# Chapter 9: Support vector machines 

Yu-Tzung Chang and Hsuan-Wei Lee<br>Department of Political Science, National Taiwan University<br>2019.01.03.

## Outline

- Maximal margin classifier
- Support vector classifiers
- Support vector machines
- SVMs with more than 2 classes
- Relationship to logistic regression


## Support vector machines

Here we approach the two-class classification problem in a direct way:
We try and find a plane that separates the classes in feature space.
If we cannot, we get creative in two ways:

- We soften what we mean by "separates".
- We enrich and enlarge the feature space so that separation is possible.


## What is a hyperplane?

- A hyperplane in $p$ dimensions is a flat affine subspace of dimension $p-1$.
- In general, the equation for a hyperplane has the form:

$$
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}+\cdots+\beta_{p} X_{p}=0
$$

- In $p=2$ dimensions a hyperplane is a line.
- If $\beta_{0}=0$, the hyperplane goes through the origin, otherwise not.
- The vector $\beta=\left(\beta_{1}, \beta_{2}, \ldots, \beta_{p}\right)$ is called the normal vector - it points in a direction orthogonal to the surface of a hyperplane.

Hyperplane in 2 dimensions


## Separating hyperplanes




- If $f(X)=\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}+\cdots+\beta_{p} X_{p}$, then $f(X)>0$ for points on one side of the hyperplane, and $f(X)<0$ for points on the other side.
- If we code the colored points as $Y_{i}=+1$ for blue, say, and $Y_{i}=-1$ for mauve, then if $Y_{i} \cdot f\left(X_{i}\right)>0$ for all $i, f(X)=0$ defines a separating hyperplane.


## Maximal margin classifier

- Among all separating hyperplanes, find the one that makes the biggest gap or margin between the two classes.
- Constrained optimization problem maximize ${ }_{\beta_{0}, \beta_{1}, \ldots, \beta_{p}} M$ subject to $\sum_{j=1}^{p} \beta_{j}^{2}=1$, $y_{i}\left(\beta_{0}+\beta_{1} X_{i s 1}+\beta_{2} X_{i 2}+\cdots+\beta_{p} X_{i p}\right) \geqslant M, \forall i=1, \ldots, N$.

- Note: this can be rephrased as a convex quadratic program, and solved efficiently.


## Non-separable data

The data are not separable by a linear boundary. This is often the case unless $N<p$.


## Noisy data

Sometimes the data are separable, but noisy. This can lead to a poor solution for the maximal-margin classifier.


The support vector classifier maximizes a soft margin.

## Support vector classifier


maximize $_{\beta_{0}, \beta_{1}, \ldots, \beta_{p}, \epsilon_{1}, \ldots, \epsilon_{n}} M$ subject to $\sum_{j=1}^{p} \beta_{j}^{2}=1$,
$y_{i}\left(\beta_{0}+\beta_{1} X_{i 1}+\beta_{2} X_{i 2}+\cdots+\beta_{p} X_{i p}\right) \geqslant M\left(1-\epsilon_{i}\right)$, $\epsilon_{i} \geqslant 0, \sum_{i=1}^{n} \epsilon_{i} \leqslant C$.

## $C$ is a regularization parameter



## Linear boundary can fail



Sometime a linear boundary simply won't work, no matter what value of $C$.

## Feature expansion

- Enlarge the space of features by including transformations, e.g. $X_{1}^{2}, X_{1}^{3}, X_{1} X_{2}, X_{1} X_{2}^{2}, \ldots$. Hence go from a $p$-dimensional space to a $N<p_{\text {new }}$ dimensional space.
- Fit a support vector classifier in the enlarged space.
- This results in non-linear decision boundaries in the original space.

Example: Suppose we use $\left(X_{1}, X_{2}, X_{1}^{2}, X_{2}^{2}, X_{1} X_{2}\right)$ instead of just $\left(X_{1}, X_{2}\right)$. Then the decision boundary would be of the form

$$
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}+\beta_{3} X_{1}^{2}+\beta_{4} X_{2}^{2}+\beta_{5} X_{1} X_{2}=0
$$

This leads to nonlinear decision boundaries in the original space (quadratic conic sections).

