

Asymptotic Least Squares Theory

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When Regressors are Stochastic

Given $\mathbf{y} = \mathbf{X}\beta + \mathbf{e}$, suppose that \mathbf{X} is stochastic. Then, [A2](i) does not hold because $\mathbb{E}(\mathbf{y})$ can not be $\mathbf{X}\beta_o$.

- It would be difficult to evaluate $\mathbb{E}(\hat{\beta}_T)$ and $\text{var}(\hat{\beta}_T)$ because $\hat{\beta}_T$ is a complex function of the elements of \mathbf{y} and \mathbf{X} .
- Assume $\mathbb{E}(\mathbf{y} | \mathbf{X}) = \mathbf{X}\beta_o$.
 - $\mathbb{E}(\hat{\beta}_T) = \mathbb{E}[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbb{E}(\mathbf{y} | \mathbf{X})] = \beta_o$.
 - If $\text{var}(\mathbf{y} | \mathbf{X}) = \sigma_o^2\mathbf{I}_T$,

$$\text{var}(\hat{\beta}_T) = \mathbb{E}[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\text{var}(\mathbf{y} | \mathbf{X})\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}] = \sigma_o^2\mathbb{E}(\mathbf{X}'\mathbf{X})^{-1},$$

which is not the same as $\sigma_o^2(\mathbf{X}'\mathbf{X})^{-1}$.

- $(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$ is not normally distributed even when \mathbf{y} is.

Q: Is the condition $\mathbb{E}(\mathbf{y} \mid \mathbf{X}) = \mathbf{X}\beta_o$ realistic?

Suppose that \mathbf{x}_t contains only one regressor y_{t-1} . Then,

$\mathbb{E}(y_t \mid \mathbf{x}_1, \dots, \mathbf{x}_T) = \mathbf{x}'_t \beta_o$ implies

$$\mathbb{E}(y_t \mid y_1, \dots, y_{T-1}) = \beta_o y_{t-1},$$

which is y_t with probability one. As such, the conditional variance of y_t ,

$$\text{var}(y_t \mid y_1, \dots, y_{T-1}) = \mathbb{E}\{[y_t - \mathbb{E}(y_t \mid y_1, \dots, y_{T-1})]^2 \mid y_1, \dots, y_{T-1}\},$$

must be zero, rather than a positive constant σ_o^2 .

Note: When \mathbf{X} is stochastic, a different framework is needed to evaluate the properties of the OLS estimator.

Notations

- We observe $(y_t \mathbf{w}_t')'$, where \mathbf{w}_t ($m \times 1$) is the vector of all “exogenous” variables.
- $\mathcal{W}^t = \{\mathbf{w}_1, \dots, \mathbf{w}_t\}$ and $\mathcal{Y}^t = \{y_1, \dots, y_t\}$. Then, $\{\mathcal{Y}^{t-1}, \mathcal{W}^t\}$ generates a σ -algebra that is the information set up to time t .
- Regressors \mathbf{x}_t ($k \times 1$) are taken from the information set $\{\mathcal{Y}^{t-1}, \mathcal{W}^t\}$, and the resulting linear specification is

$$y_t = \mathbf{x}_t' \boldsymbol{\beta} + e_t, \quad t = 1, 2, \dots, T.$$

- The OLS estimator of this specification is

$$\hat{\boldsymbol{\beta}}_T = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} = \left(\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\sum_{t=1}^T \mathbf{x}_t y_t \right).$$

Consistency

The OLS estimator $\hat{\beta}_T$ is **strongly (weakly) consistent** for β^* if $\hat{\beta}_T \xrightarrow{\text{a.s.}} \beta^*$ ($\hat{\beta}_T \xrightarrow{\mathbf{P}} \beta^*$) as $T \rightarrow \infty$. That is, $\hat{\beta}_T$ will be eventually close to β^* in a proper probabilistic sense when “enough” information becomes available.

[B1] (i) $\{\mathbf{x}_t \mathbf{x}_t'\}$ obeys a SLLN (WLLN) with the almost sure (prob.) limit

$$\mathbf{M}_{xx} := \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(\mathbf{x}_t \mathbf{x}_t'),$$

which is nonsingular.

[B1] (ii) $\{\mathbf{x}_t y_t\}$ obeys a SLLN (WLLN) with the almost sure (prob.) limit

$$\mathbf{m}_{xy} := \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(\mathbf{x}_t y_t).$$

[B2] There exists a β_o such that $y_t = \mathbf{x}_t' \beta_o + \epsilon_t$ with $\mathbb{E}(\mathbf{x}_t \epsilon_t) = \mathbf{0}$ for all t .

By [B1] and Lemma 5.13, the OLS estimator of $\hat{\beta}_T$ is

$$\left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t y_t \right) \rightarrow \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy} \quad \text{a.s. (in probability).}$$

When [B2] holds, $\mathbb{E}(\mathbf{x}_t \mathbf{y}_t) = \mathbb{E}(\mathbf{x}_t \mathbf{x}_t') \beta_o$, so that $\mathbf{m}_{xy} = \mathbf{M}_{xx} \beta_o$, and $\beta^* = \beta_o$.

Theorem 6.1

Consider the linear specification $y_t = \mathbf{x}_t' \beta + e_t$.

- (i) When [B1] holds, $\hat{\beta}_T$ is strongly (weakly) consistent for $\beta^* = \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy}$.
- (ii) When [B1] and [B2] hold, $\beta_o = \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy}$ so that $\hat{\beta}_T$ is strongly (weakly) consistent for β_o .

Remarks:

- Theorem 6.1 is about **consistency** (not unbiasedness), and what really matters is whether the data are governed by some SLLN (WLLN).
- Note that [B1] explicitly allows \mathbf{x}_t to be a random vector which may contain some lagged dependent variables ($y_{t-j}, j \geq 1$) and other random variables in the information set. Also, the random data may exhibit **dependence** and **heterogeneity**, as long as such dependence and heterogeneity do not affect the LLN in [B1].
- Given [B2], $\mathbf{x}'_t \boldsymbol{\beta}$ is the correct specification for the **linear projection** of y_t , and the OLS estimator converges to the parameter of interest $\boldsymbol{\beta}_o$.
- A sufficient condition for [B2] is that there exists $\boldsymbol{\beta}_o$ such that $\mathbb{E}(y_t | \mathcal{Y}^{t-1}, \mathcal{W}^t) = \mathbf{x}'_t \boldsymbol{\beta}_o$. (Why?)

Corollary 6.2

Suppose that $(y_t \mathbf{x}'_t)'$ are independent random vectors with bounded $(2 + \delta)$ th moment for any $\delta > 0$, such that \mathbf{M}_{xx} and \mathbf{m}_{xy} defined in [B1] exist. Then, the OLS estimator $\hat{\beta}_T$ is strongly consistent for $\beta^* = \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy}$. If [B2] also holds, $\hat{\beta}_T$ is strongly consistent for β_o .

Proof: By the Cauchy-Schwartz inequality (Lemma 5.5), the i th element of $\mathbf{x}_t y_t$ is such that

$$\mathbb{E} |x_{ti} y_t|^{1+\delta} \leq [\mathbb{E} |x_{ti}|^{2(1+\delta)}]^{1/2} [\mathbb{E} |y_t|^{2(1+\delta)}]^{1/2} \leq \Delta,$$

for some $\Delta > 0$. Similarly, each element of $\mathbf{x}_t \mathbf{x}'_t$ also has bounded $(1 + \delta)$ th moment. Then, $\{\mathbf{x}_t \mathbf{x}'_t\}$ and $\{\mathbf{x}_t y_t\}$ obey Markov's SLLN by Lemma 5.26 with the respective almost sure limits \mathbf{M}_{xx} and \mathbf{m}_{xy} .

Example: Given the specification: $y_t = \alpha y_{t-1} + e_t$, suppose that $\{y_t^2\}$ and $\{y_t y_{t-1}\}$ obey a SLLN (WLLN). Then, the OLS estimator of α is such that

$$\hat{\alpha}_T \rightarrow \frac{\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(y_t y_{t-1})}{\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(y_{t-1}^2)} \quad \text{a.s. (in probability).}$$

When $\{y_t\}$ indeed follows a stationary AR(1) process:

$$y_t = \alpha_o y_{t-1} + u_t, \quad |\alpha_o| < 1,$$

where u_t are i.i.d. with mean zero and variance σ_u^2 , we have $\mathbb{E}(y_t) = 0$, $\text{var}(y_t) = \sigma_u^2 / (1 - \alpha_o^2)$ and $\text{cov}(y_t, y_{t-1}) = \alpha_o \text{var}(y_t)$. We have

$$\hat{\alpha}_T \rightarrow \frac{\text{cov}(y_t, y_{t-1})}{\text{var}(y_t)} = \alpha_o, \quad \text{a.s. (in probability).}$$

When $\mathbf{x}'_t\boldsymbol{\beta}_o$ is not the linear projection, i.e., $\mathbb{E}(\mathbf{x}_t\epsilon_t) \neq \mathbf{0}$,

$$\mathbb{E}(\mathbf{x}_t y_t) = \mathbb{E}(\mathbf{x}_t \mathbf{x}'_t) \boldsymbol{\beta}_o + \mathbb{E}(\mathbf{x}_t \epsilon_t).$$

Then, $\mathbf{m}_{xy} = \mathbf{M}_{xx} \boldsymbol{\beta}_o + \mathbf{m}_{x\epsilon}$, where

$$\mathbf{m}_{x\epsilon} = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(\mathbf{x}_t \epsilon_t).$$

The limit of the OLS estimator now reads

$$\boldsymbol{\beta}^* = \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy} = \boldsymbol{\beta}_o + \mathbf{M}_{xx}^{-1} \mathbf{m}_{x\epsilon}.$$

Example: Given the specification: $y_t = \mathbf{x}'_t \boldsymbol{\beta} + e_t$, suppose

$$\mathbb{E}(y_t \mid \mathcal{Y}^{t-1}, \mathcal{W}^t) = \mathbf{x}'_t \boldsymbol{\beta}_o + \mathbf{z}'_t \boldsymbol{\gamma}_o,$$

where \mathbf{z}_t are in the information set but distinct from \mathbf{x}_t . Writing

$$y_t = \mathbf{x}'_t \boldsymbol{\beta}_o + \mathbf{z}'_t \boldsymbol{\gamma}_o + \epsilon_t = \mathbf{x}'_t \boldsymbol{\beta}_o + u_t,$$

we have $\mathbb{E}(\mathbf{x}_t u_t) = \mathbb{E}(\mathbf{x}_t \mathbf{z}'_t) \boldsymbol{\gamma}_o \neq \mathbf{0}$. It follows that

$$\hat{\boldsymbol{\beta}}_T \rightarrow \mathbf{M}_{xx}^{-1} \mathbf{m}_{xy} = \boldsymbol{\beta}_o + \mathbf{M}_{xx}^{-1} \mathbf{M}_{xz} \boldsymbol{\gamma}_o,$$

with $\mathbf{M}_{xz} := \lim_T \sum_{t=1}^T \mathbb{E}(\mathbf{x}_t \mathbf{z}'_t) / T$. The limit can not be $\boldsymbol{\beta}_o$ unless \mathbf{x}_t is orthogonal to \mathbf{z}_t , i.e., $\mathbb{E}(\mathbf{x}_t \mathbf{z}'_t) = \mathbf{0}$.

