Introduction to Time Series Diagnostic Tests

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Time Series Diagnostic Tests

Outline

Introduction

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Introduction

- Time series properties of y_t
 - Serial uncorrelatedness: y_t uncorrelated with y_{t-i} , i = 1, 2, ...
 - Martingale difference: y_t uncorrelated with any function on y_{t-i} , i = 1, 2, ...
 - Serial independence: No relation between any function of y_t and any function of y_{t-i} , i = 1, 2, ...
 - Time reversibility: Distributions are invariant wrt the reversal of time indices.
- Diagnostic testing
 - Testing results provide information on how these raw data may be modeled.
 - When a model is estimated, diagnostic tests on model residuals yield information about model adequacy.

- A weakly stationary time series $\{y_t\}$ is such that its autocovariances (autocorrelations) depend on *i* but not on *t*.
 - Autocovariances: $\gamma(i) = \operatorname{cov}(y_t, y_{t-i}), i = 0, 1, 2, \dots$
 - Autocorrelations: $\rho(i) = \gamma(i)/\gamma(0)$, i = 0, 1, 2, ...
- Estimates: Sample autocovariances are

$$\hat{\gamma}(i) = \frac{1}{T} \sum_{t=1}^{T-i} (y_t - \bar{y})(y_{t+i} - \bar{y});$$

sample autocorrelations are $\hat{\rho}(i) = \hat{\gamma}(i)/\hat{\gamma}(0)$.

• The null hypothesis of serial uncorrelatedness is:

$$H_0: \ \rho(1) = \rho(2) = \cdots = 0.$$

We test this hypothesis by checking sample autocorrelations.

Asymptotic Properties

Let
$$\boldsymbol{\rho}_m = (\rho(1), \dots, \rho(m))'$$
 and $\hat{\boldsymbol{\rho}}_m = (\hat{\rho}(1), \dots, \hat{\rho}(m))'$. We have
 $\sqrt{T}(\hat{\boldsymbol{\rho}}_m - \boldsymbol{\rho}_m) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{V}),$

where the (i, j)-th elements of **V** are

$$v_{ij} = \gamma(0)^{-2} [c_{i+1,j+1} - \rho(i)c_{1,j+1} - \rho(j)c_{1,i+1} + \rho(i)\rho(j)c_{1,1}],$$

with

$$c_{i+1,j+1} = \sum_{k=-\infty}^{\infty} \mathbb{E}\left[(y_t - \mu)(y_{t+i} - \mu)(y_{t+k} - \mu)(y_{t+k+j} - \mu) \right] - \mathbb{E}\left[(y_t - \mu)(y_{t+i} - \mu) \right] \mathbb{E}\left[(y_{t+k} - \mu)(y_{t+k+j} - \mu) \right].$$

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• Under the null, $\rho_m = \mathbf{0}$, so that $\sqrt{T} \mathbf{V}^{-1/2} \hat{\rho}_m \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_m)$ and

$$T\hat{\rho}'_m \mathbf{V}^{-1}\hat{\rho}_m \xrightarrow{D} \chi^2(m).$$

This result holds when **V** is replaced by a consistent estimator **V**. • When $\rho(i) = 0$ for all *i*, $v_{ij} = c_{i+1,j+1}/\gamma(0)^2$ with

$$c_{i+1,j+1} = \sum_{k=-\infty}^{\infty} \mathbb{E} \big[(y_t - \mu)(y_{t+i} - \mu)(y_{t+k} - \mu)(y_{t+k+j} - \mu) \big].$$

This can be further simplified when more conditions are imposed.

