

Composite Singer Arrays with Hole-Free Coarrays and Enhanced Robustness

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ICASSP 2019

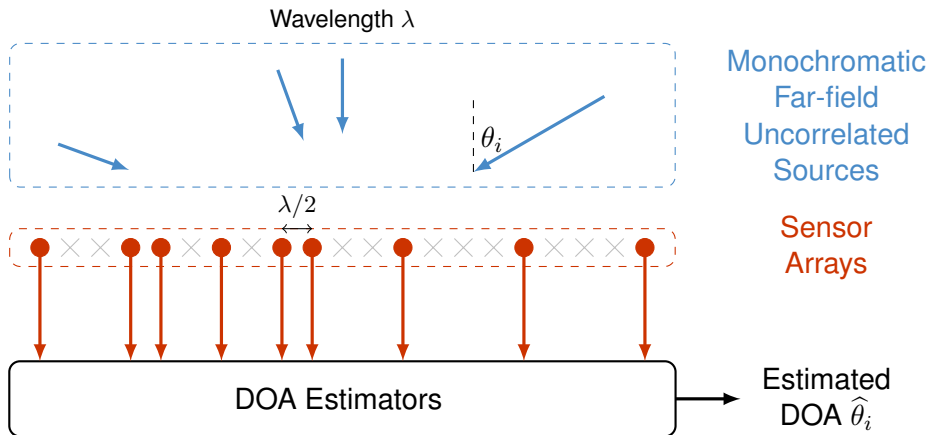
Outline

- 1 Introduction
- 2 Review of Sparse Array Design for Robustness
- 3 Composite Singer Arrays (Proposed)
- 4 A Numerical Example of Composite Singer Arrays
- 5 Concluding Remarks

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Direction-Of-Arrival (DOA) Estimation



¹Van Trees, *Optimum Array Processing: Part IV of Detection, Estimation, and Modulation Theory*, 2002.

Physical Array and Difference Coarray

Physical array $\mathbb{S} = \{1, 2, 3, 4, 5, 10, 15, 20\}$



Difference coarray $\mathbb{D} = \{n_1 - n_2 : n_1, n_2 \in \mathbb{S}\}$



¹Van Trees, *Optimum Array Processing: Part IV of Detection, Estimation, and Modulation Theory*, 2002; Pillai, Bar-Ness, and Haber, *Proc. IEEE*, 1985; Abramovich, Gray, Gorokhov, and Spencer, *IEEE Trans. Signal Process.*, 1998; Pal and Vaidyanathan, *IEEE Trans. Signal Process.*, 2010; Vaidyanathan and Pal *IEEE Trans. Signal Process.*, 2011.

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ULA and Sparse Arrays

ULA (Not Sparse)



- Identify at most $N - 1$ uncorrelated sources¹ (N is the number of sensors)
- Can only find fewer sources than sensors
- **Robust to sensor failures**

Linear Sparse Arrays

- 1 Minimum redundancy arrays
 - 2 Nested arrays
 - 3 Coprime arrays
 - 4 Super nested arrays
- Identify $\mathcal{O}(N^2)$ uncorrelated sources since **the difference coarray has size $\mathcal{O}(N^2)$**
 - **More sources than sensors!**

¹Van Trees, *Optimum Array Processing: Part IV of Detection, Estimation, and Modulation Theory*, 2002.

²Moffet, *IEEE Trans. Antennas Propag.*, 1968. (MRA)

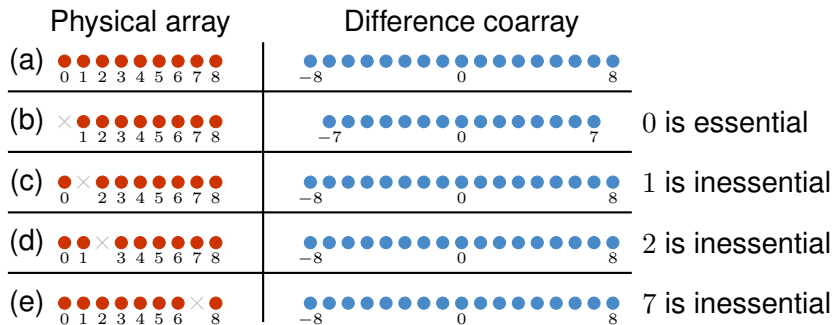
³Pal and Vaidyanathan, *IEEE Trans. Signal Process.*, 2010. (Nested arrays)

