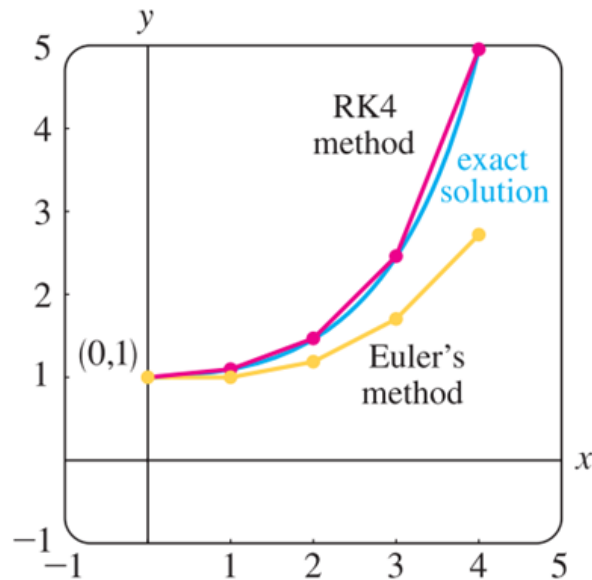


Fall 2019

# 微分方程 Differential Equations

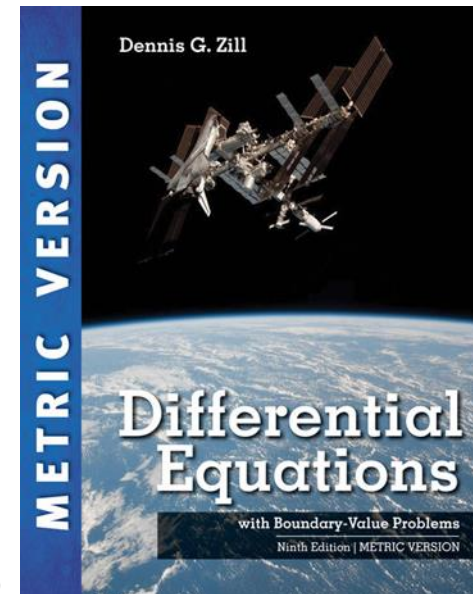
## Unit 02.6 A Numerical Method



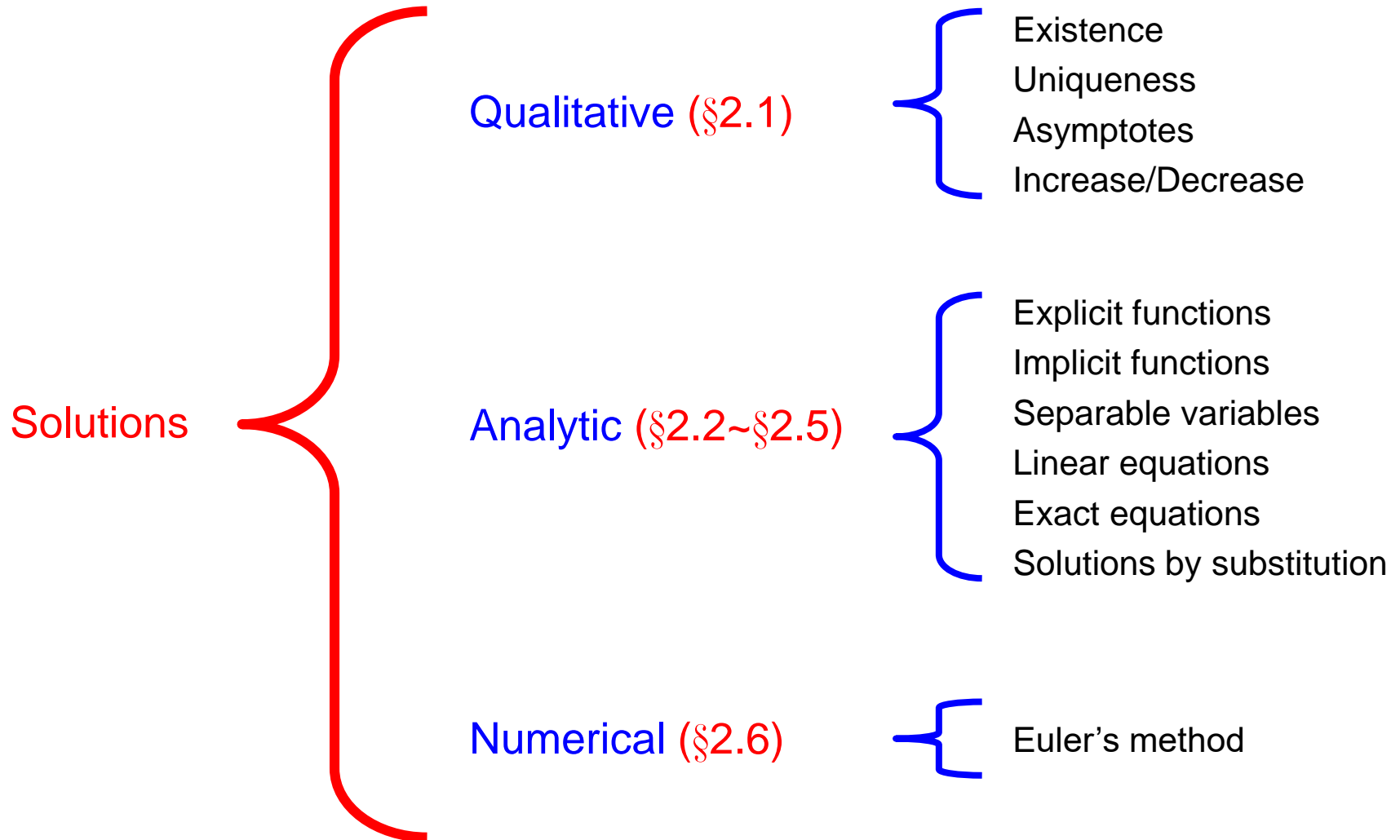
Feng-Li Lian

NTU-EE

Sep19 – Jan20



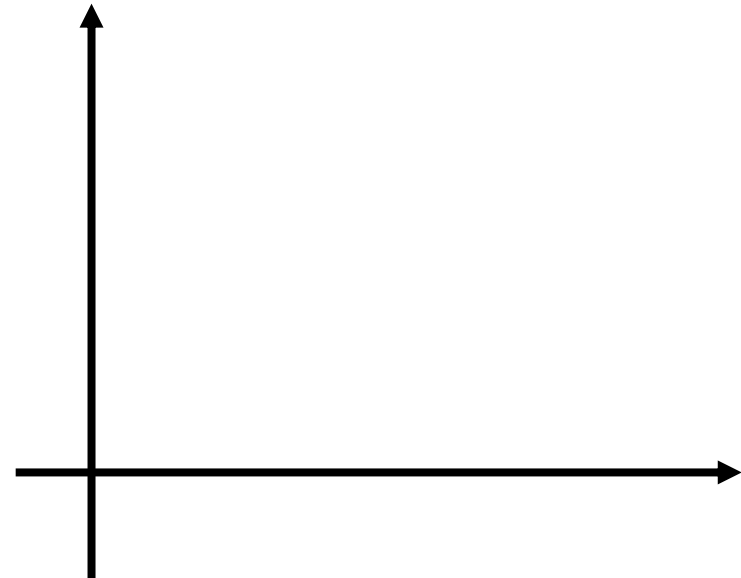
- 2.1: Solution Curves without a Solution
  - 2.1.1: Direction Fields
  - 2.1.2: Autonomous First-Order DEs
- 2.2: Separable Equations
- 2.3: Linear Equations
- 2.4: Exact Equations
- 2.5: Solutions by Substitutions
- 2.6: A Numerical Method



$$\frac{dy}{dx} = f(x, y), \quad \text{with } y(x_0) = y_0$$

- Example

$$\frac{dy}{dx} = 0.1 \sqrt{y} + 0.4 x^2, \quad \text{with } y(2) = 4$$