When y_t are serially independent,

$$c_{i+1,j+1} = \sum_{k=-\infty}^{\infty} \mathbb{E} \left[(y_t - \mu)(y_{t+i} - \mu)(y_{t+k} - \mu)(y_{t+k+j} - \mu) \right]$$
$$= \begin{cases} \gamma(0)^2, & i = j, \\ 0, & i \neq j. \end{cases}$$

In this case, ${\bf V}$ simplifies to ${\bf I}_m.$

Box and Pierce (1970)

Under serial independence,

$$Q_T = T \hat{\rho}'_m \hat{\rho}_m \xrightarrow{D} \chi^2(m).$$

Fuller (1976, p. 242):

$$\mathsf{cov}ig(\sqrt{T}\hat
ho(i),\,\sqrt{T}\hat
ho(j)ig) = \left\{egin{array}{c} rac{T-i}{T} + O(T^{-1}), & i=j
eq 0,\ O(T^{-1}), & i
eq j. \end{array}
ight.$$

That is, (T - i)/T is a better estimate of the diagonal elements v_{ii} in finite samples. This suggests that the finite-sample power may be improved if $\hat{\rho}(i)^2$ are normalized by (T - i)/T.

Ljung and Box (1978)

$$\widetilde{\mathcal{Q}}_T = T^2 \sum_{i=1}^m \frac{\widehat{\rho}(i)^2}{T-i} \xrightarrow{D} \chi^2(m).$$

This test is also computed as: $T(T+2)\sum_{i=1}^{m} \hat{\rho}(i)^2/(T-i)$.

Modified Q Test

• Without the serial independence condition, we assume

$$\mathbb{E}[(y_t - \mu)(y_{t+i} - \mu)(y_{t+k} - \mu)(y_{t+k+j} - \mu)] = 0,$$

for each k when $i \neq j$ and for $k \neq 0$ when i = j.

• We have: $c_{i+1,j+1} = 0$ when $i \neq j$, and

$$c_{i+1,j+1} = \mathbb{E}[(y_t - \mu)^2(y_{t+i} - \mu)^2],$$

when i = j. Hence, **V** is diagonal with $v_{ii} = c_{i+1,i+1}/\gamma(0)^2$.

• Estimate of *v_{ii}*:

$$\hat{v}_{ii} = \frac{\frac{1}{T} \sum_{t=1}^{T-i} (y_t - \bar{y})^2 (y_{t+i} - \bar{y})^2}{[\frac{1}{T} \sum_{t=1}^{T} (y_t - \bar{y})^2]^2}.$$

Lobato et al. (2001)

$$\mathcal{Q}_T^* = T \sum_{i=1}^m \hat{\rho}(i)^2 / \hat{v}_{ii} \stackrel{D}{\longrightarrow} \chi^2(m).$$

Under conditional homoskedasticity,

 $c_{i+1,i+1} = \mathbb{E}[(y_t - \mu)^2(y_{t+i} - \mu)^2] = \gamma(0)^2$. Estimating $c_{i+1,i+1}$ thus makes the Q^* test more robust to conditional heteroskedasticity, such as ARCH and GARCH processes.

• When the *Q*-type tests are applied to the residuals of an ARMA(p,q) model, the asymptotic null distribution becomes $\chi^2(m - p - q)$.

Spectral Tests

 Instead of testing only *m* autocorrelations, it would be nice if one can test all correlation coefficients. To this end, note that the spectral density function is the Fourier transform of the autocorrelations:

$$f(\omega) = rac{1}{2\pi} \sum_{j=-\infty}^{\infty}
ho(j) e^{-ij\omega}, \quad \omega \in [-\pi,\pi].$$

Under the null, $f(\omega) = (2\pi)^{-1}$.

• The spectral test compares the sample counterpart of f (also known as the periodogram) with $(2\pi)^{-1}$, i.e.,

$$\frac{1}{2\pi} \left(\sum_{j=-(\mathcal{T}-1)}^{\mathcal{T}-1} \hat{\rho}(j) e^{-ij\omega} - 1 \right).$$

• Recall that $\exp(-ij\omega) = \cos(j\omega) - i \sin(j\omega)$, where sin is an odd function and cos an even function. Thus,

$$\frac{1}{2\pi}\left(\sum_{j=-(\mathcal{T}-1)}^{\mathcal{T}-1}\hat{\rho}(j)e^{-ij\omega}-1\right)=\frac{1}{\pi}\sum_{j=1}^{\mathcal{T}-1}\hat{\rho}(j)\cos(j\omega).$$

• Integrating this function wrt ω on [0, a], $0 \le a \le \pi$, we obtain

$$\frac{1}{\pi}\sum_{j=1}^{T-1}\hat{\rho}(j)\,\frac{\sin(ja)}{j},$$

which are the cumulated differences and also a process in a.