Example: Given $y_t = \alpha y_{t-1} + e_t$, suppose that

$$y_t = \alpha_o y_{t-1} + \epsilon_t, \quad |\alpha_o| < 1,$$

where $\epsilon_t = u_t - \pi_o u_{t-1}$ with $|\pi_o| < 1$, and $\{u_t\}$ is a white noise with mean zero and variance σ_u^2 . Here, $\{y_t\}$ is a weakly stationary **ARMA(1,1)** process. We know $\hat{\alpha}_T$ converges to $\text{cov}(y_t, y_{t-1}) / \text{var}(y_{t-1})$ almost surely (in probability). Note, however, that $\epsilon_{t-1} = u_{t-1} - \pi_o u_{t-2}$ and

$$\mathbb{E}(y_{t-1} \epsilon_t) = \mathbb{E}[y_{t-1}(u_t - \pi_o u_{t-1})] = -\pi_o \sigma_u^2.$$

The limit of $\hat{\alpha}_T$ is then

$$\frac{\text{cov}(y_t, y_{t-1})}{\text{var}(y_{t-1})} = \frac{\alpha_o \text{var}(y_{t-1}) + \text{cov}(\epsilon_t, y_{t-1})}{\text{var}(y_{t-1})} = \alpha_o - \frac{\pi_o \sigma_u^2}{\text{var}(y_{t-1})}.$$

The OLS estimator is inconsistent for α_o unless $\pi_o = 0$.

Remark: Given the specification: $y_t = \alpha y_{t-1} + \mathbf{x}'_t \boldsymbol{\beta} + e_t$, suppose that

$$y_t = \alpha_o y_{t-1} + \mathbf{x}'_t \boldsymbol{\beta}_o + \epsilon_t,$$

such that ϵ_t are **serially correlated** (e.g., AR(1) or MA(1)). The OLS estimator is **inconsistent** because $\alpha_o y_{t-1} + \mathbf{x}'_t \boldsymbol{\beta}_o$ is **not** the linear projection, a consequence of the **joint** presence of a lagged dependent variable (e.g., y_{t-1}) and serially correlated disturbances (e.g., ϵ_t being AR(1) or MA(1)).

Asymptotic Normality

By **asymptotic normality** of $\hat{\beta}_T$ we mean:

$$\sqrt{T}(\hat{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{D}_o),$$

where \mathbf{D}_o is a p.d. matrix. We may also write

$$\mathbf{D}_o^{-1/2} \sqrt{T}(\hat{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_k).$$

Given the specification $y_t = \mathbf{x}'_t \beta + e_t$ and [B2], define

$$\mathbf{V}_T := \text{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{x}_t \epsilon_t \right).$$

[B3] $\{\mathbf{V}_o^{-1/2} \mathbf{x}_t \epsilon_t\}$ obeys a CLT, where $\mathbf{V}_o = \lim_{T \rightarrow \infty} \mathbf{V}_T$ is p.d.

- The normalized OLS estimator is

$$\begin{aligned}
 \sqrt{T}(\hat{\beta}_T - \beta_o) &= \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{x}_t \epsilon_t \right) \\
 &= \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \mathbf{V}_o^{1/2} \left[\mathbf{V}_o^{-1/2} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{x}_t \epsilon_t \right) \right] \\
 &\xrightarrow{D} \mathbf{M}_{xx}^{-1} \mathbf{V}_o^{1/2} \mathcal{N}(\mathbf{0}, \mathbf{I}_k).
 \end{aligned}$$

Theorem 6.6

Given $y_t = \mathbf{x}_t' \beta + e_t$, suppose that [B1](i), [B2] and [B3] hold. Then,

$$\sqrt{T}(\hat{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{D}_o), \quad \mathbf{D}_o = \mathbf{M}_{xx}^{-1} \mathbf{V}_o \mathbf{M}_{xx}^{-1}.$$

Corollary 6.7

Given $y_t = \mathbf{x}_t' \boldsymbol{\beta} + e_t$, suppose that $(y_t \ \mathbf{x}_t')'$ are independent random vectors with bounded $(4 + \delta)$ th moment for any $\delta > 0$ and that [B2] holds. If \mathbf{M}_{xx} defined in [B1] and \mathbf{V}_o defined in [B3] exist,

$$\sqrt{T}(\hat{\boldsymbol{\beta}}_T - \boldsymbol{\beta}_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{D}_o), \quad \mathbf{D}_o = \mathbf{M}_{xx}^{-1} \mathbf{V}_o \mathbf{M}_{xx}^{-1}.$$

Proof: Let $z_t = \boldsymbol{\lambda}' \mathbf{x}_t \epsilon_t$, where $\boldsymbol{\lambda}$ is such that $\boldsymbol{\lambda}' \boldsymbol{\lambda} = 1$. If $\{z_t\}$ obeys a CLT, then $\{\mathbf{x}_t \epsilon_t\}$ obeys a multivariate CLT by the **Cramér-Wold device**. Clearly, z_t are independent r.v. with mean zero and $\text{var}(z_t) = \boldsymbol{\lambda}' [\text{var}(\mathbf{x}_t \epsilon_t)] \boldsymbol{\lambda}$. By data independence,

$$\mathbf{V}_T = \text{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{x}_t \epsilon_t \right) = \frac{1}{T} \sum_{t=1}^T \text{var}(\mathbf{x}_t \epsilon_t).$$

Proof (Cont'd):

The average of $\text{var}(z_t)$ is then

$$\frac{1}{T} \sum_{t=1}^T \text{var}(z_t) = \boldsymbol{\lambda}' \mathbf{V}_T \boldsymbol{\lambda} \rightarrow \boldsymbol{\lambda}' \mathbf{V}_o \boldsymbol{\lambda}.$$

By the Cauchy-Schwartz inequality,

$$\mathbb{E} |x_{ti} y_t|^{2+\delta} \leq [\mathbb{E} |x_{ti}|^{2(2+\delta)}]^{1/2} [\mathbb{E} |y_t|^{2(2+\delta)}]^{1/2} \leq \Delta,$$

for some $\Delta > 0$. Similarly, $x_{ti} x_{tj}$ have bounded $(2 + \delta)$ th moment. It follows that $x_{ti} \epsilon_t$ and z_t also have bounded $(2 + \delta)$ th moment by Minkowski's inequality. Then by Liapunov's CLT,

$$\frac{1}{\sqrt{T(\boldsymbol{\lambda}' \mathbf{V}_o \boldsymbol{\lambda})}} \sum_{t=1}^T z_t \xrightarrow{D} \mathcal{N}(0, 1).$$

Example: Consider $y_t = \alpha y_{t-1} + e_t$. Case 1: $y_t = \alpha_o y_{t-1} + u_t$ with $|\alpha_o| < 1$, where u_t are i.i.d. with mean zero and variance σ_u^2 . Note

$$\text{var}(y_{t-1}u_t) = \mathbb{E}(y_{t-1}^2) \mathbb{E}(u_t^2) = \sigma_u^4 / (1 - \alpha_o^2),$$

and $\text{cov}(y_{t-1}u_t, y_{t-1-j}u_{t-j}) = 0$ for all $j > 0$. A CLT ensures:

$$\frac{\sqrt{1 - \alpha_o^2}}{\sigma_u^2 \sqrt{T}} \sum_{t=1}^T y_{t-1} u_t \xrightarrow{D} \mathcal{N}(0, 1).$$

As $\sum_{t=1}^T y_{t-1}^2 / T$ converges to $\sigma_u^2 / (1 - \alpha_o^2)$, we have

$$\frac{\sqrt{1 - \alpha_o^2}}{\sigma_u^2} \frac{\sigma_u^2}{1 - \alpha_o^2} \sqrt{T}(\hat{\alpha}_T - \alpha_o) = \frac{1}{\sqrt{1 - \alpha_o^2}} \sqrt{T}(\hat{\alpha}_T - \alpha_o) \xrightarrow{D} \mathcal{N}(0, 1),$$

or equivalently, $\sqrt{T}(\hat{\alpha}_T - \alpha_o) \xrightarrow{D} \mathcal{N}(0, 1 - \alpha_o^2)$.

Example (cont'd): When $\{y_t\}$ is a random walk:

$$y_t = y_{t-1} + u_t.$$

We already know $\text{var}(T^{-1/2} \sum_{t=1}^T y_{t-1} u_t)$ diverges with T and hence $\{y_{t-1} u_t\}$ does not obey a CLT. Thus, there is no guarantee that normalized $\hat{\alpha}_T$ is asymptotically normally distributed.

Theorem 6.9

Given $y_t = \mathbf{x}_t' \boldsymbol{\beta} + e_t$, suppose that [B1](i), [B2] and [B3] hold. Then,

$$\hat{\mathbf{D}}_T^{-1/2} \sqrt{T}(\hat{\boldsymbol{\beta}}_T - \boldsymbol{\beta}_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_k),$$

where $\hat{\mathbf{D}}_T = (\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' / T)^{-1} \hat{\mathbf{V}}_T (\sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' / T)^{-1}$, with $\hat{\mathbf{V}}_T \xrightarrow{P} \mathbf{V}_o$.

Remarks:

- 1 Theorem 6.6 may hold for weakly dependent and heterogeneously distributed data, as long as these data obey proper LLN and CLT.
- 2 Normalizing the OLS estimator with an inconsistent estimator of $\mathbf{D}_o^{-1/2}$ destroys asymptotic normality.

