Elements of Probability Theory

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Lecture Outline

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Probability Space and σ -Algebra

- A probability space is a triplet $(\Omega, \mathcal{F}, \mathbb{P})$, where
 - Ω is the outcome space, whose elements ω are outcomes of the random experiment,
 - **2** \mathcal{F} is a a σ -algebra, a collection of subsets of Ω ,
 - **(3)** \mathbb{P} is a a probability measure assigned to the elements in \mathcal{F} .
- \mathcal{F} is a σ -algebra if
 - $\ \, \Omega \in \mathcal{F},$
 - 2) if $A \in \mathcal{F}$, then $A^c \in \mathcal{F}$,
 - **3** if $A_1, A_2, \dots \in \mathcal{F}$, then $\bigcup_{n=1}^{\infty} A_n \in \mathcal{F}$.
- By (2), $\Omega^{c} = \emptyset \in \mathcal{F}$. From de Mongan's law,

$$\left(\bigcup_{n=1}^{\infty}A_n\right)^c=\bigcap_{n=1}^{\infty}A_n^c\in\mathcal{F}.$$

If {A_n} is an increasing (decreasing) sequence in *F* with the limiting set A, then lim_{n→∞} P(A_n) = P(A).

Borel Field

- Let C be a collection of subsets of Ω. The σ-algebra generated by C, σ(C), is the intersection of all σ-algebras that contain C and hence the smallest σ-algebra containing C.
- When Ω = ℝ, the Borel field, B, is the σ-algebra generated by all open intervals (a, b) in ℝ.
- Note that (a, b), [a, b], (a, b], and (-∞, b] can be obtained from each other by taking complement, union and/or intersection. For example,

$$(a,b] = \bigcap_{n=1}^{\infty} \left(a,b+\frac{1}{n}\right), \qquad (a,b) = \bigcup_{n=1}^{\infty} \left(a,b-\frac{1}{n}\right].$$

Thus, the collection all open intervals (closed intervals, half-open intervals or half lines) generates the same Borel field.

• The Borel field on \mathbb{R}^d , \mathcal{B}^d , is generated by all open hypercubes:

$$(a_1, b_1) \times (a_2, b_2) \times \cdots \times (a_d, b_d).$$

• \mathcal{B}^d can be generated by all closed hypercubes:

$$[a_1, b_1] \times [a_2, b_2] \times \cdots \times [a_d, b_d],$$

or by

$$(-\infty, b_1] \times (-\infty, b_2] \times \cdots \times (-\infty, b_d].$$

• The sets that generate the Borel field \mathcal{B}^d are all Borel sets.

 A random variable z defined on (Ω, F, P) is a function z: Ω → ℝ such that for every B in the Borel field B, its inverse image is in F:

$$z^{-1}(B) = \{\omega \colon z(\omega) \in B\} \in \mathcal{F}.$$

That is, z is a \mathcal{F}/\mathcal{B} -measurable (or simply \mathcal{F} -measurable) function.

- Given ω , the resulting value $z(\omega)$ is known as a realization of z.
- A R^d valued random variable (random vector) z defined on (Ω, F, IP)
 is: z: Ω → R^d such that for every B ∈ B^d,

$$\mathbf{z}^{-1}(B) = \{\omega \colon \mathbf{z}(\omega) \in B\} \in \mathcal{F};$$

i.e., \boldsymbol{z} is a $\mathcal{F}/\mathcal{B}^d\text{-measurable}$ function.

Borel Measurable

- All the inverse images of random vector z, z⁻¹(B), form a σ-algebra, denoted as σ(z).
 - It is known as the σ-algebra generated by z, or the information set associated with z.
 - It is the smallest σ -algebra in $\mathcal F$ such that $\mathbf z$ is measurable.
- A function $g: \mathbb{R} \mapsto \mathbb{R}$ is \mathcal{B} -measurable or Borel measurable if

 $\{\zeta \in \mathbb{R} : g(\zeta) \leq b\} \in \mathcal{B}.$

For random variable z defined on (Ω, F, ℙ) and Borel measurable function g(·), g(z) is a random variable defined on (Ω, F, ℙ). The same conclusion holds for d-dimensional random vector z and B^d-measurable function g(·).

The joint distribution function of z is a non-decreasing,
 right-continuous function F_z such that for ζ = (ζ₁,...,ζ_d)' ∈ ℝ^d,

$$F_{\mathbf{z}}(\zeta) = \mathbb{P}\{\omega \in \Omega \colon z_1(\omega) \le \zeta_1, \ldots, z_d(\omega) \le \zeta_d\},\$$

with

$$\lim_{\zeta_1 \to -\infty, \dots, \zeta_d \to -\infty} F_{\mathbf{z}}(\zeta) = 0, \qquad \lim_{\zeta_1 \to \infty, \dots, \zeta_d \to \infty} F_{\mathbf{z}}(\zeta) = 1.$$

• The marginal distribution function of the *i*th component of **z** is

$$F_{z_i}(\zeta_i) = \mathbb{P}\{\omega \in \Omega \colon z_i(\omega) \le \zeta_i\} = F_{z}(\infty, \dots, \infty, \zeta_i, \infty, \dots, \infty).$$

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• y and z are (pairwise) independent iff for any Borel sets B_1 and B_2 ,

$$\mathbb{P}(y \in B_1 \text{ and } z \in B_2) = \mathbb{P}(y \in B_1) \mathbb{P}(z \in B_2).$$

• A sequence of random variables $\{z_i\}$ is totally independent if

$$\mathbb{P}\left(\bigcap_{\text{all }i} \{z_i \in B_i\}\right) = \prod_{\text{all }i} \mathbb{P}(z_i \in B_i).$$

Lemma 5.1

Let $\{z_i\}$ be a sequence of independent random variables and h_i , i = 1, 2, ... be Borel-measurable functions. Then $\{h_i(z_i)\}$ is also a sequence of independent random variables.

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• The expectation of Z_i is the Lebesgue integral of z_i wrt to IP:

$$\mathbb{E}(z_i) = \int_{\Omega} z_i(\omega) \, \mathrm{d} \, \mathbb{P}(\omega).$$

In terms of its distribution function,

$$\mathbb{E}(z_i) = \int_{\mathbb{R}^d} \zeta_i \, \mathrm{d} F_{\mathsf{z}}(\zeta) = \int_{\mathbb{R}} \zeta_i \, \mathrm{d} F_{z_i}(\zeta_i).$$

• For Borel measurable function $g(\cdot)$ of \mathbf{z} ,

$$\mathbb{E}[g(\mathbf{z})] = \int_{\Omega} g(\mathbf{z}(\omega)) \, \mathrm{d} \, \mathbb{IP}(\omega) = \int_{\mathbb{R}^d} g(\zeta) \, \mathrm{d} \, F_{\mathbf{z}}(\zeta).$$

For example, the covariance matrix of $z \Vdash (zz')$.