• Durlauf's test is based on normalized, cumulated differences:

$$D_{T}(t) = \frac{\sqrt{2T}}{\pi} \sum_{j=1}^{m(T)} \hat{\rho}(j) \frac{\sin(j\pi t)}{j},$$
 (1)

where $\pi t = a$ and m(T) grows with T at a slower rate.

• The spectral representation of the standard Brownian motion B is:

$$W_T(t) = \epsilon_0 t + rac{\sqrt{2}}{\pi} \sum_{j=1}^T \epsilon_j rac{\sin(j\pi t)}{j} \Rightarrow B(t), \quad t \in [0,1],$$

where ϵ_t are i.i.d. $\mathcal{N}(0,1)$ r.v. Then, $\mathcal{W}_{\mathcal{T}}(1) = \epsilon$ and

$$W_{\mathcal{T}}(t) - tW_{\mathcal{T}}(1) = rac{\sqrt{2}}{\pi} \sum_{j=1}^{\mathcal{T}} \epsilon_j \, rac{\sin(j\pi t)}{j} \Rightarrow B^0(t), \quad t \in [0,1],$$

where B^0 denotes the Brownian bridge.

Using $\sqrt{T}\hat{\rho}(i) \approx \mathcal{N}(0,1)$, we have $D_T(t) \Rightarrow B^0(t)$, $t \in [0,1]$. A test can be constructed by applying a functional to measure the fluctuation of D_T .

Durlauf (1991)

(1) Anderson-Darling test:

$$\mathsf{AD}_{T} = \int_{0}^{1} \frac{[D_{T}(t)]^{2}}{t(1-t)} \, \mathrm{d}t \Rightarrow \int_{0}^{1} \frac{[B^{0}(t)]^{2}}{t(1-t)} \, \mathrm{d}t.$$

(2) Cramér-von Mises test:

$$\operatorname{CvM}_{T} = \int_{0}^{1} [D_{T}(t)]^{2} dt \Rightarrow \int_{0}^{1} [B^{0}(t)]^{2} dt.$$

(3) Kolmogorov-Smirnov test:

$$\mathsf{KS}_{\mathcal{T}} = \sup |D_{\mathcal{T}}(t)| \Rightarrow \sup |B^0(t)|.$$

as in Lobato et al. (2001), Deo (2000) also finds the asymptotic variance of $\sqrt{T}\hat{\rho}(j)$ is $\mathbb{E}(y_t^2 y_{t-j}^2)/\gamma(0)^2$ under conditional heteroskedasticity. Normalized using \hat{v}_{jj} we have

$$D^{\mathsf{c}}_{\mathcal{T}}(t) = rac{\sqrt{2\,\mathcal{T}}}{\pi}\,\sum_{j=1}^{m(\mathcal{T})}rac{\hat{
ho}(j)}{\sqrt{\hat{m{v}}_{jj}}}\,rac{{
m sin}(j\pi t)}{j}.$$

The test based on D_T^c ought to be more robust to conditional heteroskedasticity than Durlauf's test.

Deo (2000)

$$\operatorname{CvM}_T^c = \int_0^1 [D_T^c(t)]^2 \, \mathrm{d} t \Rightarrow \int_0^1 [B^0(t)]^2 \, \mathrm{d} t.$$

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- Null hypothesis: i.i.d.
- y_t are i.i.d. with mean zero and variance σ^2 . For any k, var $(y_t + \cdots + y_{t-k+1}) = k\sigma^2$.
- Let $\tilde{\sigma}_k^2$ denote an estimator of $\operatorname{var}(y_t + \cdots + y_{t-k+1})$ and $\hat{\sigma}^2$ the sample variance of y_t . Then, $\tilde{\sigma}_k^2/k$ and $\hat{\sigma}^2$ should be close to each other under the null.
- The variance ratio test of Cochrane (1988) is simply a normalized version of $\tilde{\sigma}_k^2/(k\hat{\sigma}^2)$.
- Notation: η_t is the partial sum of y_i such that $y_t = \eta_t \eta_{t-1}$. Suppose there are kT + 1 observations $\eta_0, \eta_1, \dots, \eta_{kT}$.

