A: Models Of Practical Systems.
  - Ball and Beam System
  - Inverted Pendulum
  - Electric Power System
  - Hydro-Turbine and Penstock
- B: Root-Locus Plots. Discrete Fourier Transform.
- C: Matlab Commands.



- Control Tutorial for Matlab & Simulink  
by Tilbury of UMich & Messner of CMU  
<http://ctms.engin.umich.edu/CTMS/>