⁴Vaidyanathan and Pal, *IEEE Trans. Signal Process.*, 2011. (Coprime arrays)

⁵Liu and Vaidyanathan, *IEEE Trans. Signal Process.*, 2016. (Super nested arrays)

The Essentialness Property

The sensor $n \in \mathbb{S}$ is **essential** with respect to \mathbb{S} if $\overline{\mathbb{D}} \neq \mathbb{D}$.



¹Liu and Vaidyanathan, *IEEE ICASSP*, 2018; *IEEE Trans. Signal Process.*, 2019.

² \mathbb{D} is the difference coarray of \mathbb{S} and $\overline{\mathbb{D}}$ is the difference coarray of $\mathbb{S} \setminus \{n\}$.

The Fragility of an Array \mathcal{S}

$$\text{The fragility } F(\mathcal{S}) \triangleq \frac{\text{\# of essential sensors}}{N}.$$

\mathcal{S} : The sensor array;

N : The number of sensors

$$\frac{2}{N} \leq F(\mathcal{S}) \leq 1 \quad (\text{for } N \geq 4 \text{ and any } \mathcal{S})$$



¹Liu and Vaidyanathan, *IEEE ICASSP*, 2018; *IEEE Trans. Signal Process.*, 2019.

Sparse Arrays with Minimum Fragility

Main Idea

We would like to study an array configuration \mathbb{S} such that

- 1 \mathbb{S} owns hole-free difference coarrays of size $\mathcal{O}(N^2)$
- 2 \mathbb{S} is as robust as ULA with the same number of sensors N
(In particular, $F(\mathbb{S}) = 2/N$)

Known Solutions: Robust Minimum Redundancy Arrays (RMRA)

- Hole-free difference coarrays of size $\mathcal{O}(N^2)$
- Minimum fragility ($F(\mathbb{S}) = 2/N$)
- No closed-form solutions

¹Liu and Vaidyanathan, *Proc. of the 52th Asilomar Conference on Signals, Systems, and Computers*, 2018.

The Focus of This Talk

Main Idea

We would like to study an array configuration \mathbb{S} such that

- 1 \mathbb{S} owns hole-free difference coarrays of size $\mathcal{O}(N^2)$
- 2 \mathbb{S} is as robust as ULA with the same number of sensors N
(In particular, $F(\mathbb{S}) = 2/N$)

Solutions to the above problem
whose sensor locations can be found easily

¹Liu and Vaidyanathan, *IEEE ICASSP*, 2019.

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Singer Arrays

Theorem (Rephrase from [1])

Let q be a power of a prime number. Assume that $M = q^2 + q + 1$. Then there exist $q + 1$ integers d_1, d_2, \dots, d_{q+1} such that

- ① $0 = d_1 < d_2 < \dots < d_{q+1} < M$ and
- ② The set of pairwise differences between d_i and d_j for $i \neq j$ is equivalent to $\{1, 2, \dots, M - 1\}$, under the modulo- M operation. That is,

$$\begin{aligned} & \{((d_i - d_j))_M : i \neq j, \quad i, j = 1, 2, \dots, q + 1\} \\ & = \{1, 2, \dots, M - 1\}, \end{aligned}$$

where $((a))_b$ denotes the remainder of a divided by b .

Definition: Singer Arrays

A Singer array with the parameter q (a power of a prime) is defined as the set $\{d_1, d_2, \dots, d_{q+1}\}$, where d_1, d_2, \dots, d_{q+1} are given in the above theorem.

¹J. Singer, *Trans. Amer. Math. Soc.*, 1938.