• The standard estimator of σ^2 :

$$\hat{\sigma}^2 = \frac{1}{kT} \sum_{t=1}^{kT} (\eta_t - \eta_{t-1} - \bar{y})^2,$$

which is both consistent and asymptotically efficient under the null.

• An estimator of $\sigma_k^2 = var(\eta_t - \eta_{t-k})$ is

$$\tilde{\sigma}_{k}^{2} = \frac{1}{T} \sum_{t=1}^{T} (\eta_{kt} - \eta_{kt-k} - k\bar{y})^{2} = \frac{1}{T} \sum_{t=1}^{T} [k(\bar{y}_{t} - \bar{y})]^{2},$$

where $\bar{y}_t = \sum_{kt-k+1}^{kt} y_i/k$. Clearly, $\tilde{\sigma}_k^2/k$ is consistent for σ^2 but not asymptotically efficient under the null.

• Under the null, $\sqrt{kT}(\hat{\sigma}^2 - \sigma^2) \stackrel{D}{\longrightarrow} \mathcal{N}(0, 2\sigma^4)$ and

$$\sqrt{T}(\tilde{\sigma}_k^2 - k\sigma^2) \xrightarrow{D} \mathcal{N}(0, 2k^2\sigma^4).$$

- Hausman (1978) test: Let $\hat{\theta}_e$ be a consistent and asymptotically efficient estimator of θ and $\hat{\theta}_c$ a consistent but not asymptotically efficient estimator. Then, $\hat{\theta}_e$ is asymptotically uncorrelated with $\hat{\theta}_c - \hat{\theta}_e$. For if not, there would exist a linear combination of $\hat{\theta}_e$ and $\hat{\theta}_c - \hat{\theta}_e$ that is asymptotically more efficient than $\hat{\theta}_e$.
- A decomposition:

$$\frac{1}{\sqrt{k}}\sqrt{T}(\tilde{\sigma}_k^2 - k\sigma^2) = \sqrt{kT}\left(\frac{\tilde{\sigma}_k^2}{k} - \sigma^2\right)$$
$$= \sqrt{kT}\left(\frac{\tilde{\sigma}_k^2}{k} - \hat{\sigma}^2\right) + \sqrt{kT}(\hat{\sigma}^2 - \sigma^2).$$

The LHS is $\mathcal{N}(0, 2k\sigma^4)$, and the second term on the RHS is $\mathcal{N}(0, 2\sigma^4)$.

• The first term on the RHS is thus:

$$\sqrt{kT}\left(\frac{\tilde{\sigma}_k^2}{k}-\hat{\sigma}^2\right) \stackrel{D}{\longrightarrow} \mathcal{N}(0, 2(k-1)\sigma^4).$$

The normalized variance ratio is

$$\sqrt{kT}\left(\frac{\tilde{\sigma}_k^2}{k\hat{\sigma}^2}-1\right) \xrightarrow{D} \mathcal{N}(0, 2(k-1)).$$

Cochrane (1988)

Letting VR = $\tilde{\sigma}_k^2/(k\hat{\sigma}^2)$, we have under the null of i.i.d.,

$$\sqrt{kT}(VR-1)/\sqrt{2(k-1)} \xrightarrow{D} \mathcal{N}(0, 1).$$

- Null hypothesis: i.i.d.
- Brock, Dechert, and Scheinkman (1987) and Brock, Dechert, Scheinkman, and LeBaron (1996).

• A strictly stationary process $\{y_t\}$ is said to be time reversible (TR) if

$$F_{t_1,t_2,\ldots,t_n}(c_1,c_2,\ldots,c_n) = F_{t_n,t_{n-1},\ldots,t_1}(c_1,c_2,\ldots,c_n).$$

Examples: Independent sequences, Gaussian ARMA processes.

