

**INTRODUCTION TO SYMPLECTIC GEOMETRY
HOMEWORK 7**

DUE: MONDAY, OCTOBER 28

- (1) Let (M, ω) be a symplectic manifold. Let $(\mathcal{C}^\infty(M), \{, \})$ be the Poisson algebra of M . We have proved that

$$X_{\{f, g\}} = -[X_f, X_g] . \tag{0.1}$$

We compute

$$\begin{aligned} \{f, \{g, h\}\} + \{g, \{h, f\}\} &= \omega(X_f, X_{\{g, h\}}) + \omega(X_g, X_{\{h, f\}}) \\ &= -X_f(\{g, h\}) - X_g(\{h, f\}) \\ &= X_f(X_g(h)) - X_g(X_f(h)) \\ &= [X_f, X_g](h) \\ &= -X_{\{f, g\}}(h) \quad \text{by (0.1)} \\ &= -\{h, \{f, g\}\} , \end{aligned}$$

and this proves the Jacobi identity. In this exercise, you are asked to prove the Jacobi identity using another argument.

- (a) Let $\varphi_t = \exp(tX_h)$ be the flow of X_h . Prove that

$$\left. \frac{d}{dt} \right|_{t=0} X_{\varphi_t^* f} = X_{X_h(f)} . \tag{0.2}$$

- (b) Note that $\varphi_t^* \{f, g\} = \{\varphi_t^* f, \varphi_t^* g\}$. Differentiate the equation with respect to t and evaluate at $t = 0$. Use it to conclude the Jacobi identity.

- (2) (from [CdS1, #1 of Howework 15]) Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a smooth function. f is called *strictly convex* if $f''(x) > 0$ for all $x \in \mathbb{R}$.

- (a) Assuming that f is strictly convex, prove that the following four conditions are equivalent:

- $f' = 0$ at some point x_0 ,
- f has a local minimum at some point x_0 ,
- f has a unique (global) minimum at some point x_0 ,
- $f(x) \rightarrow \infty$ as $x \rightarrow \pm\infty$. (*Hint.* Strictly convexity implies that the graph of f must lie above its tangent line (of any point).)

The function f is *stable* if it satisfies one (and hence all) of these conditions. The same story works in higher dimensions as well, see [CdS1, #2 of Howework 15].

- (b) For what values of a is the function $e^x + ax$ stable? For those values of a for which it is not stable, what does the graph look like?

- (3) (from [CdS1, #3 of Howework 15]) let V be an n -dimensional vector space and $F : V \rightarrow \mathbb{R}$ be a smooth function. Since V is a vector space, there is a canonical identification $T_p^*V \cong V^*$, for every $p \in V$. Therefore, we can define a map

$$L_F : V \rightarrow V^* \quad (\text{Legendre transform})$$

by setting

$$L_F(p) = (dF)|_p \in T_p^*V \cong V^* .$$

Show that, if F is strictly convex, then, for every point $p \in V$, L_F maps a neighborhood of p diffeomorphically onto a neighborhood of $L_F(p)$.

- (4) (from [CdS1, #4, #6 of Howework 15]) Given any strictly convex function $F : V \rightarrow \mathbb{R}$, we will denote by S_F the set of $\ell \in V^*$ for which the function

$$\begin{aligned} F_\ell : V &\rightarrow \mathbb{R} \\ p &\mapsto F(p) - \ell(p) \end{aligned}$$

is stable. Prove that:

- (a) The set S_F is open and convex.
- (b) L_F maps V diffeomorphically onto S_F .
- (c) If $\ell \in S_F$ and $p_0 = L_F^{-1}(\ell)$, then p_0 is the unique minimum point of the function F_ℓ .

Let $F^* : S_F \rightarrow \mathbb{R}$ be the function defined by

$$F^*(\ell) = - \min_{p \in V} F_\ell(p) . \quad (0.3)$$

It is not hard to prove that the function F^* is also a smooth function, and is called the *dual* of the function F .

- (d) Prove the Young's inequality: $F(p) + F^*(\ell) \geq \ell(p)$ for any $p \in V$ and $\ell \in S_F$.
 - (e) In Exercise (3), the Legendre transform is defined using derivative. Give a definition of $L_F(p)$ that does not involve taking derivative. (*Hint.* The construction of F^* does not use derivatives.)
- (5) (from [CdS1, #5 of Howework 15]) For the following strictly convex functions on \mathbb{R}^1 , find out the set S_f defined in Exercise (4).
- (a) $f(x) = x^4$.
 - (b) $f(x) = e^x - x$.

In general, S_F may not be the whole space V^* . A sufficient condition for $S_F = V^*$ is that F has *quadratic growth at infinity*. That is to say, there exists a positive-definite quadratic form Q on V and a constant K such that $F(p) \geq Q(p) - K$, for all $p \in V$.