Consistent Estimation of Covariance Matrix

- Consistent estimation of \mathbf{D}_o amounts to consistent estimation of \mathbf{V}_o .
- Write $\mathbf{V}_o = \lim_{T \rightarrow \infty} \mathbf{V}_T = \lim_{T \rightarrow \infty} \sum_{j=-T+1}^{T-1} \mathbf{\Gamma}_T(j)$, with

$$\mathbf{\Gamma}_T(j) = \begin{cases} \frac{1}{T} \sum_{t=j+1}^T \mathbb{E}(\mathbf{x}_t \epsilon_t \epsilon_{t-j} \mathbf{x}'_{t-j}), & j = 0, 1, 2, \dots, \\ \frac{1}{T} \sum_{t=-j+1}^T \mathbb{E}(\mathbf{x}_{t+j} \epsilon_{t+j} \epsilon_t \mathbf{x}'_t), & j = -1, -2, \dots \end{cases}$$

- When $\{\mathbf{x}_t \epsilon_t\}$ is weakly stationary, $\mathbb{E}(\mathbf{x}_t \epsilon_t \epsilon_{t-j} \mathbf{x}'_{t-j})$ depends only on the time difference $|j|$ but not on t . Thus,

$$\mathbf{\Gamma}_T(j) = \mathbf{\Gamma}_T(-j) = \mathbb{E}(\mathbf{x}_t \epsilon_t \epsilon_{t-j} \mathbf{x}'_{t-j}), \quad j = 0, 1, 2, \dots,$$

$$\text{and } \mathbf{V}_o = \mathbf{\Gamma}(0) + \lim_{T \rightarrow \infty} 2 \sum_{j=1}^{T-1} \mathbf{\Gamma}(j).$$

Eicker-White Estimator

Case 1: When $\{\mathbf{x}_t\epsilon_t\}$ has no serial correlations,

$$\mathbf{V}_o = \lim_{T \rightarrow \infty} \mathbf{\Gamma}_T(0) = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}(\epsilon_t^2 \mathbf{x}_t \mathbf{x}_t').$$

- A **heteroskedasticity-consistent** estimator of \mathbf{V}_o is

$$\widehat{\mathbf{V}}_T = \frac{1}{T} \sum_{t=1}^T \hat{\epsilon}_t^2 \mathbf{x}_t \mathbf{x}_t',$$

which permits conditional heteroskedasticity of unknown form.

- The **Eicker-White estimator** of \mathbf{D}_o is:

$$\widehat{\mathbf{D}}_T = \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \left(\frac{1}{T} \sum_{t=1}^T \hat{\epsilon}_t^2 \mathbf{x}_t \mathbf{x}_t' \right) \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1}.$$

- The Eicker-White estimator is “robust” when heteroskedasticity is present and of an unknown form.
- If ϵ_t are also **conditionally homoskedastic**: $\mathbb{E}(\epsilon_t^2 \mid \mathcal{Y}^{t-1}, \mathcal{W}^t) = \sigma_o^2$,

$$\mathbf{V}_o = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \mathbb{E}[\mathbb{E}(\epsilon_t^2 \mid \mathcal{Y}^{t-1}, \mathcal{W}^t) \mathbf{x}_t \mathbf{x}_t'] = \sigma_o^2 \mathbf{M}_{xx}.$$

Then, \mathbf{D}_o is $\mathbf{M}_{xx}^{-1} \mathbf{V}_o \mathbf{M}_{xx}^{-1} = \sigma_o^2 \mathbf{M}_{xx}^{-1}$, and it can be consistently estimated by

$$\hat{\mathbf{D}}_T = \hat{\sigma}_T^2 \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1},$$

as in the classical model.

Newey-West Estimator

Case 2: When $\{\mathbf{x}_t \epsilon_t\}$ exhibits serial correlations such that

$$\mathbf{V}_T^\dagger = \sum_{j=-\ell(T)}^{\ell(T)} \mathbf{\Gamma}_T(j) \rightarrow \mathbf{V}_o,$$

where $\ell(T)$ diverges with T , we may try to estimate \mathbf{V}_T^\dagger .

- A difficulty: The sample counterpart $\sum_{j=-\ell(T)}^{\ell(T)} \widehat{\mathbf{\Gamma}}_T(j)$, which is based on the sample counterpart of $\mathbf{\Gamma}_T(j)$, may not be p.s.d.
- A **heteroskedasticity and autocorrelation-consistent** (HAC) estimator that is guaranteed to be p.s.d. has the following form:

$$\widehat{\mathbf{V}}_T^\kappa = \sum_{j=-T+1}^{T-1} \kappa\left(\frac{j}{\ell(T)}\right) \widehat{\mathbf{\Gamma}}_T(j), \quad (1)$$

where κ is a kernel function and $\ell(T)$ is its bandwidth.

- The estimator of \mathbf{D}_o due to Newey and West (1987),

$$\widehat{\mathbf{D}}_T^\kappa = \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \widehat{\mathbf{V}}_T^\kappa \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1},$$

is robust to **both** conditional heteroskedasticity of ϵ_t and serial correlations of $\mathbf{x}_t \epsilon_t$.

- The Eicker-White and Newey-West estimators do not rely on any parametric model of cond. heteroskedasticity and serial correlations.
- κ satisfies: $|\kappa(x)| \leq 1$, $\kappa(0) = 1$, $\kappa(x) = \kappa(-x)$ for all $x \in \mathbb{R}$, $\int |\kappa(x)| dx < \infty$, κ is continuous at 0 and at all but a finite number of other points in \mathbb{R} , and

$$\int_{-\infty}^{\infty} \kappa(x) e^{-ix\omega} dx \geq 0, \quad \forall \omega \in \mathbb{R}.$$

Some Commonly Used Kernel Functions

- 1 Bartlett kernel (Newey and West, 1987): $\kappa(x) = 1 - |x|$ for $|x| \leq 1$, and $\kappa(x) = 0$ otherwise.
- 2 Parzen kernel (Gallant, 1987):

$$\kappa(x) = \begin{cases} 1 - 6x^2 + 6|x|^3, & |x| \leq 1/2, \\ 2(1 - |x|)^3, & 1/2 \leq |x| \leq 1, \\ 0, & \text{otherwise;} \end{cases}$$

- 3 Quadratic spectral kernel (Andrews, 1991):

$$\kappa(x) = \frac{25}{12\pi^2 x^2} \left(\frac{\sin(6\pi x/5)}{6\pi x/5} - \cos(6\pi x/5) \right);$$

- 4 Daniel kernel (Ng and Perron, 1996): $\kappa(x) = \frac{\sin(\pi x)}{\pi x}$.

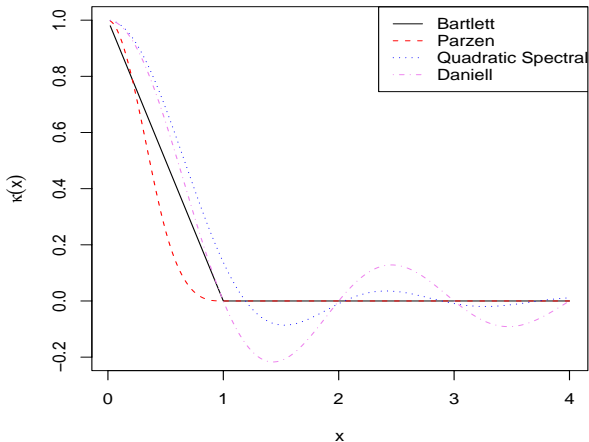


Figure: The Bartlett, Parzen, quadratic spectral and Daniell kernels.

Remarks:

- Bandwidth $\ell(T)$: It can be of order $o(T^{1/2})$, Andrews (1991). (What does this imply?)
- The Bartlett and Parzen kernels have the bounded support $[-1, 1]$, but the quadratic spectral and Daniel kernels have unbounded support.
- Andrews (1991): The **quadratic spectral kernel** is to be preferred in HAC estimation.
 - Rate of convergence: $O(T^{-1/3})$ for the Bartlett kernel, and $O(T^{-2/5})$ for the Parzen and quadratic spectral.
 - The quadratic spectral kernel is more efficient asymptotically than the Parzen kernel, and the Bartlett kernel is the least efficient.
- The optimal choice of $\ell(T)$ is an important issue in practice.

Null hypothesis: $\mathbf{R}\beta_o = \mathbf{r}$

- Want to check if $\mathbf{R}\hat{\beta}_T$ is sufficiently “close” to \mathbf{r} .
- By Theorem 6.6, $(\mathbf{R}\mathbf{D}_o\mathbf{R}')^{-1/2}\sqrt{T}\mathbf{R}(\hat{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_q)$, where $\mathbf{D}_o = \mathbf{M}_{xx}^{-1}\mathbf{V}_o\mathbf{M}_{xx}^{-1}$.
- Given a consistent estimator for \mathbf{D}_o :

$$\hat{\mathbf{D}}_T = \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1} \hat{\mathbf{V}}_T \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \mathbf{x}_t' \right)^{-1},$$

with $\hat{\mathbf{V}}_T$ be a consistent estimator of \mathbf{V}_o , we have

$$(\mathbf{R}\hat{\mathbf{D}}_T\mathbf{R}')^{-1/2}\sqrt{T}\mathbf{R}(\hat{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_q).$$

The **Wald** test statistic is

$$\mathcal{W}_T = T(\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r})'(\mathbf{R}\hat{\mathbf{D}}_T\mathbf{R}')^{-1}(\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r}).$$

Theorem 6.10

Given $y_t = \mathbf{x}_t'\boldsymbol{\beta} + e_t$, suppose that [B1](i), [B2] and [B3] hold. Then under the null, $\mathcal{W}_T \xrightarrow{D} \chi^2(q)$, where q is the number of hypotheses.

- Data are **not** required to be serially uncorrelated, homoskedastic, or normally distributed.
- The limiting χ^2 distribution of the Wald test is only an **approximation** to the exact distribution.

Example: Given the specification $y_t = \mathbf{x}'_{1,t} \mathbf{b}_1 + \mathbf{x}'_{2,t} \mathbf{b}_2 + e_t$, where $\mathbf{x}_{1,t}$ is $(k - s) \times 1$ and $\mathbf{x}_{2,t}$ is $s \times 1$.