## Cubic polynomials




Here we use a basis expansion of cubic polynomials. From 2 variables to 9 . The support vector classifier in the enlarged space solves the problem in the lower-dimensional space.

$$
\begin{gather*}
\beta_{0}+\beta_{1} X_{1}+\beta_{2} X_{2}+\beta_{3} X_{1}^{2}+\beta_{4} X_{2}^{2}+\beta_{5} X_{1} X_{2} \\
\quad+\beta_{6} X_{1}^{3}+\beta_{7} X_{2}^{2}+\beta_{8} X_{1} X_{2}^{2}+\beta_{9} X_{1}^{2} X_{2}=0
\end{gather*}
$$

## Nonlinearities and kernels

- Polynomials (especially high-dimensional ones) get wild rather fast.
- There is a more elegant and controlled way to introduce nonlinearities in support vector classifiers - through the use of kernels.
- Need to understand the role of inner products in support vector classifiers.


## Inner products and support vectors

- $\left\langle x_{i}, x_{i^{\prime}}\right\rangle=\sum_{j=1}^{p} x_{i j} x_{i^{\prime} j}-$ inner products between vectors
- The linear support vector classifier can be represented as

$$
f(x)=\beta_{0}+\sum_{i=1}^{n} \alpha_{i}\left\langle x, x_{i}\right\rangle
$$

with $n$ parameters.

- To estimate the parameters $\alpha_{1}, \ldots, \alpha_{n}$ and $\beta_{0}$, all we need are the $\binom{n}{2}$ inner products $\left\langle x_{i}, x_{i^{\prime}}\right\rangle$ between all pairs of training observations.
- It turns out that most of the $\hat{\alpha}_{i}$ can be zero:

$$
f(x)=\beta_{0}+\sum_{i \in S} \hat{\alpha}_{i}\left\langle x, x_{i}\right\rangle
$$

where $S$ is the support set of indices $i$ such that $\hat{\alpha}_{i}>0$.

## Kernels and support vector machines

- If we can compute inner-products between observations, we can fit a SV classifier. This can be quite abstract.
- Some special kernel functions can do this for us. E.g.

$$
K\left(x_{i}, x_{i^{\prime}}\right)=\left(1+\sum_{j=1}^{p} x_{i j} x_{i^{\prime} j}\right)^{d}
$$

computes the inner-products needed for $d$ dimensional polynomials - $\binom{p+d}{d}$ basis functions.

- The solution has the form

$$
f(x)=\beta_{0}+\sum_{i \in S} \hat{\alpha}_{i} K\left(x, x_{i}\right)
$$

## Radial kernel

$$
K\left(x_{i}, x_{i^{\prime}}\right)=\exp \left(-\gamma \sum_{j=1}^{p}\left(x_{i j}-x_{i^{\prime} j}\right)^{2}\right)
$$



$$
f(x)=\beta_{0}+\sum_{i \in S} \hat{\alpha}_{i} K\left(x, x_{i}\right) .
$$

Implicit feature space; very high dimensional. Controls variances by squashing down most dimensions severely.

## Example: Heart data (training)



ROC curve is obtained by changing the threshold 0 to threshold $t$ in $\hat{f}(X)>t$, and recording false positive and true positive rates as $t$ varies. Here we see ROC curves on training data.

## Example: Heart data (test)



## SVMs: more than 2 classes?

The SVM as defined works for $K=2$ classes. What do we do if we have $K>2$ classes?

- OVA One versus All. Fit $K$ different 2-class SVM classifiers $\hat{f}_{k}(x), k=1, \ldots, K$; each class versus the rest. Classify $x^{*}$ to the class for which $\hat{f}_{k}\left(x^{*}\right)$ is largest.
- OVO One versus One. Fit all $\binom{K}{2}$ pairwise classifiers $\hat{f}_{k l}(x)$. Classify $x^{*}$ to the class that wins the most pairwise competitions.
Which one to choose? If $K$ is not too large, use OVO.


## Support vector versus logistic regression?

With $f(X)=\beta_{0}+\beta_{1} X_{1}+\cdots+\beta_{p} X_{p}$ can rephrase support vector classifier optimization as

$$
\operatorname{minimize}_{\beta_{0}, \beta_{1}, \ldots, \beta_{p}}\left\{\sum_{i=1}^{n} \max \left[0,1-y_{i} f\left(x_{i}\right)\right]+\lambda \sum_{j=1}^{p} \beta_{j}^{2}\right\}
$$

This has the form loss plus penalty.


The loss is known as the hinge loss. It's very similar to "loss" in logistic regression (negative log-likelihood).

## Which to use: SVM or logistic regression

- When classes are (nearly) separable, SVM does better than LR. So does LDA.
- When not, LR (with ridge penalty) and SVM very similar.
- If you wish to estimate probabilities, LR is the choice.
- For nonlinear boundaries, kernel SVMs are popular.Can use kernels with LR and LDA as well, but computations are more expensive.