A function g is convex on a set S if for any $a \in [0,1]$ and any x, y in S,

$$g\left(ax+(1-a)y\right)\leq ag(x)+(1-a)g(y);$$

g is concave on S if the inequality above is reversed.

Lemma 5.2 (Jensen)

Let g be a convex function on the support of z. For an integrable random variable z such that g(z) is integrable, $g(\mathbb{E}(z)) \leq \mathbb{E}[g(z)]$; the inequality reverses if g is concave.



- For random variable z with finite pth moment, its L_p -norm is: $||z||_p = [\mathbb{E}(z^p)]^{1/p}$.
- The inner product of square integrable random variables z_i and z_j is:

$$\langle z_i, z_j \rangle = \mathbb{E}(z_i z_j).$$

The L_2 -norm of z_i can be obtained as $||z_i||_2 = \langle z_i, z_i \rangle^{1/2}$.

• For any c > 0 and p > 0, note that

$$c^p \, \mathbb{P}(|z| \ge c) = c^p \int \mathbf{1}_{\{\zeta:|\zeta| \ge c\}} dF_z(\zeta) \le \int_{\{\zeta:|\zeta| \ge c\}} |\zeta|^p dF_z(\zeta) \le \mathbb{E} \, |z|^p,$$

where $\mathbf{1}_A$ is the indicator function of the event A.

Lemma 5.3 (Markov)

Let z be a random variable with finite p^{th} moment. Then,

$$\mathbb{P}(|z| \ge c) \le \frac{\mathbb{E} |z|^{\rho}}{c^{\rho}},$$

where c is a positive real number.

- For *p* = 2, Markov's inequality is also known as Chebyshev's inequality.
- Markov's inequality is trivial if c is small such that IE |z|^p/c^p > 1.
 When c becomes large, the probability that z assumes very extreme values will be vanishing at the rate c^{-p}.

Lemma 5.4 (Hölder)

Let y be a random variable with finite p^{th} moment (p > 1) and z a random variable with finite q^{th} moment (q = p/(p - 1)). Then,

 $\mathbb{E}|yz| \leq \|y\|_p \|z\|_q.$

Since $|\mathbb{E}(yz)| \leq \mathbb{E}|yz|$, we also have:

Lemma 5.5 (Cauchy-Schwatz)

Let y and z be two square integrable random variables. Then,

 $|\mathbb{E}(yz)| \le ||y||_2 ||z||_2.$

Let y = 1 and $x = z^p$. For q > p and r = q/p, by Hölder's inequality,

$$\mathbb{E} |z^{p}| \leq \|x\|_{r} \|y\|_{r/(r-1)} = [\mathbb{E}(z^{pr})]^{1/r} = [\mathbb{E}(z^{q})]^{p/q}.$$

Lemma 5.6 (Liapunov)

Let z be a random variable with finite q^{th} moment. Then for p < q, $\|z\|_p \le \|z\|_q$.

Lemma 5.7 (Minkowski)

Let z_i , i = 1, ..., n, be random variables with finite p th moment $(p \ge 1)$. Then, $\|\sum_{i=1}^n z_i\|_p \le \sum_{i=1}^n \|z_i\|_p$.

When n = 2, this is just the triangle inequality for L_p -norms.

- Given A, B ∈ F, suppose we know B has occurred. Given the outcome space is restricted to B, the likelihood of A is characterized by the conditional probability: IP(A | B) = IP(A ∩ B) / IP(B).
- The conditional density function of ${\bf z}$ given ${\bf y}=\eta$ is

$$f_{\mathbf{z}|\mathbf{y}}(\zeta \mid \mathbf{y} = \eta) = rac{f_{\mathbf{z},\mathbf{y}}(\zeta,\eta)}{f_{\mathbf{y}}(\eta)}$$

• $f_{\mathbf{z}|\mathbf{y}}(\zeta \mid \mathbf{y} = \eta)$ is clearly non-negative. Also

$$\int_{\mathbb{R}^d} f_{\mathsf{z}|\mathsf{y}}(\zeta \mid \mathsf{y} = \eta) d\zeta = \frac{1}{f_{\mathsf{y}}(\eta)} \int_{\mathbb{R}^d} f_{\mathsf{z},\mathsf{y}}(\zeta,\eta) d\zeta = \frac{1}{f_{\mathsf{y}}(\eta)} f_{\mathsf{y}}(\eta) = 1.$$

That is, $f_{\mathbf{z}|\mathbf{y}}(\zeta \mid \mathbf{y} = \eta)$ is a legitimate density function.

• Given the conditional density function $f_{z|v}$, for $A \in \mathcal{B}^d$,

$$\mathbb{P}(\mathbf{z} \in A \mid \mathbf{y} = \eta) = \int_{A} f_{\mathbf{z}|\mathbf{y}}(\zeta \mid \mathbf{y} = \eta) d\zeta.$$

This probability is defined even when $\mathbb{P}(\mathbf{y} = \eta)$ is zero.

When A = (-∞, ζ₁] × ··· × (-∞, ζ_d], the conditional distribution function is

$$F_{\mathbf{z}|\mathbf{y}}(\zeta \mid \mathbf{y} = \eta) = \mathbb{IP}(z_1 \leq \zeta_1, \dots, z_d \leq \zeta_d \mid \mathbf{y} = \eta).$$

• When **z** and **y** are independent, the conditional density (distribution) reduces to the unconditional density (distribution).

Let G be a sub-σ-algebra of F, the conditional expectation E(z | G) is the integrable and G-measurable random variable satisfying

$$\int_{\mathcal{G}} \mathbb{I\!E}(\mathbf{z} \mid \mathcal{G}) \, \mathrm{d} \, \mathbb{I\!P} = \int_{\mathcal{G}} \mathbf{z} \, \mathrm{d} \, \mathbb{I\!P}, \quad \forall \mathcal{G} \in \mathcal{G}.$$

• Suppose that \mathcal{G} is the trivial σ -algebra $\{\Omega, \emptyset\}$, then $\mathsf{IE}(\mathbf{z} \mid \mathcal{G})$ must be a constant c, so that

$$\mathbb{E}(\mathbf{z}) = \int_{\Omega} \mathbf{z} \, \mathrm{d} \, \mathbb{P} = \int_{\Omega} \mathbf{c} \, \mathrm{d} \, \mathbb{P} = \mathbf{c}.$$

• Consider $\mathcal{G} = \sigma(\mathbf{y})$, the σ -algebra generated by \mathbf{y} .

$$\mathbb{E}(\mathbf{z} \mid \mathbf{y}) = \mathbb{E}[\mathbf{z} \mid \sigma(\mathbf{y})],$$

which is interpreted as the prediction of \boldsymbol{z} given all the information associated with $\boldsymbol{y}.$

By definition,

$$\mathbb{E}[\mathbb{E}(\mathsf{z} \mid \mathcal{G})] = \int_{\Omega} \mathbb{E}(\mathsf{z} \mid \mathcal{G}) \, \mathsf{d} \, \mathbb{P} = \int_{\Omega} \mathsf{z} \, \mathsf{d} \, \mathbb{P} = \mathbb{E}(\mathsf{z});$$

That is, only a smaller σ -algebra matters in conditional expectation.