- Hypothesis: $\mathbf{R}\boldsymbol{\beta}_o = \mathbf{0}$, where $\mathbf{R} = [\mathbf{0}_{s \times (k-s)} \quad \mathbf{I}_s]$.
- The Wald test statistic is

$$\mathcal{W}_T = T \hat{\boldsymbol{\beta}}_T' \mathbf{R}' (\mathbf{R} \hat{\mathbf{D}}_T \mathbf{R}')^{-1} \mathbf{R} \hat{\boldsymbol{\beta}}_T \xrightarrow{D} \chi^2(s),$$

where $\hat{\mathbf{D}}_T = (\mathbf{X}'\mathbf{X}/T)^{-1} \hat{\mathbf{V}}_T (\mathbf{X}'\mathbf{X}/T)^{-1}$. The exact form of \mathcal{W}_T depends on $\hat{\mathbf{D}}_T$.

- When $\hat{\mathbf{V}}_T = \hat{\sigma}_T^2 (\mathbf{X}'\mathbf{X}/T)$ is consistent for \mathbf{V}_o , $\hat{\mathbf{D}}_T = \hat{\sigma}_T^2 (\mathbf{X}'\mathbf{X}/T)^{-1}$ is consistent for \mathbf{D}_o , and the Wald statistic becomes

$$\mathcal{W}_T = T \hat{\boldsymbol{\beta}}_T' \mathbf{R}' [\mathbf{R} (\mathbf{X}'\mathbf{X}/T)^{-1} \mathbf{R}']^{-1} \mathbf{R} \hat{\boldsymbol{\beta}}_T / \hat{\sigma}_T^2,$$

which is s times the standard F statistic.

Lagrange Multiplier (LM) Test

- Given the constraint $\mathbf{R}\boldsymbol{\beta} = \mathbf{r}$, the Lagrangian is

$$\frac{1}{T}(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})'(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) + (\mathbf{R}\boldsymbol{\beta} - \mathbf{r})'\boldsymbol{\lambda},$$

where $\boldsymbol{\lambda}$ is the $q \times 1$ vector of **Lagrange multipliers**. The solutions are:

$$\ddot{\boldsymbol{\lambda}}_T = 2[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}(\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r}),$$

$$\ddot{\boldsymbol{\beta}}_T = \hat{\boldsymbol{\beta}}_T - (\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}'\ddot{\boldsymbol{\lambda}}_T/2.$$

- The **LM** test checks if $\ddot{\boldsymbol{\lambda}}_T$ (the “shadow price” of the constraint) is sufficiently “close” to zero.

By the asymptotic normality of $\sqrt{T}(\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r})$,

$$\mathbf{\Lambda}_o^{-1/2} \sqrt{T} \ddot{\boldsymbol{\lambda}}_T \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_q),$$

where $\mathbf{\Lambda}_o = 4(\mathbf{R}\mathbf{M}_{xx}^{-1}\mathbf{R}')^{-1}(\mathbf{R}\mathbf{D}_o\mathbf{R}')(\mathbf{R}\mathbf{M}_{xx}^{-1}\mathbf{R}')^{-1}$. Let $\ddot{\mathbf{V}}_T$ be a consistent estimator of \mathbf{V}_o based on the **constrained estimation** result. Then,

$$\begin{aligned} \ddot{\mathbf{\Lambda}}_T &= 4[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\ddot{\mathbf{V}}_T(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}'] \\ &\quad [\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}, \end{aligned}$$

and $\ddot{\mathbf{\Lambda}}_T^{-1/2} \sqrt{T} \ddot{\boldsymbol{\lambda}}_T \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_q)$. The LM statistic is

$$\mathcal{LM}_T = T \ddot{\boldsymbol{\lambda}}_T' \ddot{\mathbf{\Lambda}}_T^{-1} \ddot{\boldsymbol{\lambda}}_T.$$

Theorem 6.12

Given $y_t = \mathbf{x}'_t \boldsymbol{\beta} + e_t$, suppose that [B1](i), [B2] and [B3] hold. Then under the null, $\mathcal{LM}_T \xrightarrow{D} \chi^2(q)$, where q is the number of hypotheses.

Writing $\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r} = \mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{X}'(\mathbf{y} - \mathbf{X}\ddot{\boldsymbol{\beta}}_T)/T = \mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{X}'\ddot{\mathbf{e}}/T$, $\ddot{\boldsymbol{\lambda}}_T = 2[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{X}'\ddot{\mathbf{e}}/T$. The LM test is then

$$\mathcal{LM}_T = T\ddot{\mathbf{e}}'\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\ddot{\mathbf{V}}_T(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\ddot{\mathbf{e}}.$$

That is, the LM test requires **only constrained estimation**.

Note: Under the null, $\mathcal{W}_T - \mathcal{LM}_T \xrightarrow{P} 0$; if \mathbf{V}_0 is known, the Wald and LM tests would be algebraically equivalent. (why?)

Example: Testing whether one would like to add additional s regressors to the specification: $y_t = \mathbf{x}'_{1,t} \mathbf{b}_1 + e_t$.

- The unconstrained specification is

$$y_t = \mathbf{x}'_{1,t} \mathbf{b}_1 + \mathbf{x}'_{2,t} \mathbf{b}_2 + e_t,$$

and the null hypothesis is $\mathbf{R}\beta_o = \mathbf{0}$ with $\mathbf{R} = [\mathbf{0}_{s \times (k-s)} \quad \mathbf{I}_s]$.

- The LM test can be computed as in previous page, using the constrained estimator $\check{\beta}_T = (\check{\mathbf{b}}'_{1,T} \mathbf{0}')'$ with $\check{\mathbf{b}}_{1,T} = (\mathbf{X}'_1 \mathbf{X}_1)^{-1} \mathbf{X}'_1 \mathbf{y}$.
- Letting $\mathbf{X} = [\mathbf{X}_1 \quad \mathbf{X}_2]$ and $\check{\mathbf{e}} = \mathbf{y} - \mathbf{X}_1 \check{\mathbf{b}}_{1,T}$, suppose that $\check{\mathbf{V}}_T = \check{\sigma}_T^2 (\mathbf{X}' \mathbf{X} / T)$ is consistent for \mathbf{V}_o under the null, where $\check{\sigma}_T^2 = \sum_{t=1}^T \check{e}_t^2 / (T - k + s)$. Then, the LM test is

$$\mathcal{LM}_T = T \check{\mathbf{e}}' \mathbf{X} (\mathbf{X}' \mathbf{X})^{-1} \mathbf{R}' [\mathbf{R} (\mathbf{X}' \mathbf{X} / T)^{-1} \mathbf{R}']^{-1} \mathbf{R} (\mathbf{X}' \mathbf{X})^{-1} \mathbf{X}' \check{\mathbf{e}} / \check{\sigma}_T^2.$$

Using the formula for the inverse of a partitioned matrix,

$$\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}' = [\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1)\mathbf{X}_2]^{-1},$$

$$\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}' = [\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1)\mathbf{X}_2]^{-1}\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1).$$

Clearly, $(\mathbf{I} - \mathbf{P}_1)\ddot{\mathbf{e}} = \ddot{\mathbf{e}}$. The LM statistic is thus

$$\begin{aligned}\mathcal{LM}_T &= \ddot{\mathbf{e}}'\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'[\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}']^{-1}\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\ddot{\mathbf{e}}/\ddot{\sigma}_T^2 \\ &= \ddot{\mathbf{e}}'(\mathbf{I} - \mathbf{P}_1)\mathbf{X}_2[\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1)\mathbf{X}_2]^{-1}\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1)\ddot{\mathbf{e}}/\ddot{\sigma}_T^2 \\ &= \ddot{\mathbf{e}}'\mathbf{X}_2[\mathbf{X}'_2(\mathbf{I} - \mathbf{P}_1)\mathbf{X}_2]^{-1}\mathbf{X}'_2\ddot{\mathbf{e}}/\ddot{\sigma}_T^2 \\ &= \ddot{\mathbf{e}}'\mathbf{X}_2\mathbf{R}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{R}'\mathbf{X}'_2\ddot{\mathbf{e}}/\ddot{\sigma}_T^2.\end{aligned}$$

As $\mathbf{X}'_1\ddot{\mathbf{e}} = \mathbf{0}$, we can write

$$\ddot{\mathbf{e}}'\mathbf{X}_2\mathbf{R} = [\mathbf{0}_{1 \times (k-s)} \quad \ddot{\mathbf{e}}'\mathbf{X}_2] = \ddot{\mathbf{e}}'\mathbf{X}.$$

A simple version of the LM test reads

$$\mathcal{LM}_T = \frac{\ddot{\mathbf{e}}'\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\ddot{\mathbf{e}}}{\ddot{\mathbf{e}}'\ddot{\mathbf{e}}/(T-k+s)} = (T-k+s)R^2,$$

where R^2 is the non-centered R^2 of the auxiliary regression of $\ddot{\mathbf{e}}$ on \mathbf{X} .

Note: The LM test may also be computed as TR^2 , if $\hat{\sigma}_T^2 = \ddot{\mathbf{e}}'\ddot{\mathbf{e}}/T$ is an MLE estimator.

Likelihood Ratio (LR) Test

- The OLS estimator $\hat{\beta}_T$ is also the MLE $\tilde{\beta}_T$ that maximizes

$$L_T(\beta, \sigma^2) = -\frac{1}{2} \log(2\pi) - \frac{1}{2} \log(\sigma^2) - \frac{1}{T} \sum_{t=1}^T \frac{(y_t - \mathbf{x}'_t \beta)^2}{2\sigma^2}.$$

With $\hat{e}_t = y_t - \mathbf{x}'_t \tilde{\beta}_T$, the unconstrained MLE of σ^2 is

$$\tilde{\sigma}_T^2 = \frac{1}{T} \sum_{t=1}^T \hat{e}_t^2.$$

- Given $\mathbf{R}\beta = \mathbf{r}$, let $\ddot{\beta}_T$ denote the constrained MLE of β . Then $\ddot{e}_t = y_t - \mathbf{x}'_t \ddot{\beta}_T$, and the constrained MLE of σ^2 is

$$\ddot{\sigma}_T^2 = \frac{1}{T} \sum_{t=1}^T \ddot{e}_t^2.$$

For $H_0 : \mathbf{R}\beta_o = \mathbf{r}$, the LR test compares the constrained and unconstrained L_T :

$$\mathcal{LR}_T = -2T(L_T(\ddot{\beta}_T, \ddot{\sigma}_T^2) - L_T(\tilde{\beta}_T, \tilde{\sigma}_T^2)) = T \log \left(\frac{\ddot{\sigma}_T^2}{\tilde{\sigma}_T^2} \right).$$

The null would be rejected if \mathcal{LR}_T is far from zero.

