DIFFERENTIAL GEOMETRY I HOMEWORK 2

DUE: WEDNESDAY, OCTOBER 1

(1) Consider the determinant function on $\operatorname{Gl}(n; \mathbb{R})$. Show that

$$\mathrm{d}(\mathrm{det})|_{\mathfrak{m}} = \mathrm{det}(\mathfrak{m}) \sum_{i,j=1}^{n} (\mathfrak{m}^{-1})_{ji} \mathrm{d}\mathfrak{m}_{ij} \ .$$

If we denote by $d\mathfrak{m}$ the $n \times n$ matrix whose (i, j)-element is the coordinate differential $d\mathfrak{m}_{ij}$, we can write the above formula as

$$d(\det)|_{\mathfrak{m}} = \det(\mathfrak{m}) \operatorname{tr}(\mathfrak{m}^{-1} \mathrm{d}\mathfrak{m})$$

[*Hint*: This is a direct consequence of the Leibniz rule and the cofactor matrix construction of inverse matrices.]

(2) The main purpose of this exercise is to show that SO(3) is diffeomorphic to \mathbb{RP}^3 . Part of this exercise is similar to #2 of Homework 1.

Let $F : \mathbb{R}^4 \to \mathbb{M}(3; \mathbb{R}) \cong \mathbb{R}^9$ be given by

$$F(x, y, z, w) = \begin{bmatrix} x^2 + y^2 - z^2 - w^2 & 2(-xw + yz) & 2(xz + yw) \\ 2(xw + yz) & x^2 - y^2 + z^2 - w^2 & 2(-xy + zw) \\ 2(-xz + yw) & 2(xy + zw) & x^2 - y^2 - z^2 + w^2 \end{bmatrix}$$

Let $\mathbf{S}^3 = \{(x, y, z, w) \in \mathbb{R}^4 \mid x^2 + y^2 + z^2 + w^2 = 1\}$. Observe that $f = F|_{\mathbf{S}^3}$ satisfies f(x, y, z, w) = f(-x, -y, -z, -w), so that it descends to a map

$$\tilde{f}: \mathbb{RP}^3 = \mathbf{S}^3 / \{\pm 1\} \to \mathbb{M}(3; \mathbb{R})$$
.

- (a) Check that the image of \tilde{f} belongs to SO(3).
- (b) Prove that \tilde{f} is injective. [*Hint*: x^2 , y^2 , z^2 and w^2 can be solved from the diagonal elements.]
- (c) Show that \tilde{f} is a smooth embedding. [*Hint*: A bijective continuous map from a compact topological space to a Hausdorff topological space is a homeomorphism.]

To sum up, the image of \tilde{f} is a smooth submanifold of SO(3). Since both \mathbb{RP}^3 and SO(3) are of dimension three, the image of \tilde{f} must be open in SO(3). Since \mathbb{RP}^3 is compact, the image of \tilde{f} is closed in SO(3). By the *connectedness* (think about this fact) of SO(3), \tilde{f} is a diffeomorphism from \mathbb{RP}^3 to SO(3). Or, you can use Item (b) to prove surjectivity directly.

(3) Reading Assignment: p.75–85 of Calculus on Manifolds by Michael Spivak.