Lemma 5.9 (Law of Iterated Expectations)

Let \mathcal{G} and \mathcal{H} be two sub- σ -algebras of \mathcal{F} such that $\mathcal{G} \subseteq \mathcal{H}$. Then for the integrable random vector \mathbf{z} ,

 $\mathbb{E}[\mathbb{E}(\mathsf{z} \mid \mathcal{H}) \mid \mathcal{G}] = \mathbb{E}[\mathbb{E}(\mathsf{z} \mid \mathcal{G}) \mid \mathcal{H}] = \mathbb{E}(\mathsf{z} \mid \mathcal{G}).$

• If z is \mathcal{G} -measurable, then $\mathbb{E}[g(z)x \mid \mathcal{G}] = g(z)\mathbb{E}(x \mid \mathcal{G})$ with prob. 1.

Lemma 5.11

Let z be a square integrable random variable. Then

$$\mathbb{E}[z - \mathbb{E}(z \mid \mathcal{G})]^2 \leq \mathbb{E}(z - \tilde{z})^2,$$

for any \mathcal{G} -measurable random variable \tilde{z} .

Proof: For any square integrable, G-measurable random variable \tilde{z} ,

$$\mathbb{E}\big([z - \mathbb{E}(z \mid \mathcal{G})]\tilde{z}\big) = \mathbb{E}\big([\mathbb{E}(z \mid \mathcal{G}) - \mathbb{E}(z \mid \mathcal{G})]\tilde{z}\big) = 0.$$

It follows that

$$\begin{split} \mathsf{E}(z - \tilde{z})^2 &= \mathsf{I\!E}[z - \mathsf{I\!E}(z \mid \mathcal{G}) + \mathsf{I\!E}(z \mid \mathcal{G}) - \tilde{z}]^2 \\ &= \mathsf{I\!E}[z - \mathsf{I\!E}(z \mid \mathcal{G})]^2 + \mathsf{I\!E}[\mathsf{I\!E}(z \mid \mathcal{G}) - \tilde{z}]^2 \\ &\geq \mathsf{I\!E}[z - \mathsf{I\!E}(z \mid \mathcal{G})]^2. \quad \Box \end{split}$$

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• The conditional variance-covariance matrix of z given y is

$$\begin{aligned} \mathsf{var}(\mathsf{z} \mid \mathsf{y}) &= \mathsf{I\!E}\big([\mathsf{z} - \mathsf{I\!E}(\mathsf{z} \mid \mathsf{y})][\mathsf{z} - \mathsf{I\!E}(\mathsf{z} \mid \mathsf{y})]' \mid \mathsf{y}\big) \\ &= \mathsf{I\!E}(\mathsf{z}\mathsf{z}' \mid \mathsf{y}) - \mathsf{I\!E}(\mathsf{z} \mid \mathsf{y}) \,\mathsf{I\!E}(\mathsf{z} \mid \mathsf{y})', \end{aligned}$$

which leads to decomposition of analysis of variance:

$$var(z) = \mathbb{E}[var(z \mid y)] + var(\mathbb{E}(z \mid y)).$$

• Example 5.12: Suppose that

$$\left[\begin{array}{c} \mathbf{y} \\ \mathbf{x} \end{array} \right] \sim \mathcal{N} \left(\left[\begin{array}{c} \boldsymbol{\mu}_{\mathbf{y}} \\ \boldsymbol{\mu}_{\mathbf{x}} \end{array} \right], \\ \left[\begin{array}{c} \boldsymbol{\Sigma}_{\mathbf{y}\mathbf{y}} & \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{y}}' \\ \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{y}} & \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{x}} \end{array} \right] \right)$$

Then,

$$\begin{split} & \mathbb{E}(\mathbf{y} \mid \mathbf{x}) = \boldsymbol{\mu}_{\mathbf{y}} - \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{y}}' \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{x}}^{-1} (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}}), \\ & \mathsf{var}(\mathbf{y} \mid \mathbf{x}) = \mathsf{var}(\mathbf{y}) - \mathsf{var} \big(\mathbb{E}(\mathbf{y} \mid \mathbf{x}) \big) = \boldsymbol{\Sigma}_{\mathbf{y}\mathbf{y}} - \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{y}}' \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{x}}^{-1} \boldsymbol{\Sigma}_{\mathbf{x}\mathbf{y}}. \end{split}$$

A sequence of random variables, $\{z_n(\cdot)\}_{n=1,2,...}$, is such that for a given ω , $z_n(\omega)$ is a realization of the random element ω with index n, and that for a given n, $z_n(\cdot)$ is a random variable.

Almost Sure Convergence

Suppose $\{z_n\}$ and z are all defined on $(\Omega, \mathcal{F}, \mathbb{IP})$. $\{z_n\}$ is said to converge to z almost surely if, and only if,

$$\mathsf{P}(\omega: z_n(\omega) \to z(\omega) \text{ as } n \to \infty) = 1,$$

denoted as $z_n \xrightarrow{\text{a.s.}} z$ or $z_n \to z$ a.s. (with prob. 1).

Lemma 5.13

Let $g : \mathbb{R} \mapsto \mathbb{R}$ be a function continuous on $S_g \subseteq \mathbb{R}$. If $z_n \xrightarrow{a.s.} z$, where z is a random variable such that $\mathbb{P}(z \in S_g) = 1$, then $g(z_n) \xrightarrow{a.s.} g(z)$.

Proof: Let $\Omega_0 = \{\omega : z_n(\omega) \to z(\omega)\}$ and $\Omega_1 = \{\omega : z(\omega) \in S_g\}$. Thus, for $\omega \in (\Omega_0 \cap \Omega_1)$, continuity of g ensures that $g(z_n(\omega)) \to g(z(\omega))$. Note that

 $(\Omega_0 \cap \Omega_1)^c = \Omega_0^c \cup \Omega_1^c,$

which has probability zero because $\mathbb{P}(\Omega_0^c) = \mathbb{P}(\Omega_1^c) = 0$. (Why?) It follows that $\Omega_0 \cap \Omega_1$ has probability one, showing that $g(z_n) \to g(z)$ with probability one. \Box

Convergence in Probability

 $\{z_n\}$ is said to converge to z in probability if for every $\epsilon > 0$,

$$\lim_{n\to\infty} \mathbb{P}(\omega \colon |z_n(\omega) - z(\omega)| > \epsilon) = 0,$$

or equivalently, $\lim_{n\to\infty} \mathbb{P}(\omega : |z_n(\omega) - z(\omega)| \le \epsilon) = 1$. This is denoted as $z_n \xrightarrow{\mathbb{P}} z$ or $z_n \to z$ in probability.