Theorem 6.15

Given $y_t = \mathbf{x}'_t \beta + e_t$, suppose that [B1](i), [B2] and [B3] hold and that $\tilde{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$ is consistent for \mathbf{V}_o . Then under the null hypothesis,

$$\mathcal{LR}_T \xrightarrow{D} \chi^2(q),$$

where q is the number of hypotheses.

Noting $\ddot{\mathbf{e}} = \mathbf{X}(\tilde{\boldsymbol{\beta}}_T - \ddot{\boldsymbol{\beta}}_T) + \hat{\mathbf{e}}$ and $\mathbf{X}'\hat{\mathbf{e}} = \mathbf{0}$, we have

$$\ddot{\sigma}_T^2 = \tilde{\sigma}_T^2 + (\tilde{\boldsymbol{\beta}}_T - \ddot{\boldsymbol{\beta}}_T)'(\mathbf{X}'\mathbf{X}/T)(\tilde{\boldsymbol{\beta}}_T - \ddot{\boldsymbol{\beta}}_T).$$

We have seen

$$\ddot{\boldsymbol{\beta}}_T - \tilde{\boldsymbol{\beta}}_T = -(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}'[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}(\mathbf{R}\hat{\boldsymbol{\beta}}_T - \mathbf{r}).$$

It follows that

$$\ddot{\sigma}_T^2 = \tilde{\sigma}_T^2 + (\mathbf{R}\tilde{\boldsymbol{\beta}}_T - \mathbf{r})'[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}(\mathbf{R}\tilde{\boldsymbol{\beta}}_T - \mathbf{r}),$$

and that

$$\mathcal{LR}_T = T \log\left(1 + \underbrace{(\mathbf{R}\tilde{\boldsymbol{\beta}}_T - \mathbf{r})'[\mathbf{R}(\mathbf{X}'\mathbf{X}/T)^{-1}\mathbf{R}']^{-1}(\mathbf{R}\tilde{\boldsymbol{\beta}}_T - \mathbf{r})/\tilde{\sigma}_T^2}_{=: a_T}\right).$$

Owing to consistency of $\hat{\beta}_T$, $a_T \rightarrow 0$. The mean value expansion of $\log(1 + a_T)$ about $a_T = 0$ yields

$$\log(1 + a_T) \approx (1 + a_T^\dagger)^{-1} a_T,$$

where a_T^\dagger lies between a_T and 0 and converges to zero. Then,

$$\mathcal{LR}_T = T(1 + a_T^\dagger)^{-1} a_T = Ta_T + o_{\mathbf{P}}(1),$$

where Ta_T is the Wald statistic with $\hat{\mathbf{V}}_T = \tilde{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$. When this $\hat{\mathbf{V}}_T$ is consistent for \mathbf{V}_o , \mathcal{LR}_T has a limiting $\chi^2(q)$ distribution.

Note: The applicability of the LR test here is limited because it can **not** be made robust to conditional heteroskedasticity and serial correlation. (Why?)

Remarks:

- When the Wald test involves $\widehat{\mathbf{V}}_T = \tilde{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$ and the LM test uses $\ddot{\mathbf{V}}_T = \ddot{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$, it can be shown that

$$W_T \geq \mathcal{LR}_T \geq \mathcal{LM}_T.$$

Hence, conflicting inferences in finite samples may arise when the critical values are between two statistics.

- When $\widehat{\mathbf{V}}_T = \tilde{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$ and $\ddot{\mathbf{V}}_T = \ddot{\sigma}_T^2(\mathbf{X}'\mathbf{X}/T)$ are all consistent for \mathbf{V}_o , the Wald, LM, and LR tests are asymptotically equivalent.

Power of Tests

Consider the alternative hypothesis: $\mathbf{R}\beta_o = \mathbf{r} + \delta$, where $\delta \neq \mathbf{0}$.

- Under the alternative,

$$\sqrt{T}(\mathbf{R}\hat{\beta}_T - \mathbf{r}) = \sqrt{T}\mathbf{R}(\hat{\beta}_T - \beta_o) + \sqrt{T}\delta,$$

where the first term on the RHS converges and the second term diverges.

- We have $\mathbb{P}(\mathcal{W}_T > c) \rightarrow 1$ for any critical value c , because

$$\frac{1}{T} \mathcal{W}_T \xrightarrow{\mathbf{P}} \delta'(\mathbf{R}\mathbf{D}_o\mathbf{R}')^{-1}\delta.$$

The Wald test is therefore a **consistent** test.

Example: Analysis of Suicide Rate

Part I: Estimation results based on different covariance matrices

| | const | D_t | u_{t-1} | $u_{t-1}D_t$ | \bar{R}^2 |
|---------------|--------|---------|-----------|--------------|-------------|
| OLS Coeff. | 5.60 | -0.75 | 1.93 | 0.52 | 0.64 |
| OLS s.e. | 2.32* | 3.00 | 1.17 | 1.27 | |
| White s.e. | 2.23* | 2.55 | 0.96* | 1.04 | |
| NW-B s.e. | 2.79* | 3.62 | 1.09 | 1.26 | |
| (t -ratio) | (2.00) | (-0.21) | (1.78) | (0.42) | |
| NW-QS s.e. | 2.94 | 3.98 | 1.13 | 1.32 | |
| (t -ratio) | (1.91) | (-0.19) | (1.72) | (0.40) | |
| FGLS Coeff. | 19.14 | 0.73 | 0.13 | -0.10 | |

NW-B and NW-QS stand for the Newey-West estimates based on the Bartlett and quadratic spectral kernels, respectively, with the truncation lag chosen by the package in R; $D_t = 1$ for $t > T^* = 1994$.

Part II: Estimation results based on different covariance matrices

| | const | D_t | u_{t-1} | t | tD_t | \bar{R}^2 |
|---------------|--------|---------|-----------|----------|--------|-------------|
| OLS Coeff. | 12.36 | -15.26 | 0.38 | -0.50 | 1.19 | 0.91 |
| OLS s.e. | 1.05** | 2.04** | 0.36 | 0.08** | 0.14** | |
| White s.e. | 0.71** | 1.41** | 0.26 | 0.05** | 0.09** | |
| NW-B s.e. | 1.67** | 14.58 | 0.86 | 0.04** | 0.70 | |
| (t -ratio) | (7.41) | (-1.05) | (0.44) | (-14.10) | (1.69) | |
| NW-QS s.e. | 1.94** | 17.35 | 1.01 | 0.04** | 0.84 | |
| (t -ratio) | (6.37) | (-0.88) | (0.38) | (-12.43) | (1.42) | |
| FGLS Coeff. | 14.67 | -18.22 | -0.23 | -0.56 | 1.35 | |

NW-B and NW-QS stand for the Newey-West estimates based on the Bartlett and quadratic spectral kernels, respectively, with the truncation lag chosen by the package in R; $D_t = 1$ for $t > T^* = 1994$.

Instrumental Variable Estimator

- OLS inconsistency:
 - ① A model omits relevant regressors.
 - ② A model includes lagged dependent variables as regressors and serially correlated errors.
 - ③ A model involves regressors that are measured with errors.
 - ④ The dependent variable and regressors are jointly determined at the same time (**simultaneity** problem).
 - ⑤ The dependent variable is determined by some unobservable factors which are correlated with regressors (**selectivity** problem).
- To obtain consistency, let \mathbf{z}_t ($k \times 1$) be variables taken from $(\mathcal{Y}^{t-1}, \mathcal{W}^t)$ such that $\mathbb{E}(\mathbf{z}_t \epsilon_t) = \mathbf{0}$ and \mathbf{z}_t are correlated with \mathbf{x}_t in the sense that $\mathbb{E}(\mathbf{z}_t \mathbf{x}_t')$ is not singular.

- The sample counterpart of $\mathbb{E}(\mathbf{z}_t \epsilon_t) = \mathbb{E}[\mathbf{z}_t(y_t - \mathbf{x}'_t \beta_o)] = \mathbf{0}$ is

$$\frac{1}{T} \sum_{t=1}^T [\mathbf{z}_t(y_t - \mathbf{x}'_t \beta)] = \mathbf{0},$$

which is a system of k equations with k unknowns.

- The solution is the **instrumental variable** (IV) estimator:

$$\check{\beta}_T = \left(\sum_{t=1}^T \mathbf{z}_t \mathbf{x}'_t \right)^{-1} \left(\sum_{t=1}^T \mathbf{z}_t y_t \right) \xrightarrow{\mathbf{P}} \mathbf{M}_{\mathbf{z}\mathbf{x}}^{-1} \mathbf{m}_{\mathbf{z}y} = \beta_o,$$

under suitable LLN.

- This is also a **method of moment** estimator, because it solves the sample counterpart of the moment conditions: $\mathbb{E}[\mathbf{z}_t(y_t - \mathbf{x}'_t \beta_o)] = \mathbf{0}$.
- This method breaks down when more than k instruments are available.

- Assume CLT: $T^{-1/2} \sum_{t=1}^T \mathbf{z}_t \epsilon_t \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{V}_o)$ with

$$\mathbf{V}_o = \lim_{T \rightarrow \infty} \text{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{z}_t \epsilon_t \right).$$

- The normalized IV estimator has asymptotic normality:

$$\sqrt{T}(\check{\beta}_T - \beta_o) = \left(\frac{1}{T} \sum_{t=1}^T \mathbf{z}_t \mathbf{x}'_t \right)^{-1} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \mathbf{z}_t \epsilon_t \right) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{D}_o),$$

where $\mathbf{D}_o = \mathbf{M}_{\mathbf{zx}}^{-1} \mathbf{V}_o \mathbf{M}_{\mathbf{zx}}^{-1}$.

- Then, $\hat{\mathbf{D}}_T^{-1/2} \sqrt{T}(\check{\beta}_T - \beta_o) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \mathbf{I}_k)$, where $\hat{\mathbf{D}}_T$ is a consistent estimator for \mathbf{D}_o .