$$\frac{dy}{dx} = 0.1 \sqrt{y} + 0.4 x^2, \quad \text{with } y(2) = 4$$

**TABLE 2.1**  $h = 0.1$ 

---

$x_n$	$y_n$
2.00	4.0000
2.10	4.1800
2.20	4.3768
2.30	4.5914
2.40	4.8244
2.50	5.0768

---

**TABLE 2.2**  $h = 0.05$ 

---

$x_n$	$y_n$
2.00	4.0000
2.05	4.0900
2.10	4.1842
2.15	4.2826
2.20	4.3854
2.25	4.4927
2.30	4.6045
2.35	4.7210
2.40	4.8423
2.45	4.9686
2.50	5.0997

---

⇒ By Taylor series expansion

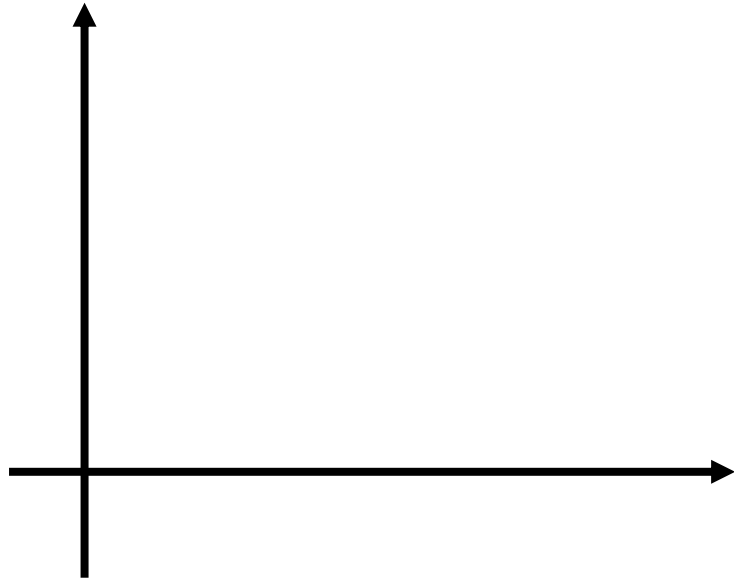
$$y(x) = y(x_0) + \left. \frac{dy}{dx} \right|_{(x_0, y_0)} \cdot (x - x_0) \\ + \frac{1}{2!} \left. \frac{d^2y}{dx^2} \right|_{(x_0, y_0)} \cdot (x - x_0)^2 + \text{H.O.T.}$$