Note: In this definition, the events $\Omega_n(\epsilon) = \{\omega : |z_n(\omega) - z(\omega)| \le \epsilon\}$ may vary with *n*, and convergence is referred to the probability of such events: $p_n = \mathbb{P}(\Omega_n(\epsilon))$, rather than the random variables z_n .

Almost sure convergence implies convergence in probability.

To see this, let Ω_0 denote the set of ω such that $z_n(\omega) \to z(\omega)$. For $\omega \in \Omega_0$, there is some *m* such that ω is in $\Omega_n(\epsilon)$ for all n > m. That is,

$$\Omega_0 \subseteq \bigcup_{m=1}^{\infty} \bigcap_{n=m}^{\infty} \Omega_n(\epsilon) \in \mathcal{F}.$$

As $\bigcap_{n=m}^{\infty} \Omega_n(\epsilon)$ is non-decreasing in *m*, it follows that

$$\begin{split} \mathbb{P}(\Omega_0) &\leq \mathbb{P}\left(\bigcup_{m=1}^{\infty} \bigcap_{n=m}^{\infty} \Omega_n(\epsilon)\right) \\ &= \lim_{m \to \infty} \mathbb{P}\left(\bigcap_{n=m}^{\infty} \Omega_n(\epsilon)\right) \leq \lim_{m \to \infty} \mathbb{P}(\Omega_m(\epsilon)). \end{split}$$

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• Example 5.15

Let $\Omega = [0, 1]$ and \mathbb{P} be the Lebesgue measure. Consider the sequence of intervals $\{I_n\}$ in [0, 1]: [0, 1/2), [1/2, 1], [0, 1/3), [1/3, 2/3), [2/3, 1], ..., and let $z_n = \mathbf{1}_{I_n}$. When *n* tends to infinity, I_n shrinks toward a singleton. For $0 < \epsilon < 1$, we have

 $\mathbb{P}(|z_n| > \epsilon) = \mathbb{P}(I_n) \to 0,$

which shows $z_n \xrightarrow{\mathbf{P}} 0$. On the other hand, each $\omega \in [0, 1]$ must be covered by infinitely many intervals, so that $z_n(\omega) = 1$ for infinitely many *n*. This shows that $z_n(\omega)$ does not converge to zero. \Box **Note:** Convergence in probability permits z_n to deviate from the probability limit infinitely often, but almost sure convergence does not, except for those ω in the set of probability zero.

Lemma 5.16

Let $\{z_n\}$ be a sequence of square integrable random variables. If $\mathbb{E}(z_n) \to c$ and $\operatorname{var}(z_n) \to 0$, then $z_n \xrightarrow{\mathbb{P}} c$.

Lemma 5.17

Let $g : \mathbb{R} \mapsto \mathbb{R}$ be a function continuous on $S_g \subseteq \mathbb{R}$. If $z_n \xrightarrow{\mathbb{P}} z$, where z is a random variable such that $\mathbb{P}(z \in S_g) = 1$, then $g(z_n) \xrightarrow{\mathbb{P}} g(z)$.

Proof: By the continuity of g, for each $\epsilon > 0$, we can find a $\delta > 0$ s.t.

$$\begin{aligned} \{\omega: |z_n(\omega) - z(\omega)| &\leq \delta\} \cap \{\omega: z(\omega) \in S_g\} \\ &\subseteq \{\omega: |g(z_n(\omega)) - g(z(\omega))| \leq \epsilon\}. \end{aligned}$$

Taking complementation of both sides, we have

$$\mathbb{P}(|g(z_n)-g(z)| > \epsilon) \le \mathbb{P}(|z_n-z| > \delta) \to 0.$$

Lemma 5.13 and Lemma 5.17 are readily generalized to \mathbb{R}^d -valued random variables. For instance, $\mathbf{z}_n \xrightarrow{\mathbf{a.s.}} \mathbf{z} \ (\mathbf{z}_n \xrightarrow{\mathbf{P}} \mathbf{z})$ implies

$$\begin{split} z_{1,n} + z_{2,n} & \xrightarrow{\text{a.s.}} \left(\stackrel{\mathbb{P}}{\longrightarrow} \right) z_1 + z_2, \\ z_{1,n} z_{2,n} & \xrightarrow{\text{a.s.}} \left(\stackrel{\mathbb{P}}{\longrightarrow} \right) z_1 z_2, \\ z_{1,n}^2 + z_{2,n}^2 & \xrightarrow{\text{a.s.}} \left(\stackrel{\mathbb{P}}{\longrightarrow} \right) z_1^2 + z_2^2, \end{split}$$

where $z_{1,n}, z_{2,n}$ are two elements of \mathbf{z}_n and z_1, z_2 are the corresponding elements of \mathbf{z} . Also, provided that $z_2 \neq 0$ with probability one,

$$z_{1,n}/z_{2,n} \xrightarrow{\text{a.s.}} (\stackrel{\mathbb{P}}{\longrightarrow}) z_1/z_2.$$

Convergence in Distribution

 $\{z_n\}$ is said to converge to z in distribution, denoted as $z_n \xrightarrow{D} z$, if

 $\lim_{n\to\infty}F_{z_n}(\zeta)=F_z(\zeta),$

for every continuity point ζ of F_z .

- We also say that z_n is asymptotically distributed as F_z , denoted as $z_n \stackrel{A}{\sim} F_z$; F_z is thus known as the limiting distribution of z_n .
- Cramér-Wold Device. Let $\{\mathbf{z}_n\}$ be a sequence of random vectors in \mathbb{R}^d . Then $\mathbf{z}_n \xrightarrow{D} \mathbf{z}$ if and only if $\alpha' \mathbf{z}_n \xrightarrow{D} \alpha' \mathbf{z}$ for every $\alpha \in \mathbb{R}^d$ such that $\alpha' \alpha = 1$.

Lemma 5.19

If
$$z_n \xrightarrow{\mathbb{P}} z$$
, then $z_n \xrightarrow{D} z$. For a constant $c, z_n \xrightarrow{\mathbb{P}} c$ iff $z_n \xrightarrow{D} c$.

Proof: For some arbitrary $\epsilon > 0$ and a continuity point ζ of F_z , we have

$$\mathbb{P}(z_n \leq \zeta) = \\\mathbb{P}(\{z_n \leq \zeta\} \cap \{|z_n - z| \leq \epsilon\}) + \mathbb{P}(\{z_n \leq \zeta\} \cap \{|z_n - z| > \epsilon\}) \\ \leq \mathbb{P}(z \leq \zeta + \epsilon) + \mathbb{P}(|z_n - z| > \epsilon).$$

Similarly, $\mathbb{P}(z \leq \zeta - \epsilon) \leq \mathbb{P}(z_n \leq \zeta) + \mathbb{P}(|z_n - z| > \epsilon)$. If $z_n \xrightarrow{\mathbb{P}} z$, then by passing to the limit and noting that ϵ is arbitrary,

$$\lim_{n\to\infty} \mathbb{P}(z_n \leq \zeta) = \mathbb{P}(z \leq \zeta).$$

That is, $F_{z_n}(\zeta) \to F_z(\zeta)$. The converse is not true in general, however.