- When the condition fails, $\{y_t\}$ is said to be time irreversible.
 - A linear, non-Gaussian process is time irreversible in general.
 - Tong (1990): "time irreversibility is the rule rather than the exception when it comes to nonliearity" (p. 197).
- A test of time reversibility can be viewed as a joint test of linearity and Gaussianity or a test of independence, e.g., Ramsey and Rothman (1996) and Chen, Chou, and Kuan (2000).

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A Condition on Distribution Symmetry

- Cox (1981): When {y_t} is TR, the marginal distribution of y_t y_{t-k} must be symmetric about the the origin for any k.
- Existing tests of the symmetry of $y_t y_{t-k}$:
 - Testing the third central moment being zero.
 - Testing the bi-covariances being zero, because

$$\mathbb{E}(y_t - y_{t-k})^3 = -3 \mathbb{E}(y_t^2 y_{t-k}) + 3 \mathbb{E}(y_t y_{t-k}^2).$$

• Note: These are all necessary conditions of distribution symmetry. Drawbacks: Such tests require the data to possess high-order moments.

• A distribution is symmetric iff the imaginary part of its characteristic function is zero. Hence, time reversibility implies

$$h_k(\omega) := \mathbb{E} \left[\sin \left(\omega (y_t - y_{t-k}) \right) \right] = 0, \quad \forall \omega \in \mathbb{R}^+.$$

 We may integrate out ω with a positive and integrable weighting function g:

$$\int_{\mathbb{R}^+} h_k(\omega) g(\omega) \, \mathrm{d}\omega = \int_{\mathbb{R}} \left(\int_{\mathbb{R}^+} \sin \big(\omega (y_t - y_{t-k}) \big) g(\omega) \, \mathrm{d}\omega \right) \, \mathrm{d}F = 0,$$

where F is the cdf of y_t .

• We can test if $\mathbb{E}[\psi_g(y_t-y_{t-k})]=0,$ with

$$\psi_{g}(y_{t} - y_{t-k}) = \int_{\mathbb{R}^{+}} \sin(\omega(y_{t} - y_{t-k}))g(\omega) d\omega.$$

CCK Test

Chen, Chou, and Kuan (2000)

$$\mathcal{C}_{g,k} = \sqrt{T_k} \bar{\psi}_{g,k} / \bar{\sigma}_{g,k} \stackrel{D}{\longrightarrow} \mathcal{N}(0,1).$$

where $T_k = T - k$, $\bar{\psi}_{g,k} = \sum_{t=k+1}^{T} \psi_g(y_t - y_{t-k}) / T_k$, and $\bar{\sigma}_{g,k}^2$ is a consistent estimator of the asymptotic variance of $\sqrt{T_k} \bar{\psi}_{g,k}$.

- ψ_g is bounded so that no moment condition is needed for the CLT; this test is thus robust to moment failure.
- Setting $g(\omega) = \exp(-\omega/\beta)/\beta$ with $\beta > 0$ (exponential dist),

$$\psi_{\exp}(y_t - y_{t-k}) = \frac{\beta(y_t - y_{t-k})}{1 + \beta^2(y_t - y_{t-k})^2};$$

a rule of thumb is to set $\beta=1/\sigma_y.$



Figure: $h(\omega)$ of centered exponential distributions with $\beta = 0.5$ (line 0), $\beta + 1$ (line 1) and $\beta = 2$ (line 2).

- When this test is applied to model residuals, it is difficult to estimate the asymptotic variance of $\sqrt{T_k}\bar{\psi}_{g,k}$. An easy way is to bootstrap the standard error.
- Chen and Kuan (2002): This test is powerful against asymmetric dependence in data, such as volatility asymmetry, but the existing *Q*-type and BDS tests are not. Thus, this test may be used to distinguish between EGARCH and GARCH models.
- We may test the L₂ norm of h_k(·): ∫_{ℝ+} h_k(ω)² dω = 0. The resulting test does not have an analytic form and usually has a data-dependent distribution.