I(1) Variables

$\{y_t\}$ is said to be an **I(1)** (**integrated of order 1**) process if $y_t = y_{t-1} + \epsilon_t$, with ϵ_t satisfying:

[C1] $\{\epsilon_t\}$ is a weakly stationary process with mean zero and variance σ_ϵ^2 and obeys an FCLT:

$$\frac{1}{\sigma_* \sqrt{T}} \sum_{t=1}^{[Tr]} \epsilon_t = \frac{1}{\sigma_* \sqrt{T}} y_{[Tr]} \Rightarrow w(r), \quad 0 \leq r \leq 1,$$

where w is standard Wiener process, and σ_*^2 is the **long-run variance** of ϵ_t :

$$\sigma_*^2 = \lim_{T \rightarrow \infty} \text{var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T \epsilon_t \right).$$

- Partial sums of an $I(0)$ series (e.g., $\sum_{i=1}^t \epsilon_i$) form an $I(1)$ series, while taking first difference of an $I(1)$ series (e.g., $y_t - y_{t-1}$) yields an $I(0)$ series.
 - A random walk is $I(1)$ with i.i.d. ϵ_t and $\sigma_*^2 = \sigma_\epsilon^2$.
 - When $\epsilon_t = y_t - y_{t-1}$ is a stationary ARMA(p, q) process, y is an $I(1)$ process and known as an ARIMA($p, 1, q$) process.
- An $I(1)$ series y_t has mean zero and variance increasing **linearly** with t , and its autocovariances $\text{cov}(y_t, y_s)$ do **not** decrease when $|t - s|$ increases.
- Many macroeconomic and financial time series are (or behave like) $I(1)$ processes.

ARIMA vs. ARMA Processes

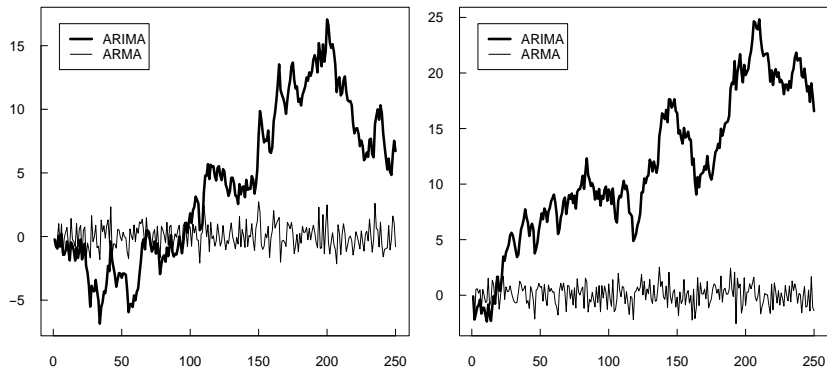


Figure: Sample paths of ARIMA and ARMA series.

$I(1)$ vs. Trend Stationarity

Trend stationary series: $y_t = a_0 + b_0 t + \epsilon_t$, where ϵ_t are $I(0)$.

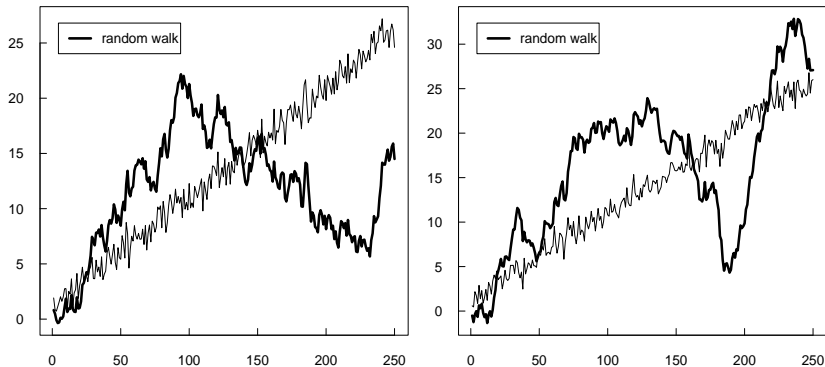


Figure: Sample paths of random walk and trend stationary series.

Autoregression of an $I(1)$ Variable

Suppose $\{y_t\}$ is a random walk such that $y_t = \alpha_0 y_{t-1} + \epsilon_t$ with $\alpha_0 = 1$ and ϵ_t i.i.d. random variables with mean zero and variance σ_ϵ^2 .

- $\{y_t\}$ does not obey a LLN, and $\sum_{t=2}^T y_{t-1} \epsilon_t = O_{\mathbf{P}}(T)$ and $\sum_{t=2}^T y_{t-1}^2 = O_{\mathbf{P}}(T^2)$.
- Given the specification: $y_t = \alpha y_{t-1} + e_t$, the OLS estimator of α is:

$$\hat{\alpha}_T = \frac{\sum_{t=2}^T y_{t-1} y_t}{\sum_{t=2}^T y_{t-1}^2} = 1 + \frac{\sum_{t=2}^T y_{t-1} \epsilon_t}{\sum_{t=2}^T y_{t-1}^2} = 1 + O_{\mathbf{P}}(T^{-1}),$$

which is **T -consistent**. This is also known as a **super consistent** estimator.

Asymptotic Properties of the OLS Estimator

Lemma 7.1

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Then,

- (i) $T^{-3/2} \sum_{t=1}^T y_{t-1} \Rightarrow \sigma_* \int_0^1 w(r) dr;$
- (ii) $T^{-2} \sum_{t=1}^T y_{t-1}^2 \Rightarrow \sigma_*^2 \int_0^1 w(r)^2 dr;$
- (iii) $T^{-1} \sum_{t=1}^T y_{t-1} \epsilon_t \Rightarrow$
 $\frac{1}{2} [\sigma_*^2 w(1)^2 - \sigma_\epsilon^2] = \sigma_*^2 \int_0^1 w(r) dw(r) + \frac{1}{2} (\sigma_*^2 - \sigma_\epsilon^2),$

where w is the standard Wiener process.

Note: When y_t is a random walk, $\sigma_*^2 = \sigma_\epsilon^2$.

Theorem 7.2

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Given the specification $y_t = \alpha y_{t-1} + e_t$, the normalized OLS estimator of α is:

$$T(\hat{\alpha}_T - 1) = \frac{\sum_{t=2}^T y_{t-1} \epsilon_t / T}{\sum_{t=2}^T y_{t-1}^2 / T^2} \Rightarrow \frac{\frac{1}{2} [w(1)^2 - \sigma_\epsilon^2 / \sigma_*^2]}{\int_0^1 w(r)^2 dr}.$$

where w is the standard Wiener process. When y_t is a random walk,

$$T(\hat{\alpha}_T - 1) \Rightarrow \frac{\frac{1}{2} [w(1)^2 - 1]}{\int_0^1 w(r)^2 dr},$$

which does not depend on σ_ϵ^2 and σ_*^2 and is **asymptotically pivotal**.

Lemma 7.3

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Then,

$$(i) \quad T^{-2} \sum_{t=1}^T (y_{t-1} - \bar{y}_{-1})^2 \Rightarrow \sigma_*^2 \int_0^1 w^*(r)^2 dr;$$

$$(ii) \quad T^{-1} \sum_{t=1}^T (y_{t-1} - \bar{y}_{-1}) \epsilon_t \Rightarrow \sigma_*^2 \int_0^1 w^*(r) dw(r) + \frac{1}{2}(\sigma_*^2 - \sigma_\epsilon^2),$$

where w is the standard Wiener process and $w^*(t) = w(t) - \int_0^1 w(r) dr$.

Theorem 7.4

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Given the specification $y_t = c + \alpha y_{t-1} + e_t$, the normalized OLS estimators of α and c are:

$$T(\hat{\alpha}_T - 1) \Rightarrow \frac{\int_0^1 w^*(r) dw(r) + \frac{1}{2}(1 - \sigma_\epsilon^2/\sigma_*^2)}{\int_0^1 w^*(r)^2 dr} =: A,$$

$$\sqrt{T}\hat{c}_T \Rightarrow A \left(\sigma_* \int_0^1 w(r) dr \right) + \sigma_* w(1).$$

In particular, when y_t is a random walk,

$$T(\hat{\alpha}_T - 1) \Rightarrow \frac{\int_0^1 w^*(r) dw(r)}{\int_0^1 w^*(r)^2 dr}.$$

- The limiting results for autoregressions with an $I(1)$ variable are **not** invariant to model specification.
- All the results here are based on the data with DGP: $y_t = y_{t-1} + \epsilon_t$.
intercept. These results would break down if the DGP is $y_t = c_o + y_{t-1} + \epsilon_t$ with a non-zero c_o ; such series are said to be $I(1)$ with **drift**.
- $I(1)$ process with a **drift**:

$$y_t = c_o + y_{t-1} + \epsilon_t = c_o t + \sum_{i=1}^t \epsilon_i,$$

which contains a deterministic trend and an $I(1)$ series without drift.

Tests of Unit Root

- ① Given the specification $y_t = \alpha y_{t-1} + e_t$, the **unit root hypothesis** is $\alpha_0 = 1$, and a leading unit-root test is the t test:

$$\tau_0 = \frac{(\sum_{t=2}^T y_{t-1}^2)^{1/2} (\hat{\alpha}_T - 1)}{\hat{\sigma}_{T,1}},$$

where $\hat{\sigma}_{T,1}^2 = \sum_{t=2}^T (y_t - \hat{\alpha}_T y_{t-1})^2 / (T - 2)$.

- ② Given the specification $y_t = c + \alpha y_{t-1} + e_t$, a unit-root test is

$$\tau_c = \frac{[\sum_{t=2}^T (y_{t-1} - \bar{y}_{-1})^2]^{1/2} (\hat{\alpha}_T - 1)}{\hat{\sigma}_{T,2}},$$

where $\hat{\sigma}_{T,2}^2 = \sum_{t=2}^T (y_t - \hat{c}_T - \hat{\alpha}_T y_{t-1})^2 / (T - 3)$.