Composite Arrays

Definition: $(\alpha, \mathbb{S}_1, \mathbb{S}_2)$ -composite array (Rephrase from [1])

Suppose α is a positive integer. Let \mathbb{S}_1 and \mathbb{S}_2 denote two sensor arrays with $\min(\mathbb{S}_1) = \min(\mathbb{S}_2) = 0$. Then the $(\alpha, \mathbb{S}_1, \mathbb{S}_2)$ -composite array \mathbb{S}_c is defined as

$$\mathbb{S}_c \triangleq \alpha\mathbb{S}_1 + \mathbb{S}_2 = \{\alpha n_1 + n_2 : n_1 \in \mathbb{S}_1, n_2 \in \mathbb{S}_2\},$$

where $\alpha > \max(\mathbb{S}_2)$.

- This technique was used in the literature to generate arrays with large difference coarrays¹.

¹Erdős and Gál, *Indagationes Mathematicae*, 1948; Leech, *J. London Math. Soc.*, 1956; Ishiguro, *Radio Science*, 1980; Yang, Haimovich, Yuan, Sun, and Chen, *IEEE Access*, 2018.

An Example of Singer Arrays and Composite Arrays

0 1 2 3



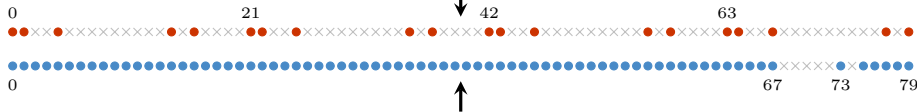
← \mathbb{S}_1 : The ULA with 4 sensors

0 1 4 14 16



← \mathbb{S}_2 : The Singer array with $q = 4$

\mathbb{S}_c : The $(\alpha, \mathbb{S}_1, \mathbb{S}_2)$ -composite array with $\alpha = 21$



\mathbb{D}_c^+ : The nonnegative part of the difference coarray of \mathbb{S}_c

- \mathbb{D}_c has a large central ULA segment.
- \mathbb{S}_c is as robust as \mathbb{S}_1 ($F(\mathbb{S}_1) = 1/2$ and $F(\mathbb{S}_c) = 1/2$).

The Focus of This Talk

Main Idea

We would like to study an array configuration \mathbb{S} such that

- 1 \mathbb{S} owns hole-free difference coarrays of size $\mathcal{O}(N^2)$
- 2 \mathbb{S} is as robust as ULA with the same number of sensors N
(In particular, $F(\mathbb{S}) = 2/N$)

Solutions to the above problem
whose sensor locations can be found easily

¹Liu and Vaidyanathan, *IEEE ICASSP*, 2019.

Problems with Composite Arrays plus Singer Arrays

0 1 2 3



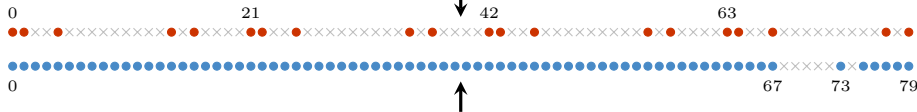
← \mathbb{S}_1 : The ULA with 4 sensors

0 1 4 14 16



← \mathbb{S}_2 : The Singer array with $q = 4$

\mathbb{S}_c : The $(\alpha, \mathbb{S}_1, \mathbb{S}_2)$ -composite array with $\alpha = 21$



\mathbb{D}_c^+ : The nonnegative part of the difference coarray of \mathbb{S}_c

- \mathbb{D}_c has holes
- \mathbb{S}_c DO NOT have minimum fragility ($F(\mathbb{S}_c) \neq \frac{2}{N}$)

Supplementary Arrays (Proposed)

Definition: Supplementary Arrays

Let P and Q be positive integers satisfying $Q > 2P(P - 1)$. The supplementary array \mathbb{S}_{supp} with parameters P and Q is defined as

$$\mathbb{S}_{\text{supp}} = \{u, uP, Q - u, Q - uP : u = 0, 1, \dots, P - 1\}.$$

The Supplementary Array with $P = 4$ and $Q = 60$

\mathbb{S}_{supp} :



$\mathbb{D}_{\text{supp}}^+$: (The nonnegative part of the difference coarray of \mathbb{S}_{supp})