Theorem 5.20 (Continuous Mapping Theorem)

Let $g : \mathbb{R} \mapsto \mathbb{R}$ be a function continuous almost everywhere on \mathbb{R} , except for at most countably many points. If $z_n \xrightarrow{D} z$, then $g(z_n) \xrightarrow{D} g(z)$.

For example,
$$z_n \xrightarrow{D} \mathcal{N}(0,1)$$
 implies $z_n^2 \xrightarrow{D} \chi^2(1)$.

Theorem 5.21

Let $\{y_n\}$ and $\{z_n\}$ be two sequences of random vectors such that $y_n - z_n \xrightarrow{\mathbb{P}} 0$. If $z_n \xrightarrow{D} z$, then $y_n \xrightarrow{D} z$.

Theorem 5.22

If y_n converges in probability to a constant c and z_n converges in distribution to z, then $y_n + z_n \xrightarrow{D} c + z$, $y_n z_n \xrightarrow{D} cz$, and $z_n/y_n \xrightarrow{D} z/c$ if $c \neq 0$.

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Order notations are used to describe the behavior of real sequences.

- b_n is (at most) of order c_n , denoted as $b_n = O(c_n)$, if there exists a $\Delta < \infty$ such that $|b_n|/c_n \le \Delta$ for all sufficiently large n.
- b_n is of smaller order than c_n , denoted as $b_n = o(c_n)$, if $b_n/c_n \to 0$.
- An O(1) sequence in bounded; an o(1) sequence converges to zero.
 The product of O(1) and o(1) sequences is o(1).

Theorem 5.23

(a) If
$$a_n = O(n^r)$$
 and $b_n = O(n^s)$, then $a_n b_n = O(n^{r+s})$, $a_n + b_n = O(n^{\max(r,s)})$.

(b) If
$$a_n = o(n^r)$$
 and $b_n = o(n^s)$, then $a_n b_n = o(n^{r+s})$, $a_n + b_n = o(n^{\max(r,s)})$.

(c) If $a_n = O(n^r)$ and $b_n = o(n^s)$, then $a_n b_n = o(n^{r+s})$, $a_n + b_n = O(n^{\max(r,s)})$.

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The order notations defined earlier easily extend to describe the behavior of sequences of random variables.

- $\{z_n\}$ is $O_{a.s.}(c_n)$ (or $O(c_n)$ almost surely) if z_n/c_n is O(1) a.s.
- $\{z_n\}$ is $O_{\mathbb{P}}(c_n)$ (or $O(c_n)$ in probability) if for every $\epsilon > 0$, there is some Δ such that $\mathbb{P}(|z_n|/c_n \ge \Delta) \le \epsilon$, for all *n* sufficiently large.
- Lemma 5.23 holds for stochastic order notations. For example, $y_n = O_{\mathbb{P}}(1)$ and $z_n = o_{\mathbb{P}}(1)$, then $y_n z_n$ is $o_{\mathbb{P}}(1)$.
- It is very restrictive to require a random variable being bounded almost surely, but a well defined random variable is typically bounded in probability, i.e., $O_{\mathbb{P}}(1)$.

Let $\{z_n\}$ be a sequence of random variables such that $z_n \xrightarrow{D} z$ and ζ be a continuity point of F_z . Then for any $\epsilon > 0$, we can choose a sufficiently large ζ such that $\mathbb{P}(|z| > \zeta) < \epsilon/2$. As $z_n \xrightarrow{D} z$, we can also choose *n* large enough such that

 $\mathbb{P}(|z_n| > \zeta) - \mathbb{P}(|z| > \zeta) < \epsilon/2,$

which implies $\mathbb{P}(|z_n| > \zeta) < \epsilon$. We have proved:

Lemma 5.24

Let $\{z_n\}$ be a sequence of random variables such that $z_n \xrightarrow{D} z$. Then $z_n = O_{\mathbb{P}}(1)$.

- When a law of large numbers holds almost surely, it is a strong law of large numbers (SLLN); when a law of large numbers holds in probability, it is a weak law of large numbers (WLLN).
- A sequence of random variables obeys a LLN when its sample average essentially follows its mean behavior; random irregularities (deviations from the mean) are "wiped out" in the limit by averaging.
- Kolmogorov's SLLN : Let $\{z_t\}$ be a sequence of *i.i.d.* random variables with mean μ_o . Then, $T^{-1} \sum_{t=1}^{T} z_t \xrightarrow{\text{a.s.}} \mu_o$.
- Note that i.i.d. random variables need not obey Kolmogorov's SLLN if they do not have a finite mean, e.g., i.i.d. Cauchy random variables.

Theorem 5.26 (Markov's SLLN)

Let $\{z_t\}$ be a sequence of independent random variables such that for some $\delta > 0$, $\mathbb{E} |z_t|^{1+\delta}$ is bounded for all t. Then,

$$\frac{1}{T}\sum_{t=1}^{T} [z_t - \mathbb{E}(z_t)] \xrightarrow{\text{a.s.}} 0.$$

- Note that here z_t need not have a common mean, and the average of their means need not converge.
- Compared with Kolmogorov's SLLN, Markov's SLLN requires a stronger moment condition but not identical distribution.
- A LLN usually obtains by regulating the moments of and dependence across random variables.

Examples

Example 5.27 Suppose that $y_t = \alpha_o y_{t-1} + u_t$ with $|\alpha_o| < 1$. Then, $\operatorname{var}(y_t) = \sigma_u^2/(1 - \alpha_o^2)$, and $\operatorname{cov}(y_t, y_{t-j}) = \alpha_o^j \frac{\sigma_u^2}{1 - \alpha_o^2}$. Thus,

$$\operatorname{var}\left(\sum_{t=1}^{T} y_{t}\right) = \sum_{t=1}^{T} \operatorname{var}(y_{t}) + 2\sum_{\tau=1}^{T-1} (T-\tau) \operatorname{cov}(y_{t}, y_{t-\tau})$$
$$\leq \sum_{t=1}^{T} \operatorname{var}(y_{t}) + 2T \sum_{\tau=1}^{T-1} |\operatorname{cov}(y_{t}, y_{t-\tau})| = O(T),$$

so that var $(T^{-1}\sum_{t=1}^{T} y_t) = O(T^{-1})$. As $\mathbb{IE}(T^{-1}\sum_{t=1}^{T} y_t) = 0$,

$$\frac{1}{T}\sum_{t=1}^{T}y_t \stackrel{\mathbb{P}}{\longrightarrow} 0.$$

by Lemma 5.16. That is, $\{y_t\}$ obeys a WLLN.