Theorem 7.5

Let y_t be generated as a **random walk**. Then,

$$\tau_0 \Rightarrow \frac{\frac{1}{2}[w(1)^2 - 1]}{[\int_0^1 w(r)^2 dr]^{1/2}},$$
$$\tau_c \Rightarrow \frac{\int_0^1 w^*(r) dw(r)}{[\int_0^1 w^*(r)^2 dr]^{1/2}}.$$

- For the specification with a time trend variable:

$$y_t = c + \alpha y_{t-1} + \beta \left(t - \frac{T}{2} \right) + e_t,$$

the t -statistic of $\alpha_0 = 1$ is denoted as τ_t .

Dickey-Fuller distributions

Table: Some percentiles of the Dickey-Fuller distributions.

| Test | 1% | 2.5% | 5% | 10% | 50% | 90% | 95% | 97.5% | 99% |
|----------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| τ_0 | -2.58 | -2.23 | -1.95 | -1.62 | -0.51 | 0.89 | 1.28 | 1.62 | 2.01 |
| τ_c | -3.42 | -3.12 | -2.86 | -2.57 | -1.57 | -0.44 | -0.08 | 0.23 | 0.60 |
| τ_t | -3.96 | -3.67 | -3.41 | -3.13 | -2.18 | -1.25 | -0.94 | -0.66 | -0.32 |

- These distributions are **not** symmetric about zero and assume **more negative** values.
- τ_c assumes negatives values about 95% of times, and τ_t is virtually a non-positive random variable.

The Dickey-Fuller Distributions

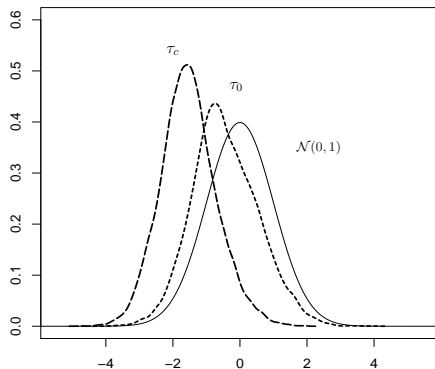


Figure: The distributions of the Dickey-Fuller τ_0 and τ_c tests vs. $\mathcal{N}(0,1)$.

Implementation

In practice, we estimate one of the following specifications:

- ① $\Delta y_t = \theta y_{t-1} + e_t.$
- ② $\Delta y_t = c + \theta y_{t-1} + e_t.$
- ③ $\Delta y_t = c + \theta y_{t-1} + \beta(t - \frac{T}{2}) + e_t.$

The unit-root hypothesis $\alpha_o = 1$ is now equivalent to $\theta_o = 0$.

- The weak limits of the normalized estimators $T\hat{\theta}_T$ are the same as the respective limits of $T(\hat{\alpha}_T - 1)$ under the null hypothesis.
- The unit-root tests are now computed as the **t-ratios** of these specifications.

Phillips-Perron Tests

Note: The Dickey-Fuller tests check only the random walk hypothesis and are **invalid for testing general $I(1)$ processes.**

Theorem 7.6

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Then,

$$\tau_0 \Rightarrow \frac{\sigma_*}{\sigma_\epsilon} \left(\frac{\frac{1}{2}[w(1)^2 - \sigma_\epsilon^2/\sigma_*^2]}{[\int_0^1 w(r)^2 dr]^{1/2}} \right),$$

$$\tau_c \Rightarrow \frac{\sigma_*}{\sigma_\epsilon} \left(\frac{\int_0^1 w^*(r) dw(r) + \frac{1}{2}(1 - \sigma_\epsilon^2/\sigma_*^2)}{[\int_0^1 w^*(r)^2 dr]^{1/2}} \right),$$

- Let $\hat{\varepsilon}_t$ denote the OLS residuals and s_{Tn}^2 a Newey-West type estimator of σ_*^2 based on $\hat{\varepsilon}_t$:

$$s_{Tn}^2 = \frac{1}{T-1} \sum_{t=2}^T \hat{\varepsilon}_t^2 + \frac{2}{T-1} \sum_{s=1}^{T-2} \kappa\left(\frac{s}{n}\right) \sum_{t=s+2}^T \hat{\varepsilon}_t \hat{\varepsilon}_{t-s},$$

with κ a kernel function and $n = n(T)$ its bandwidth.

- Phillips (1987) proposed the following modified τ_0 and τ_c statistics:

$$Z(\tau_0) = \frac{\hat{\sigma}_T}{s_{Tn}} \tau_0 - \frac{\frac{1}{2}(s_{Tn}^2 - \hat{\sigma}_T^2)}{s_{Tn}(\sum_{t=2}^T y_{t-1}^2 / T^2)^{1/2}},$$

$$Z(\tau_c) = \frac{\hat{\sigma}_T}{s_{Tn}} \tau_c - \frac{\frac{1}{2}(s_T^2 - \hat{\sigma}_T^2)}{s_{Tn}[\sum_{t=2}^T (y_{t-1} - \bar{y}_{-1})^2]^{1/2}};$$

see also Phillips and Perron (1988).

The Phillips-Perron tests eliminate the nuisance parameters by suitable transformations of τ_0 and τ_c and have the **same** limits as those of the Dickey-Fuller tests.

Corollary 7.7.

Let $y_t = y_{t-1} + \epsilon_t$ be an $I(1)$ series with ϵ_t satisfying [C1]. Then,

$$Z(\tau_0) \Rightarrow \frac{\frac{1}{2}[w(1)^2 - 1]}{[\int_0^1 w(r)^2 dr]^{1/2}},$$
$$Z(\tau_c) \Rightarrow \frac{\int_0^1 w^*(r) dw(r)}{[\int_0^1 w^*(r)^2 dr]^{1/2}}.$$

Augmented Dickey-Fuller (ADF) Tests

Said and Dickey (1984) suggest “filtering out” the correlations in a weakly stationary process by a linear AR model with a proper order. The “augmented” specifications are:

- 1 $\Delta y_t = \theta y_{t-1} + \sum_{j=1}^k \gamma_j \Delta y_{t-j} + e_t.$
- 2 $\Delta y_t = c + \theta y_{t-1} + \sum_{j=1}^k \gamma_j \Delta y_{t-j} + e_t.$
- 3 $\Delta y_t = c + \theta y_{t-1} + \beta \left(t - \frac{T}{2} \right) + \sum_{j=1}^k \gamma_j \Delta y_{t-j} + e_t.$

Note: This approach avoids non-parametric kernel estimation of σ_*^2 but requires choosing a proper lag order k for the augmented specifications (say, by a model selection criteria, such as AIC or SIC).

$\{y_t\}$ is **trend stationary** if it fluctuates around a deterministic trend:

$$y_t = a_0 + b_0 t + \epsilon_t,$$

where ϵ_t satisfy [C1]. When $b_0 = 0$, it is **level stationary**. Kwiatkowski, Phillips, Schmidt, and Shin (1992) proposed testing stationarity by

$$\eta_T = \frac{1}{T^2 s_{Tn}^2} \sum_{t=1}^T \left(\sum_{i=1}^t \hat{\epsilon}_i \right)^2,$$

where s_{Tn}^2 is a Newey-West estimator of σ_*^2 based on $\hat{\epsilon}_t$.

- To test the null of trend stationarity, $\hat{\epsilon}_t = y_t - \hat{a}_T - \hat{b}_T t$.
- To test the null of level stationarity, $\hat{\epsilon}_t = y_t - \bar{y}$.

The partial sums of $\hat{\epsilon}_t = y_t - \bar{y}$ are such that

$$\sum_{t=1}^{[Tr]} \hat{\epsilon}_t = \sum_{t=1}^{[Tr]} (\epsilon_t - \bar{\epsilon}) = \sum_{t=1}^{[Tr]} \epsilon_t - \frac{[Tr]}{T} \sum_{t=1}^T \epsilon_t, \quad r \in (0, 1].$$

Then by a suitable FCLT,

$$\frac{1}{\sigma_* \sqrt{T}} \sum_{t=1}^{[Tr]} \hat{\epsilon}_t \Rightarrow w(r) - rw(1) = w^0(r).$$

Similarly, given $\hat{\epsilon}_t = y_t - \hat{a}_T - \hat{b}_T t$,

$$\frac{1}{\sigma_* \sqrt{T}} \sum_{t=1}^{[Tr]} \hat{\epsilon}_t \Rightarrow w(r) + (2r - 3r^2)w(1) - (6r - 6r^2) \int_0^1 w(s) ds,$$

which is a “tide-down” process (it is zero at $r = 1$ with prob. one).

Theorem 7.8

Let $y_t = a_o + b_o t + \epsilon_t$ with ϵ_t satisfying [C1]. Then, η_T computed from $\hat{\epsilon}_t = y_t - \hat{a}_T - \hat{b}_T t$ is:

$$\eta_T \Rightarrow \int_0^1 f(r)^2 dr,$$

where $f(r) = w(r) + (2r - 3r^2)w(1) - (6r - 6r^2) \int_0^1 w(s) ds$.

Let $y_t = a_o + \epsilon_t$ with ϵ_t satisfying [C1]. Then, η_T computed from $\hat{\epsilon}_t = y_t - \bar{y}$ is:

$$\eta_T \Rightarrow \int_0^1 w^0(r)^2 dr,$$

where w^0 is the Brownian bridge.

Table: Some percentiles of the distributions of the KPSS test.

| Test | 1% | 2.5% | 5% | 10% |
|--------------------|-------|-------|-------|-------|
| level stationarity | 0.739 | 0.574 | 0.463 | 0.347 |
| trend stationarity | 0.216 | 0.176 | 0.146 | 0.119 |

- These tests have power against $I(1)$ series because η_T would diverge under $I(1)$ alternatives.
- KPSS tests also have power against other alternatives, such as stationarity with mean changes and trend stationarity with trend breaks. Thus, rejecting the null of stationarity does **not** imply that the series must be $I(1)$.

The KPSS Distributions

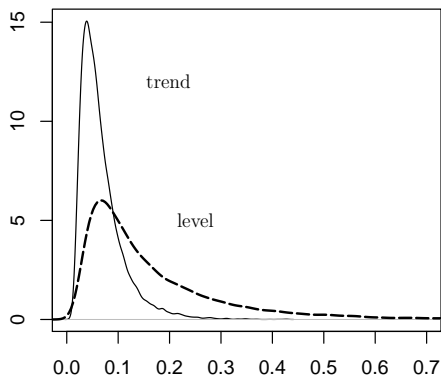


Figure: The distributions of the KPSS tests.