Properties of Supplementary Arrays

Let \mathbb{S}_{supp} be the supplementary array with parameters P and Q . Let \mathbb{D}_{supp} be the difference coarray of \mathbb{S}_{supp} . Define the new set

$$\mathbb{L} \triangleq \{1, 2, 3, \dots, P^2 - P, \\ Q - 1, Q - 2, Q - 3, \dots, Q - (P^2 - 1)\}.$$

Then the following properties hold

- 1 $|\mathbb{S}_{\text{supp}}| = 4P - 2$.
- 2 $\mathbb{L} \subseteq \mathbb{D}_{\text{supp}}$.
- 3 Let $n \in \mathbb{S}_{\text{supp}} \setminus \{0, Q\}$. Denote the difference coarray of $\overline{\mathbb{S}}_{\text{supp}} \triangleq \mathbb{S}_{\text{supp}} \setminus \{n\}$ by $\overline{\mathbb{D}}_{\text{supp}}$. Then $\mathbb{L} \subseteq \overline{\mathbb{D}}_{\text{supp}}$.

\mathbb{S}_{supp} helps to fill the holes and increase the robustness

Composite Singer Arrays \mathbb{S}_{CS}

$$\mathbb{S}_{CS} = \mathbb{S}_c \cup \mathbb{S}_{\text{supp}}$$

The $(\alpha, \mathbb{S}_1, \mathbb{S}_2)$ -Composite Array

- \mathbb{S}_1 :
 - $F(\mathbb{S}_1) = 2/|\mathbb{S}_1|$
 - Hole-free coarray
- \mathbb{S}_2 : A **Singer** array with the parameter q
 $(\mathbb{S}_2 = \{d_1, d_2, \dots, d_{q+1}\})$
- $\alpha = q^2 + q + 1$.

The Supplementary Array

- $P = \left\lceil \sqrt{2d_{q+1} + 1} \right\rceil$.
- $Q = \alpha A_1 + d_{q+1}$, where A_1 is the aperture of \mathbb{S}_1 .
- $Q > 2P(P - 1)$

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Design Parameters

- $\mathbb{S}_1 = \{0, 1, 2, 3, 5, 6\}$: Robust MRA with 6 sensors¹
 - $F(\mathbb{S}_1) = 2/6$
 - The difference coarray of \mathbb{S}_1 : $\mathbb{D}_1 = \{0, \pm 1, \pm 2, \dots, \pm 6\}$
- $\mathbb{S}_2 = \{0, 1, 4, 14, 16\}$: The Singer array with $q = 4$
- $\alpha = q^2 + q + 1 = 21$
- $P = \lceil \sqrt{2 \times 16 + 1} \rceil = 6$
- $Q = 21 \times 6 + 16 = 142$

¹Liu and Vaidyanathan, ACSSC, 2018.

Array Configurations

..... $\leftarrow \mathbb{S}_1 = \{0, 1, 2, 3, 5, 6\}$: RMRA with 6 sensors

..... $\leftarrow \mathbb{S}_2 = \{0, 1, 4, 14, 16\}$: The Singer array with $q = 4$

$\mathbb{S}_{CS} = \{0, 1, 2, 3, 4, 5, 6, 12, 14, 16, 18, 21, 22, 24, 25, 30, 35, 37, 42, 43, 46, 56, 58,$
 $63, 64, 67, 77, 79, 105, 106, 109, 112, 118, 119, 121, 124, 126, 127, 130, 136, 137, 138, 139, 140, 141, 142\}$

Essential sensors (red): 0, 142

The composite Singer array (46 sensors)



\mathbb{D}_{CS}^+ : The nonnegative part of the difference coarray of \mathbb{S}_c

$$\mathbb{D}_{CS}^+ = \{0, 1, \dots, 142\}$$

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Concluding Remarks

- Composite Singer arrays
 - Singer arrays, composite arrays, supplementary arrays
- Future work
 - New arrays with hole-free difference coarrays and minimum fragility
 - Two-dimensional arrays
- This work is supported by
 - Office of Naval Research
 - National Science Foundation
 - California Institute of Technology
 - Ministry of Education Republic of China (Taiwan)
 - National Taiwan University

Thank you!