Lemma 5.28

Let $y_t = \sum_{i=0}^{\infty} \pi_i u_{t-i}$, where u_t are i.i.d. random variables with mean zero and variance σ_u^2 . If $\sum_{i=-\infty}^{\infty} |\pi_i| < \infty$, then $T^{-1} \sum_{t=1}^{T} y_t \xrightarrow{\text{a.s.}} 0$.

- In Example 5.27, $y_t = \sum_{i=0}^{\infty} \alpha_o^i u_{t-i}$ with $|\alpha_o| < 1$, so that $\sum_{i=0}^{\infty} |\alpha_o^i| < \infty$
- Lemma 5.28 is quite general and applicable to processes that can be expressed as an MA process with absolutely summable weights, e.g., weakly stationary AR(p) processes.
- For random variables with strong correlations over time, the variation of their partial sums may grow too rapidly and cannot be eliminated by simple averaging.

Example 5.29: For the sequences $\{t\}$ and $\{t^2\}$,

$$\sum_{t=1}^{T} t = T(T+1)/2, \quad \sum_{t=1}^{T} t^2 = T(T+1)(2T+1)/6.$$

Hence, $T^{-1} \sum_{t=1}^{T} t$ and $T^{-1} \sum_{t=1}^{T} t^2$ both diverge.

Example 5.30: u_t are i.i.d. with mean zero and variance σ_u^2 . Consider now $\{tu_t\}$, which does not have bounded $(1 + \delta)$ th moment and does not obey Markov's SLLN. Moreover,

$$\operatorname{var}\left(\sum_{t=1}^{T} t u_{t}\right) = \sum_{t=1}^{T} t^{2} \operatorname{var}(u_{t}) = \sigma_{u}^{2} \frac{T(T+1)(2T+1)}{6},$$

so that $\sum_{t=1}^{T} tu_t = O_{\mathbb{P}}(T^{3/2})$. It follows that $T^{-1} \sum_{t=1}^{T} tu_t = O_{\mathbb{P}}(T^{1/2})$. That is, $\{tu_t\}$ does not obey a WLLN. **Example 5.31**: y_t is a random walk: $y_t = y_{t-1} + u_t$. For s < t,

$$y_t = y_s + \sum_{i=s+1}^t u_i = y_s + v_{t-s},$$

where v_{t-s} is independent of y_s and $cov(y_t, y_s) = \mathbb{E}(y_s^2) = s\sigma_u^2$. Thus,

$$\operatorname{var}\left(\sum_{t=1}^{T} y_{t}\right) = \sum_{t=1}^{T} \operatorname{var}(y_{t}) + 2\sum_{\tau=1}^{T-1} \sum_{t=\tau+1}^{T} \operatorname{cov}(y_{t}, y_{t-\tau}) = O(T^{3}),$$

for $\sum_{t=1}^{T} \operatorname{var}(y_t) = \sum_{t=1}^{T} t\sigma_u^2 = O(T^2)$ and

$$2\sum_{\tau=1}^{T-1}\sum_{t=\tau+1}^{T}\operatorname{cov}(y_t, y_{t-\tau}) = 2\sum_{\tau=1}^{T-1}\sum_{t=\tau+1}^{T}(t-\tau)\sigma_u^2 = O(T^3).$$

Then, $\sum_{t=1}^{T} y_t = O_P(T^{3/2})$ and $T^{-1} \sum_{t=1}^{T} y_t$ diverges in probability.

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Example 5.32: y_t is the random walk in Example 5.31. Then, $\mathbb{E}(y_{t-1}u_t) = 0$, $\operatorname{var}(y_{t-1}u_t) = \mathbb{E}(y_{t-1}^2) \mathbb{E}(u_t^2) = (t-1)\sigma_u^4$, and for s < t,

$$cov(y_{t-1}u_t, y_{s-1}u_s) = \mathbb{E}(y_{t-1}y_{s-1}u_s) \mathbb{E}(u_t) = 0.$$

This yields

$$\operatorname{var}\left(\sum_{t=1}^{T} y_{t-1} u_t\right) = \sum_{t=1}^{T} \operatorname{var}(y_{t-1} u_t) = \sum_{t=1}^{T} (t-1) \sigma_u^4 = O(T^2),$$

and $\sum_{t=1}^{T} y_{t-1} u_t = O_{\mathbf{P}}(T)$. As $\operatorname{var}(T^{-1} \sum_{t=1}^{T} y_{t-1} u_t)$ converges to $\sigma_u^4/2$, rather than 0, $\{y_{t-1} u_t\}$ does not obey a WLLN, even though its partial sums are $O_{\mathbf{P}}(T)$.

Lemma 5.35 (Lindeberg-Lévy's CLT)

Let $\{z_t\}$ be a sequence of i.i.d. random variables with mean μ_o and variance $\sigma_o^2 > 0$. Then, $\sqrt{T}(\bar{z}_T - \mu_o)/\sigma_o \xrightarrow{D} \mathcal{N}(0, 1)$.

- i.i.d. random variables need not obey this CLT if they do not have a finite variance, e.g., t(2) r.v.
- Note that \bar{z}_T converges to μ_o in probability, and its variance σ_o^2/T vanishes when T tends to infinity. A normalizing factor $T^{1/2}$ suffices to prevent a degenerate distribution in the limit.
- When $\{z_t\}$ obeys a CLT, \bar{z}_T is said to converge to μ_o at the rate $T^{-1/2}$, and \bar{z}_T is understood as a root-T consistent estimator.

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Lemma 5.36 (Liapunov's CLT)

Let $\{z_{Tt}\}$ be a triangular array of independent random variables with mean μ_{Tt} and variance $\sigma_{Tt}^2 > 0$ such that $\bar{\sigma}_T^2 = \frac{1}{T} \sum_{t=1}^T \sigma_{Tt}^2 \rightarrow \sigma_o^2 > 0$. If for some $\delta > 0$, $\mathbb{E} |z_{Tt}|^{2+\delta}$ are bounded, then $\sqrt{T}(\bar{z}_T - \bar{\mu}_T)/\sigma_o \xrightarrow{D} \mathcal{N}(0, 1)$.

- A CLT usually requires stronger conditions on the moment of and dependence across random variables than those needed to ensure a LLN.
- Moreover, every random variable must also be asymptotically negligible, in the sense that no random variable is influential in affecting the partial sums.

Examples

Example 5.37: $\{u_t\}$ is a sequence of independent random variables with mean zero, variance σ_u^2 , and bounded $(2 + \delta)$ th moment. we know $\operatorname{var}(\sum_{t=1}^{T} tu_t)$ is $O(T^3)$, which implies that variance of $T^{-1/2} \sum_{t=1}^{T} tu_t$ is diverging at the rate $O(T^2)$. On the other hand, observe that

$$\operatorname{var}\left(\frac{1}{T^{1/2}}\sum_{t=1}^{T}\frac{t}{T}u_{t}\right) = \frac{T(T+1)(2T+1)}{6T^{3}}\sigma_{u}^{2} \to \frac{\sigma_{u}^{2}}{3}.$$

It follows that

$$\frac{\sqrt{3}}{T^{1/2}\sigma_u}\sum_{t=1}^T\frac{t}{T}u_t\stackrel{D}{\longrightarrow}\mathcal{N}(0,1).$$

These results show that $\{(t/T)u_t\}$ obeys a CLT, whereas $\{tu_t\}$ does not.

