Fall 2021 (110-1)

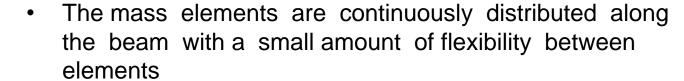
## 控制系統 Control Systems

Unit 2D
Mechanical Systems –
Distributed Parameter Systems

Feng-Li Lian NTU-EE Sep 2021 – Jan 2022

## Flexible beams

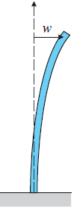
- Actual structures usually bend
- The equation is a fourth-order partial differential equation



This type of system is called a distributed parameter system

• Model (Equations of Motion, [Thomson and Dahleh, 1998] )  $EI\frac{\partial^4 w}{\partial x^4} + \rho \frac{\partial^2 w}{\partial x^2} = 0$ 





(b)

E =Young's modulus

I = beam area moment of inertia $\rho = \text{beam density}$ 

w =beam deflection at length x along the beam