Spurious Regressions

- Granger and Newbold (1974): Regressing one random walk on the other typically yields a significant t -ratio. They refer to this result as **spurious regression**.
- Given the specification $y_t = \alpha + \beta x_t + e_t$, let $\hat{\alpha}_T$ and $\hat{\beta}_T$ denote the OLS estimators for α and β , respectively, and the corresponding t -ratios: $t_\alpha = \hat{\alpha}_T/s_\alpha$ and $t_\beta = \hat{\beta}_T/s_\beta$, where s_α and s_β are the OLS standard errors for $\hat{\alpha}_T$ and $\hat{\beta}_T$.
- $y_t = y_{t-1} + u_t$ and $x_t = x_{t-1} + v_t$, where $\{u_t\}$ and $\{v_t\}$ are mutually independent processes satisfying the following condition.

[C2] $\{u_t\}$ and $\{v_t\}$ are two weakly stationary processes with mean zero and respective variances σ_u^2 and σ_v^2 and obey an FCLT with:

$$\sigma_y^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \mathbb{E} \left(\sum_{t=1}^T u_t \right)^2, \quad \sigma_x^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \mathbb{E} \left(\sum_{t=1}^T v_t \right)^2.$$

We have the following results:

$$\frac{1}{T^{3/2}} \sum_{t=1}^T y_t \Rightarrow \sigma_y \int_0^1 w_y(r) dr, \quad \frac{1}{T^2} \sum_{t=1}^T y_t^2 \Rightarrow \sigma_y^2 \int_0^1 w_y(r)^2 dr,$$

where w_y is a standard Wiener processes. Similarly,

$$\frac{1}{T^{3/2}} \sum_{t=1}^T x_t \Rightarrow \sigma_x \int_0^1 w_x(r) dr, \quad \frac{1}{T^2} \sum_{t=1}^T x_t^2 \Rightarrow \sigma_x^2 \int_0^1 w_x(r)^2 dr.$$

We also have

$$\frac{1}{T^2} \sum_{t=1}^T (y_t - \bar{y})^2 \Rightarrow \sigma_y^2 \int_0^1 w_y(r)^2 dr - \sigma_y^2 \left(\int_0^1 w_y(r) dr \right)^2 =: \sigma_y^2 m_y,$$

$$\frac{1}{T^2} \sum_{t=1}^T (x_t - \bar{x})^2 \Rightarrow \sigma_x^2 \int_0^1 w_x(r)^2 dr - \sigma_x^2 \left(\int_0^1 w_x(r) dr \right)^2 =: \sigma_x^2 m_x,$$

where $w_y^*(t) = w_y(t) - \int_0^1 w_y(r) dr$ and $w_x^*(t) = w_x(t) - \int_0^1 w_x(r) dr$ are two mutually independent, “de-meanned” Wiener processes. Also,

$$\begin{aligned} & \frac{1}{T^2} \sum_{t=1}^T (y_t - \bar{y})(x_t - \bar{x}_t) \\ & \Rightarrow \sigma_y \sigma_x \left(\int_0^1 w_y(r) w_x(r) dr - \int_0^1 w_y(r) dr \int_0^1 w_x(r) dr \right) \\ & =: \sigma_y \sigma_x m_{yx}. \end{aligned}$$

Theorem 7.9

Let $y_t = y_{t-1} + u_t$ and $x_t = x_{t-1} + v_t$, where $\{u_t\}$ and $\{v_t\}$ are mutually independent and satisfy [C2]. Given the specification $y_t = \alpha + \beta x_t + e_t$,

$$(i) \hat{\beta}_T \Rightarrow \frac{\sigma_y m_{yx}}{\sigma_x m_x},$$

$$(ii) T^{-1/2} \hat{\alpha}_T \Rightarrow \sigma_y \left(\int_0^1 w_y(r) dr - \frac{m_{yx}}{m_x} \int_0^1 w_x(r) dr \right),$$

$$(iii) T^{-1/2} t_\beta \Rightarrow \frac{m_{yx}}{(m_y m_x - m_{yx}^2)^{1/2}},$$

$$(iv) T^{-1/2} t_\alpha \Rightarrow \frac{m_x \int_0^1 w_y(r) dr - m_{yx} \int_0^1 w_x(r) dr}{[(m_y m_x - m_{yx}^2) \int_0^1 w_x(r)^2 dr]^{1/2}},$$

w_x and w_y are two mutually independent, standard Wiener processes.

- While the true parameters should be $\alpha_o = \beta_o = 0$, $\hat{\beta}_T$ has a limiting distribution, and $\hat{\alpha}_T$ diverges at the rate $T^{1/2}$.
- Theorem 7.9 (iii) and (iv) indicate that t_α and t_β both diverge at the rate $T^{1/2}$ and are likely to reject the null of $\alpha_o = \beta_o = 0$ using the critical values from the standard normal distribution.
- **Spurious trend:** Nelson and Kang (1984) showed that, when $\{y_t\}$ is in fact a random walk, one may easily find significant time trend specification: $y_t = a + b t + e_t$.
- Phillips and Durlauf (1986) demonstrate that the F test (and hence the t -ratio) of $b_o = 0$ in the time trend specification above diverges at the rate T , which explains why an incorrect inference would result.

Cointegration

- Consider an equilibrium relation between y and x : $ay - bx = 0$. With real data (y_t, x_t) , $z_t := ay_t - bx_t$ are equilibrium errors because they need not be zero all the time.
- y_t and x_t are both $I(1)$:
 - A linear combination of them, z_t , is, in general, an $I(1)$ series. Then, $\{z_t\}$ rarely crosses zero, and the equilibrium condition entails little empirical restriction on z_t .
 - When y_t and x_t involve the same random walk q_t such that $y_t = q_t + u_t$ and $x_t = cq_t + v_t$, where $\{u_t\}$ and $\{v_t\}$ are $I(0)$. Then,

$$z_t := cy_t - x_t = cu_t - v_t,$$

which is a linear combination of $I(0)$ series and hence is also $I(0)$.

- Granger (1981), Granger and Weiss (1983), and Engle and Granger (1987): Let \mathbf{y}_t be a d -dimensional vector $I(1)$ series. The elements of \mathbf{y}_t are **cointegrated** if there exists a $d \times 1$ vector, $\boldsymbol{\alpha}$, such that $z_t = \boldsymbol{\alpha}'\mathbf{y}_t$ is $I(0)$. We say the elements of \mathbf{y}_t are $CI(1,1)$.
- The vector $\boldsymbol{\alpha}$ is a **cointegrating vector**. The space spanned by linearly independent cointegrating vectors is the **cointegrating space**; the number of linearly independent cointegrating vectors is the **cointegrating rank** which is the dimension of the cointegrating space.
- If the cointegrating rank is r , we can put r linearly independent cointegrating vectors together and form the $d \times r$ matrix \mathbf{A} such that $\mathbf{z}_t = \mathbf{A}'\mathbf{y}_t$ is a vector $I(0)$ series.
- The cointegrating rank is at most $d - 1$. (Why?)

Cointegrating Regression

- **Cointegrating regression:** $y_{1,t} = \alpha' \mathbf{y}_{2,t} + z_t$. Then, $(1 \ \alpha)'$ is the cointegrating vector and z_t are the regression (equilibrium) errors.
- When the elements of \mathbf{y}_t are cointegrated, z_t is correlated with $\mathbf{y}_{2,t}$. Consistency of the OLS estimators do not matter asymptotically, but correlation would result in finite-sample bias and efficiency loss.
- **Efficiency:** Saikkonen (1991) proposed a modified co-integrating regression:

$$y_{1,t} = \alpha' \mathbf{y}_{2,t} + \sum_{j=-k}^k \Delta \mathbf{y}'_{2,t-j} \mathbf{b}_j + e_t,$$

so that the OLS estimator of α is asymptotically efficient.

Tests of Cointegration

- One can verify a cointegration relation by applying unit-root tests, such as the augmented Dickey-Fuller test and the Phillips-Perron test, to \hat{z}_t . The null hypothesis that a unit root is present is equivalent to the hypothesis of **no cointegration**.
- To implement a unit-root test on cointegration residuals \hat{z}_T , a difficulty is that \hat{z}_T is not a raw series but a result of OLS fitting. Thus, even when z_t may be $I(1)$, the residuals \hat{z}_t may not have much variation and hence behave like a stationary series.
- Engle and Granger (1987), Engle and Yoo (1987), and Davidson and MacKinnon (1993) simulated proper critical values for the unit-root tests on cointegrating residuals. Similar to the unit-root tests discussed earlier, these critical values are all “model dependent.”

Table: Some percentiles of the distributions of the cointegration τ_c test.

| d | 1% | 2.5% | 5% | 10% |
|-----|-------|-------|-------|-------|
| 2 | -3.90 | -3.59 | -3.34 | -3.04 |
| 3 | -4.29 | -4.00 | -3.74 | -3.45 |
| 4 | -4.64 | -4.35 | -4.10 | -3.81 |

- Drawbacks of cointegrating regressions:
 - 1 The choice of the dependent variable is somewhat arbitrary.
 - 2 This approach is more suitable for finding only one cointegrating relationship. One may estimate multiple cointegration relations by a vector regression.
- It is now typical to adopt the maximum likelihood approach of Johansen (1988) to estimate the cointegrating space directly.

Error Correction Model (ECM)

- When the elements of \mathbf{y}_t are cointegrated with $\mathbf{A}'\mathbf{y}_t = \mathbf{z}_t$, then there exists an error correction model (ECM):

$$\Delta\mathbf{y}_t = \mathbf{B}\mathbf{z}_{t-1} + \mathbf{C}_1\Delta\mathbf{y}_{t-1} + \cdots + \mathbf{C}_k\Delta\mathbf{y}_{t-k} + \nu_t.$$

- Cointegration characterizes the long-run equilibrium relations because it deals with the **levels** of $I(1)$ variables, and the ECM deals with the **differences** of variables and describes short-run dynamics.
- When cointegration exists, a vector AR model of $\Delta\mathbf{y}_t$ is misspecified because it omits \mathbf{z}_{t-1} , and the parameter estimates are inconsistent.
- We regress $\Delta\mathbf{y}_t$ on $\hat{\mathbf{z}}_{t-1}$ and lagged $\Delta\mathbf{y}_t$. Here, standard asymptotic theory applies because ECM involves only stationary variables when cointegration exists.