Example 5.38: y_t is a random walk: $y_t = y_{t-1} + u_t$, where u_t are i.i.d. with mean zero and variance σ_u^2 . We know y_t do not obey a LLN and hence do not obey a CLT.

CLT for Triangular Array

 $\{z_{\mathit{Tt}}\}$ is a triangular array of random variables and obeys a CLT if

$$\frac{1}{\sigma_o \sqrt{T}} \sum_{t=1}^{T} [z_{Tt} - \mathbb{IE}(z_{Tt})] = \frac{\sqrt{T}(\bar{z}_T - \bar{\mu}_T)}{\sigma_o} \xrightarrow{D} \mathcal{N}(0, 1),$$

where $\bar{z}_T = T^{-1} \sum_{t=1}^T z_{Tt}$, $\bar{\mu}_T = \mathbb{IE}(\bar{z}_T)$, and

$$\sigma_T^2 = \operatorname{var}\left(T^{-1/2}\sum_{t=1}^T z_{Tt}\right) \to \sigma_o^2 > 0.$$

• Consider an array of square integrable random vectors \mathbf{z}_{Tt} in \mathbb{R}^d . Let $\bar{\mathbf{z}}_T$ denote the average of \mathbf{z}_{Tt} , $\bar{\boldsymbol{\mu}}_T = \mathbb{IE}(\bar{\mathbf{z}}_T)$, and

$$\boldsymbol{\Sigma}_{T} = \operatorname{var}\left(\frac{1}{\sqrt{T}}\sum_{t=1}^{T} \boldsymbol{z}_{Tt}\right) \rightarrow \boldsymbol{\Sigma}_{o},$$

a positive definite matrix. Using the Cramér-Wold device, $\{z_{Tt}\}$ is said to obey a multivariate CLT, in the sense that

$$\boldsymbol{\Sigma}_{o}^{-1/2} \frac{1}{\sqrt{T}} \sum_{t=1}^{T} [\boldsymbol{z}_{Tt} - \mathbb{E}(\boldsymbol{z}_{Tt})] = \boldsymbol{\Sigma}_{o}^{-1/2} \sqrt{T} (\bar{\boldsymbol{z}}_{T} - \bar{\boldsymbol{\mu}}_{T}) \stackrel{D}{\longrightarrow} \mathcal{N}(\boldsymbol{0}, \boldsymbol{I}_{d}),$$

if $\{\alpha' \mathbf{z}_{\mathcal{T}t}\}$ obeys a CLT, for any $\alpha \in \mathbb{R}^d$ such that $\alpha' \alpha = 1$.

A d-dimensional stochastic process with the index set *T* is a measurable mapping z: Ω → (ℝ^d)^T such that

$$\mathbf{z}(\omega) = \{\mathbf{z}_t(\omega), t \in \mathcal{T}\}.$$

For each $t \in \mathcal{T}$, $\mathbf{z}_t(\cdot)$ is a \mathbb{R}^d -valued r.v.; for each ω , $\mathbf{z}(\omega)$ is a sample path (realization) of \mathbf{z} , a \mathbb{R}^d -valued function on \mathcal{T} .

• The finite-dimensional distributions of $\{\mathbf{z}(t,\cdot), t \in \mathcal{T}\}$ is

$$\mathbb{P}(\mathsf{z}_{t_1} \leq \mathsf{a}_1, \ldots, \mathsf{z}_{t_n} \leq \mathsf{a}_n) = \mathcal{F}_{t_1, \ldots, t_n}(\mathsf{a}_1, \ldots, \mathsf{a}_n).$$

z is stationary if F_{t1},...,tn</sub> are invariant under index displacement.
z is Gaussian if F_{t1},...,tn</sub> are all (multivariate) normal.

The process $\{w(t), t \in [0, \infty)\}$ is the standard Wiener process (standard Brownian motion) if it has continuous sample paths almost surely and satisfies:

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$$\mathbb{P}(w(0) = 0) = 1.$$

$$e For 0 \le t_0 \le t_1 \le \cdots \le t_k,$$

 $\mathbb{P}\big(w(t_i)-w(t_{i-1})\in B_i,\ i\leq k\big)=\prod_{i\leq k}\mathbb{P}\big(w(t_i)-w(t_{i-1})\in B_i\big),$

where B_i are Borel sets.

$$\hbox{ Sor } 0 \leq s < t, \ w(t) - w(s) \sim \mathcal{N}(0, t-s).$$

Note: w here has independent and Gaussian increments.

• $w(t) \sim \mathcal{N}(0, t)$ such that for $r \leq t$,

$$\operatorname{cov}(w(r), w(t)) = \mathbb{E}[w(r)(w(t) - w(r))] + \mathbb{E}[w(r)^2] = r.$$

• The sample paths of *w* are a.s. continuous but highly irregular (nowhere differentiable).

To see this, note $w_c(t) = w(c^2t)/c$ for c > 0 is also a standard Wiener process. (Why?) Then, $w_c(1/c) = w(c)/c$. For a large c such that w(c)/c > 1, $\frac{w_c(1/c)}{1/c} = w(c) > c$. That is, the sample path of w_c has a slope larger than c on a very small interval (0, 1/c).

• The difference quotient:

 $[w(t+h)-w(t)]/h\sim\mathcal{N}(0,\,1/|h|)$

can not converge to a finite limit (as $h \rightarrow 0$) with a positive prob.

The *d*-dimensional, standard Wiener process **w** consists of *d* mutually independent, standard Wiener processes, so that for s < t,

$$\mathbf{w}(t) - \mathbf{w}(s) \sim \mathcal{N}(\mathbf{0}, (t-s)\mathbf{I}_d).$$

Lemma 5.39

Let \mathbf{w} be the *d*-dimensional, standard Wiener process.

$$\mathbf{0} \ \mathbf{w}(t) \sim \mathcal{N}(\mathbf{0}, \ t \mathbf{I}_d).$$

$$ov(\mathbf{w}(r), \mathbf{w}(t)) = \min(r, t) \mathbf{I}_d.$$

The Brownian bridge \mathbf{w}^0 on [0, 1] is $\mathbf{w}^0(t) = \mathbf{w}(t) - t\mathbf{w}(1)$. Clearly, $\mathbb{E}[\mathbf{w}^0(t)] = \mathbf{0}$, and for r < t,

$$\operatorname{cov}(\mathbf{w}^0(r), \, \mathbf{w}^0(t)) = \operatorname{cov}(\mathbf{w}(r) - r\mathbf{w}(1), \, \mathbf{w}(t) - t\mathbf{w}(1)) = r(1-t) \, \mathbf{I}_d.$$

 \mathbb{P}_n converges weakly to \mathbb{P} , denoted as $\mathbb{P}_n \Rightarrow \mathbb{P}$, if for every bounded, continuous real function f on S,

$$\int f(s) \, \mathrm{d} \, \mathbb{P}_n(s) \to \int f(s) \, \mathrm{d} \, \mathbb{P}(s),$$

where $\{\mathbb{P}_n\}$ and \mathbb{P} are probability measures on (S, S).