• If  $x - x_0 = h$  is small,

⇒ H.O.T.  $(x - x_0)^2$ ,  $(x - x_0)^4$  can be neglected

⇒  $y(x) \approx$

- More systematically,



$$y_1 \approx y(x_1) \approx y_0 + h f(x_0, y_0)$$

- Let  $y_2$  be the approximation of  $y(x_2)$

⇒ slope at  $(x_1, y(x_1))$  is

⇒  $y_2 \approx$

- Both slope and tangent point are

- Summary

$$\frac{dy}{dx} = f(x, y), \quad \text{with } y(x_0) = y_0$$

$$\Rightarrow y_{n+1} = y_n + h f(x_n, y_n)$$

$$\text{where } x_n = x_0 + n \cdot h \quad \text{for } n = 0, 1, 2, \dots$$

$h$  : step size

$$\Rightarrow y_{n+1} \text{ is the approximation of } y(x_{n+1})$$



- Example 2:

$$\frac{dy}{dx} = 0.2 x y, \quad \text{with } y(1) = 1$$

- approximate:

- exact:

- absolute error:

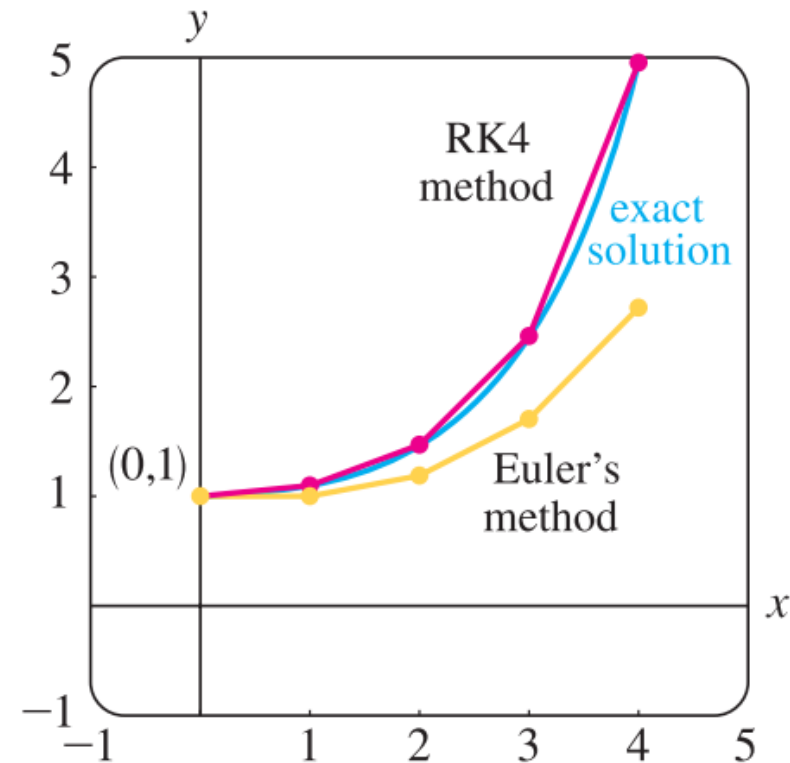
- relative error:

**TABLE 2.3**  $h = 0.1$

$x_n$	$y_n$	Actual value	Abs. error	% Rel. error
1.00	1.0000	1.0000	0.0000	0.00
1.10	1.0200	1.0212	0.0012	0.12
1.20	1.0424	1.0450	0.0025	0.24
1.30	1.0675	1.0714	0.0040	0.37
1.40	1.0952	1.1008	0.0055	0.50
1.50	1.1259	1.1331	0.0073	0.64

**TABLE 2.4**  $h = 0.05$

$x_n$	$y_n$	Actual value	Abs. error	% Rel. error
1.00	1.0000	1.0000	0.0000	0.00
1.05	1.0100	1.0103	0.0003	0.03
1.10	1.0206	1.0212	0.0006	0.06
1.15	1.0318	1.0328	0.0009	0.09
1.20	1.0437	1.0450	0.0013	0.12
1.25	1.0562	1.0579	0.0016	0.16
1.30	1.0694	1.0714	0.0020	0.19
1.35	1.0833	1.0857	0.0024	0.22
1.40	1.0980	1.1008	0.0028	0.25
1.45	1.1133	1.1166	0.0032	0.29
1.50	1.1295	1.1331	0.0037	0.32



**FIGURE 2.6.3** Comparison of the Runge-Kutta (RK4) and Euler methods