- When \mathbf{z}_n and \mathbf{z} are all \mathbb{R}^d -valued random variables, $\mathbb{IP}_n \Rightarrow \mathbb{IP}$ reduces to the usual notion of convergence in distribution: $\mathbf{z}_n \xrightarrow{D} \mathbf{z}$.
- When z_n and z are d-dimensional stochastic processes with the distributions induced by IP_n and IP, z_n ^D→ z, also denoted as z_n ⇒ z, implies that all the finite-dimensional distributions of z_n converge to the corresponding distributions of z.

Lemma 5.40 (Continuous Mapping Theorem)

Let $g : \mathbb{R}^d \mapsto \mathbb{R}$ be a function continuous almost everywhere on \mathbb{R}^d , except for at most countably many points. If $\mathbf{z}_n \Rightarrow \mathbf{z}$, then $g(\mathbf{z}_n) \Rightarrow g(\mathbf{z})$.

Proof: Let S and S' be two metric spaces with Borel σ -algebras S and S' and $g: S \mapsto S'$ be a measurable mapping. For \mathbb{P} on (S, S), define \mathbb{P}^* on (S', S') as

$$\mathsf{P}^*(\mathsf{A}') = \mathbb{P}(g^{-1}(\mathsf{A}')), \qquad \mathsf{A}' \in \mathcal{S}'.$$

For every bounded, continuous f on S', $f \circ g$ is also bounded and continuous on S. $\mathbb{P}_n \Rightarrow \mathbb{P}$ now implies that

$$\int f \circ g(s) \, \mathrm{d} \mathbb{P}_n(s) \to \int f \circ g(s) \, \mathrm{d} \mathbb{P}(s),$$

which is equivalent to $\int f(a) d\mathbb{P}_n^*(a) \to \int f(a) d\mathbb{P}^*(a)$, proving $\mathbb{P}_n^* \Rightarrow \mathbb{P}^*$.

Functional Central Limit Theorem (FCLT)

- ζ_i are i.i.d. with mean zero and variance σ^2 . Let $s_n = \zeta_1 + \cdots + \zeta_n$ and $z_n(i/n) = (\sigma \sqrt{n})^{-1} s_i$.
- For $t \in [(i-1)/n, i/n)$, the constant interpolations of $z_n(i/n)$ is

$$z_n(t) = z_n((i-1)/n) = \frac{1}{\sigma\sqrt{n}} s_{[nt]},$$

where [nt] is the the largest integer less than or equal to nt.

From Lindeberg-Lévy's CLT,

$$\frac{1}{\sigma\sqrt{n}}\,s_{[nt]} = \left(\frac{[nt]}{n}\right)^{1/2}\frac{1}{\sigma\sqrt{[nt]}}\,s_{[nt]} \xrightarrow{D} \sqrt{t}\,\mathcal{N}(0,\,1),$$

which is just $\mathcal{N}(0, t)$, the distribution of w(t).

• For r < t, we have

$$(z_n(r), z_n(t) - z_n(r)) \xrightarrow{D} (w(r), w(t) - w(r)),$$

and hence $(z_n(r), z_n(t)) \xrightarrow{D} (w(r), w(t))$. This is easily extended to establish convergence of any finite-dimensional distributions and leads to the functional central limit theorem.

Lemma 5.41 (Donsker)

Let ζ_t be i.i.d. with mean μ_o and variance $\sigma_o^2 > 0$ and

$$\mathbf{z}_T(r) = rac{1}{\sigma_o \sqrt{T}} \sum_{t=1}^{[Tr]} (\zeta_t - \mu_o), \quad r \in [0, 1].$$

Then, $z_T \Rightarrow w$ as $T \rightarrow \infty$.

• Let ζ_t be r.v.s with mean μ_t and variance $\sigma_t^2 > 0$. Define long-run variance of ζ_t as

$$\sigma_*^2 = \lim_{T \to \infty} \operatorname{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \zeta_t \right),$$

 $\{\zeta_t\}$ is said to obey an FCLT if $z_T \Rightarrow w$ as $T \to \infty$, where

$$z_T(r) = rac{1}{\sigma_*\sqrt{T}}\sum_{t=1}^{[Tr]} (\zeta_t - \mu_t), \quad r \in [0,1].$$

• In the multivariate context, FCLT is $\mathbf{z}_T \Rightarrow \mathbf{w}$ as $T \rightarrow \infty$, where

$$\mathbf{z}_T(r) = rac{1}{\sqrt{T}} \mathbf{\Sigma}_*^{-1/2} \sum_{t=1}^{[Tr]} (\boldsymbol{\zeta}_t - \boldsymbol{\mu}_t), \quad r \in [0, 1],$$

 \mathbf{w} is the *d*-dimensional, standard Wiener process, and

$$\boldsymbol{\Sigma}_* = \lim_{T \to \infty} \frac{1}{T} \mathbb{E} \left[\left(\sum_{t=1}^T (\boldsymbol{\zeta}_t - \boldsymbol{\mu}_t) \right) \left(\sum_{t=1}^T (\boldsymbol{\zeta}_t - \boldsymbol{\mu}_t) \right)' \right],$$

Example 5.43

- $y_t = y_{t-1} + u_t$, t = 1, 2, ..., with $y_0 = 0$, where u_t are i.i.d. with mean zero and variance σ_u^2 .
- By Donsker's FCLT, the partial sum $y_{[Tr]} = \sum_{t=1}^{[Tr]} u_t$ is such that

$$\frac{1}{T^{3/2}}\sum_{t=1}^{T} y_t = \sigma_u \sum_{t=1}^{T} \int_{(t-1)/T}^{t/T} \frac{1}{\sqrt{T}\sigma_u} y_{[Tr]} \,\mathrm{d}r \Rightarrow \sigma_u \int_0^1 w(r) \,\mathrm{d}r,$$

• This result also verifies that $\sum_{t=1}^{T} y_t$ is $O_{\mathbb{P}}(T^{3/2})$. Similarly,

$$\frac{1}{T^2}\sum_{t=1}^T y_t^2 = \frac{1}{T}\sum_{t=1}^T \left(\frac{y_t}{\sqrt{T}}\right)^2 \Rightarrow \sigma_u^2 \int_0^1 w(r)^2 \,\mathrm{d}r,$$

so that $\sum_{t=1}^{T} y_t^2$ is $O_{\mathbb{P}}(T^2)$.